Photogrammetry: DTM Extraction & Editing







How can one determine the x, y, and z of a location? Approaches to DTM Extraction

- Ground surveying
- Digitized topographic maps
- Photogrammetry
 - –Hardcopy vs. softcopy approach
 - -Structure from Motion (SfM/PhoDAR)
- Radar (e.g., <u>SRTM 2003</u> and <u>eSRTM 2014</u>)
- LIDAR



Photogrammetry

- The science of making reliable measurements by the use of photographs and especially aerial photographs.
- Challenges and solutions:
 - Geometric distortions (transformation)
 - Relief displacement (ortho-rectification)
 - Obscured targets (true-orthorectification)



Distortion

- Distortion: shift in the position of an image on a photograph that alters the perspective characteristics of the image.
- Displacement: shift in the position of an image on a photograph that does not alter the perspective characteristics of the photo



Types of Distortion

- Film and print Shrinkage
- Atmospheric Reaction of light rays (refraction)
- Image motion
- Lens Distortion

The effects of film shrinkage, atmospheric refraction are usually negligible in most cases.



Geometric Distortions

Systematic errors

- External errors
 - -Altitude changes
 - -Attitude changes (roll, pitch, and yaw)
- Internal errors

-e.g., lens distortion, earth rotation





Methods of Correcting Geometric Distortion

- Affine Transformation (aka linear or first-order transformation)
- Higher order polynomial transformation





Orthophoto & Ortho-rectification

Orthophotos - orthographic photographs

• Photographs that do not have distortions nor displacements.

True orthophotos:

http://www.sharpgis.net/page/True-Orthophoto-Generation.aspx









Basic Aerial Photography Geometry

- Fiducial marks
- Principal point
- •9" x 9" (or 228.6mm x 228.6mm)





Geometric Components of Relief Displacement



1/S: photo scalef: focal length of cameraH: flying height

d = relief displacement
h = object height
r = radial distance between location and PP on photo
H = flying height

Calculating Relief Displacement

- d = relief displacement
- h = object height
- r = radial distance between location and PP on photo
- H = flying height



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Relief Displacement





RD changes the measured distances and angles on photos.



Correcting for Relief Displacement: Orthorectification



- d = relief displacement
- h = object height
- r = radial distance between location and PP on photo
- H = flying height

Exercise

- Given a photo with known flight height (e.g., 1220 m)
- Demonstrate the steps to measure the height of a building on the photo.





- r = radial distance between location and PP on photo
- H = flying height

Image Parallax

 the apparent displacement or the difference in apparent direction of an object as seen from two different points not on a straight line with the object.

$$p_a = x_a - x'_a$$

 p_a = parallax of point A x_a = x coor of a on left photo x'_a = x coor of a' on right photo



Figure 3.15 Parallax displacements on overlapping vertical photographs.



Figure 189: Exposure Stations Along a Flight Path



Figure 190: A Regular Rectangular Block of Aerial Photos





$$p_a = x_a - x'_a$$

Image Parallax



$$p_a = d_a + d'_a$$

T Ground Target

Perspective center 1





H = flying height

Calculating Object Height & Location from Parallax



a stereopair; (b) superimposition of right photograph onto left.

Values of X_a, Y_a, and h?



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Measuring Parallax

Based on a stereopair of photos

- Floating half marks
- Parallax wedge





Digital Photogrammetry: Softcopy Photogrammetric Systems

- Scanned stereopair photos
- Interior and exterior orientations
 - Camera & photo parameters
 - Flight parameters
 - -GCPs
- Image matching
 - -Tie points
 - Algorithms
- Generate DEM and orthophotos



Collinearity Condition & Equations

- Alignment of exposure station (O), object location on the photo (p), and object location on the ground (P).
- If collinearity condition is achieved on both photos in a stereopair then the ground X, Y,² Z can be computed from x and y within the image coordinate system on both photos.
- Six exterior orientation parameters
- Collinearity equations can be derived using GCPs.
- Inertial Measurement Unit (IMU)





Photogrammetry / Structure From Motion Software

- VisualSFM (open source) (web)
- Agisoft PhotoScan (web)
 - Standard educational edition \$59
 - Professional educational edition \$549
- PhotoModeler (<u>web</u>)
 - PhotoModeler \$1145
 - PhotoModeler Scanner \$2495
 - PhotoModeler Motion \$3495

http://www.youtube.com/watch?v=i7ierVkXYa8