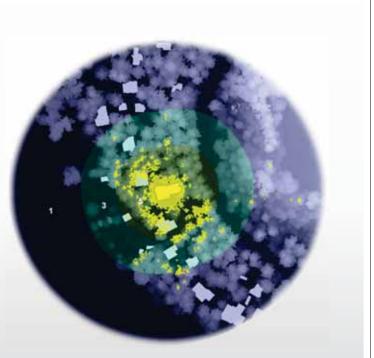
# Viewshed Analysis to Rank Home Privacy

Jen Memhard and Emily Rush

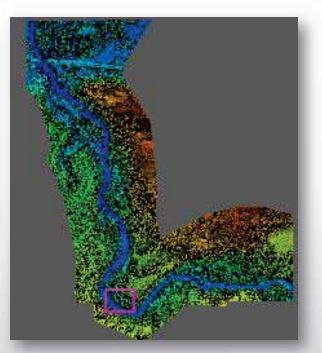
Geog 593 December 11, 2014



### Study Area



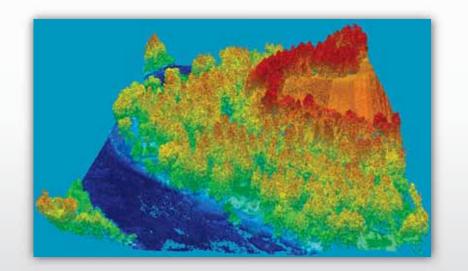
Scenic, private residential neighborhood along the Sandy River, east of Portland, OR, on the Historic Columbia River Highway



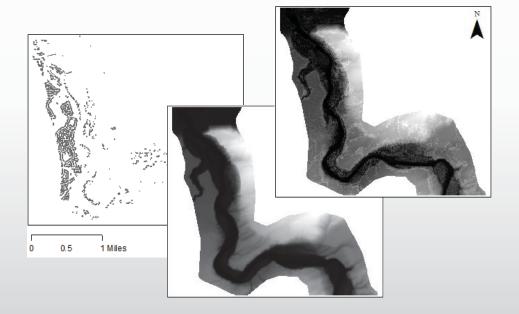
Data Source: Oregon LiDAR Consortium, Sandy River 2011 Lidar Project

# **ENVI: LiDAR for Feature Extraction**

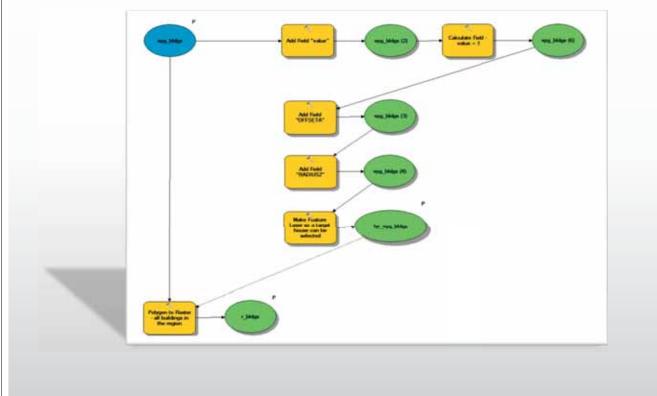
 Building footprints extracted from firstreturn lidar point cloud



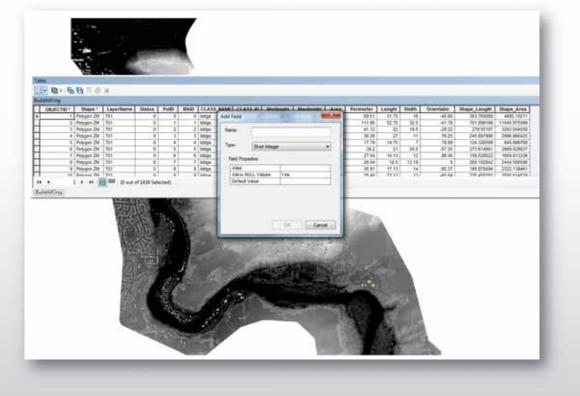
### Model Inputs: Building Footprints; Bare Earth and First Return DTMs



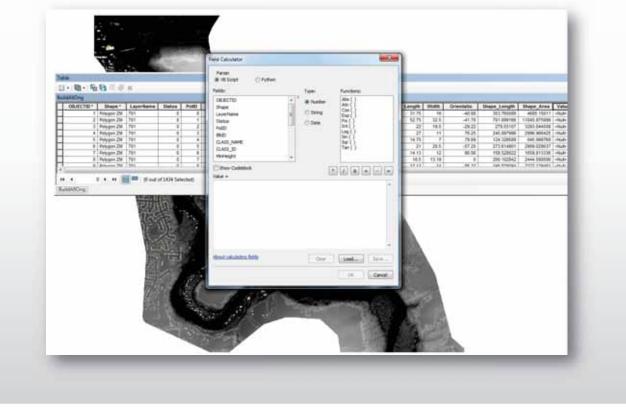
# Model 1: First tool



### Model 1: Add Fields



### Model 1: Field Calculator

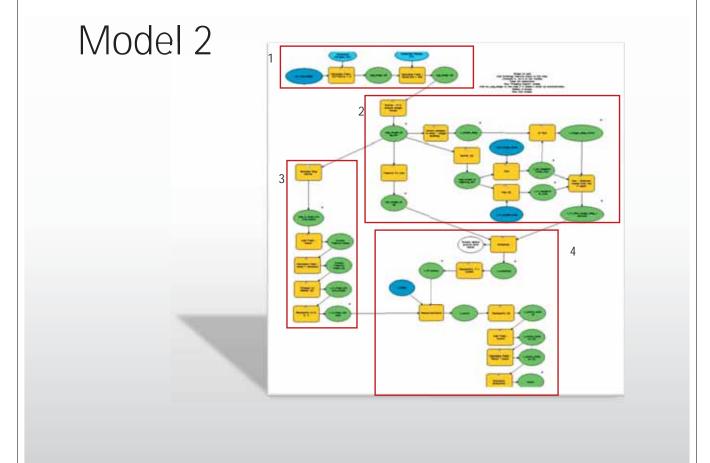


#### Model 1: Create Building Layer

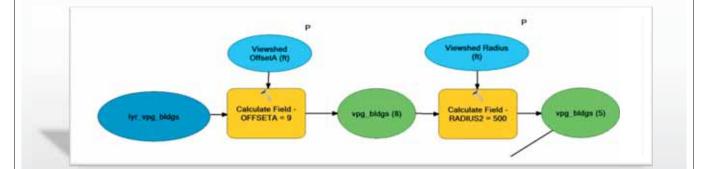
 Nation Frankane Layer	heaidh mOur
Paul Fredore Imp Malp, conjord Optic Lane Top, Malp, conjord ( ) ( ) ( ) Top, Malp, conjord ( ) ( ) ( ) Top, Malp, conjord ( ) ( ) ( ) ( ) ( ) ( ) ( ) ( ) ( ) (	Input Features

# Model 1: Polygon to Raster



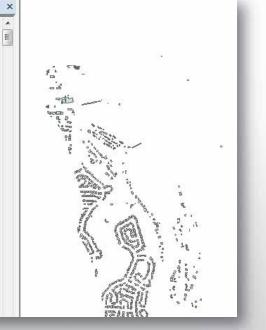


### Model 2: Segment 1, Calculate Fields

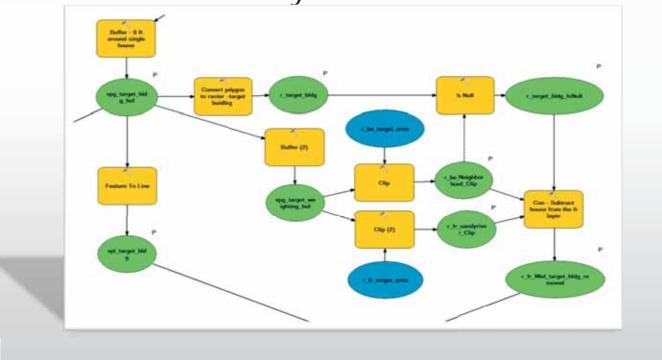


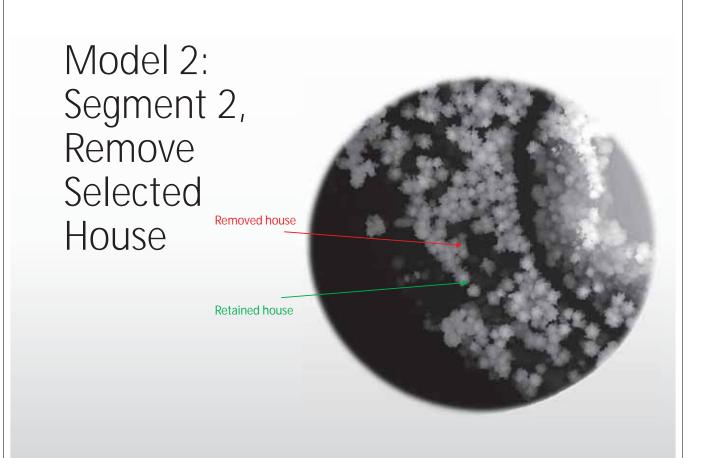
# Model 2: Segment 1, Calculate Fields

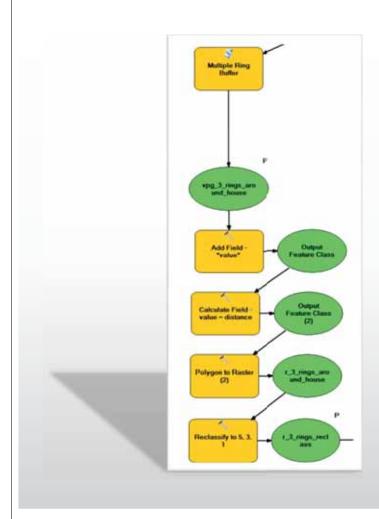
I	Shape_Length	Shape_Area	value	OFFSETA	RADIUS2
•	303.760088	4685.15011	1	9	500
T	701.899166	11045.975099	1	9	500
1	279.55107	3293.044508	1	9	500
1	245.897986	2996.966425	1	9	500
1	124.326589	845.999768	1	9	500
	273.614901	2909.029037	1	9	500
	158.528022	1659.813336	1	9	500
	200.102842	2444.580506	1	9	500
	195.878094	2322.139461	1	9	500
	225.450282	2505.614529	1	9	500
1	175.777819	1143.95739	1	9	500
1	88.531329	390.485865	1	9	500
1	72.701933	271.086835	1	9	500
1	101.9464	382.073595	1	9	500
1	307.232966	4648.839179	1	9	500
1	242.77959	3051.904736	1	9	500
1	230.909315	2799.134397	1	9	500
1	148.674875	1293.155204	1	9	500
1	86.831722	352.79534	1	9	500
1	194.683408	2248.87153	1	9	500
1	197.57682	2251.297673	1	9	500
1	65.478903	255.245089	1	9	500
1	319.675936	3977.516796	1	9	500
1	201.217071	2167.390125	1	9	500
1	124.281444	372.443833	1	9	500
1	187 651004	1696.03829	1	9	500



# Model 2: Segment 2, Null House and Create Polyline

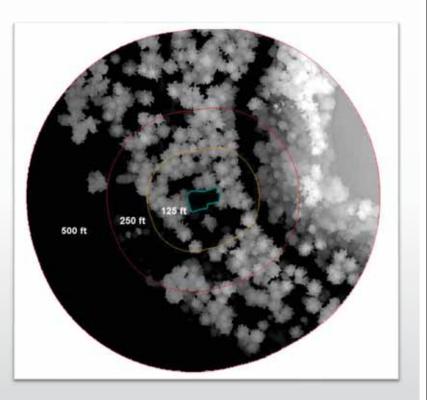




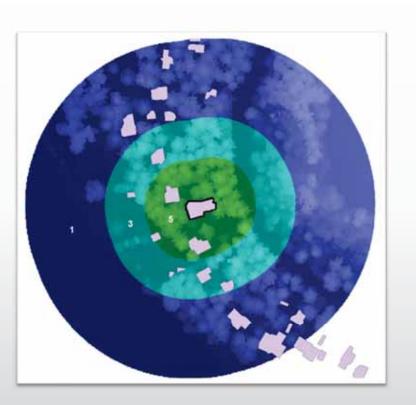


Model 2: Segment3, Multiple Ring Buffer

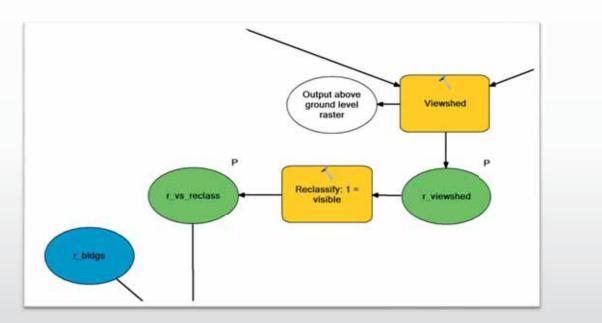
Model 2: Segment 3, Multiple Ring Buffer



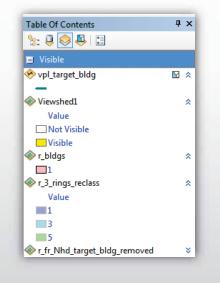
Model 2: Segment 3, Polygon to Raster & Reclassify

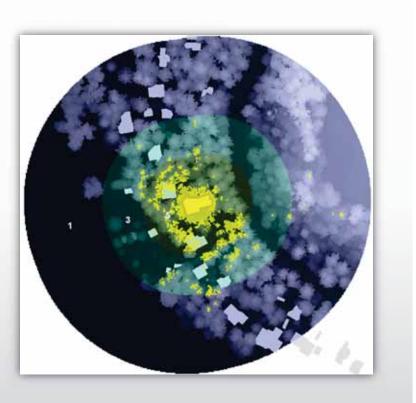


## Model 2: Segment 4, Viewshed

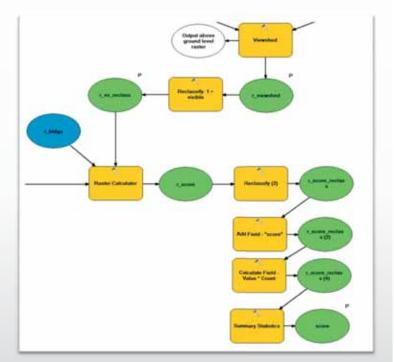


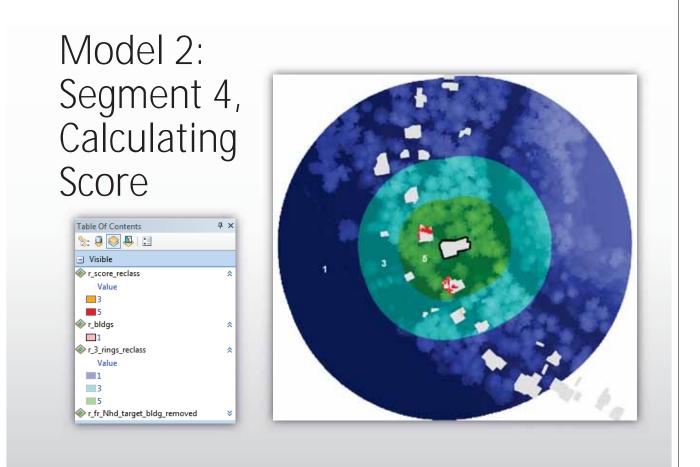
### Model 2: Segment 4, Viewshed





Model 2: Segment 4, Calculating Privacy Score





# Model 2: Segment 4, Privacy Score: '922'.

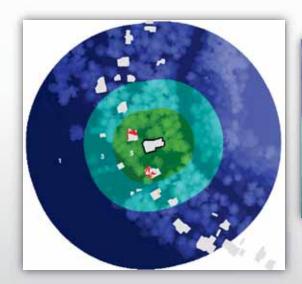
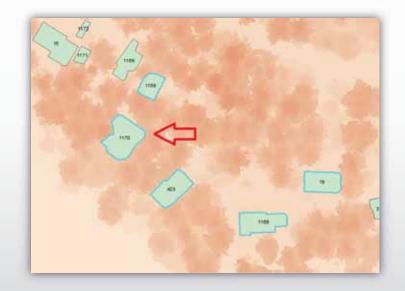


Table	□ ×					
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ScoreSumStats ×						
OBJECTID *	FREQUENCY	SUM_score				
▶ 1	2	922				
(0 out of 1 Selected)						
ScoreSumStats						

### Results of 5 Test Houses



Building ID	Privacy Score
1170	No Data (perfect privacy)
423	1
1168	25
1166	705
19	1234

#### Issues

Lidar feature extraction errors:

- Some buildings missed
- Some natural features (hedge) classified as buildings



### Conclusion

- We have created a reusable tool
- Enhancements
  - Window locations could be used instead of the vertices of the building footprint (note this would require additional data input by the user);
  - Include 2nd and 3rd floors
  - Include outside recreation areas
  - Road visibility
  - Privacy enhancement by the addition of landscaping.

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