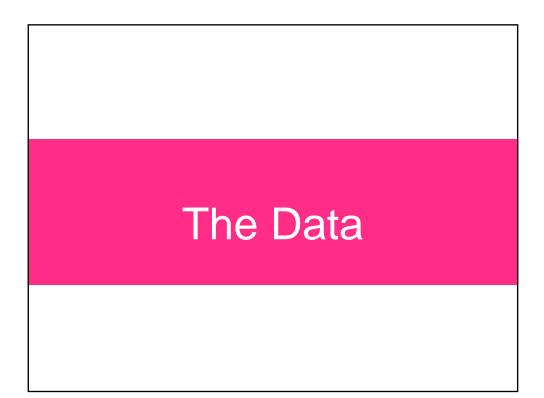
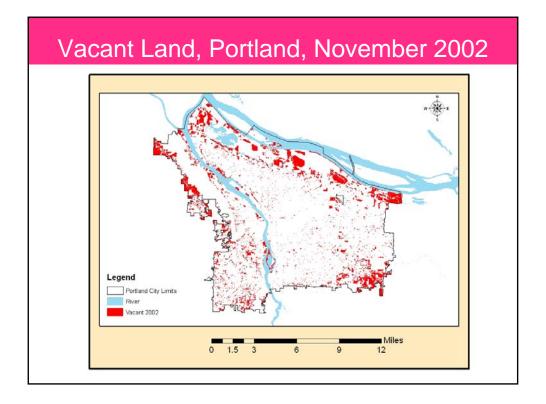


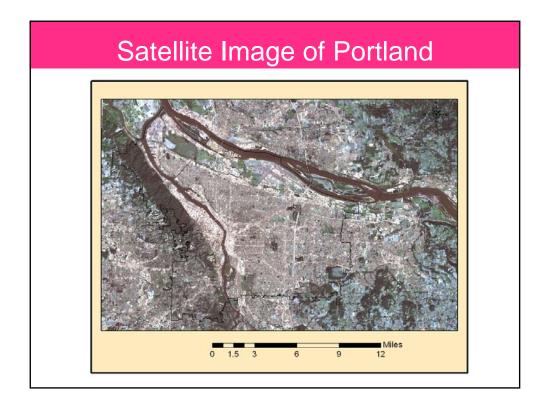
#### New Idea

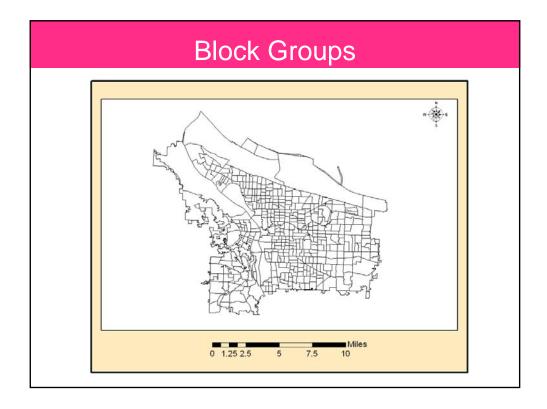
- Using similar data, and the much more accessible RLIS system, we came up with comparing development patterns in Portland, using vacant land data from 2002 and 2007
- Additionally, we will compare the development patterns to land cover and analyze runoff data.



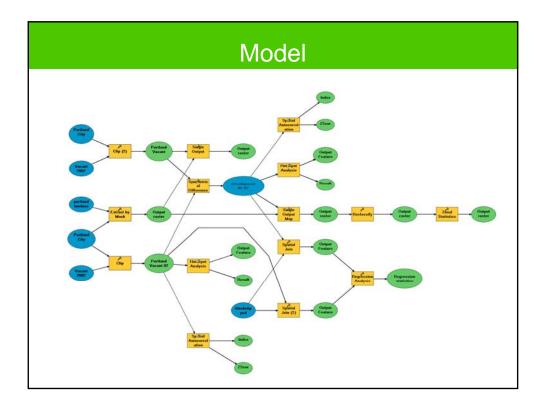


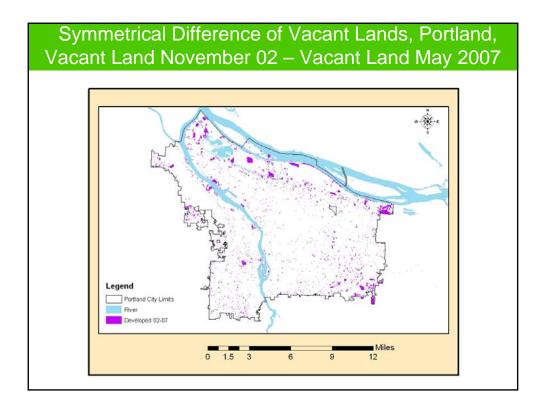


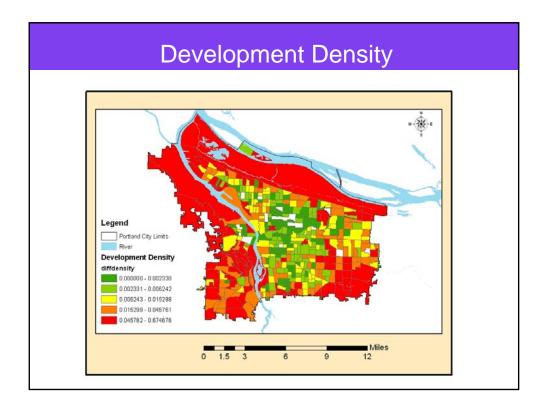




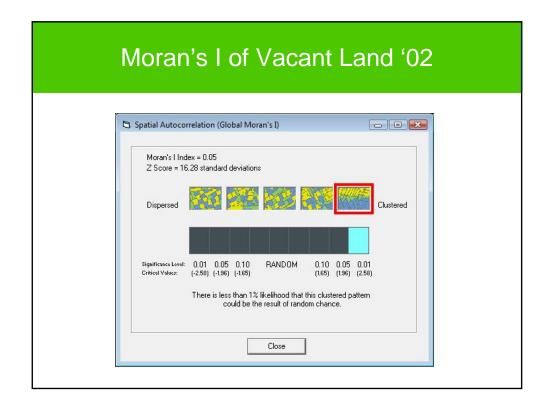


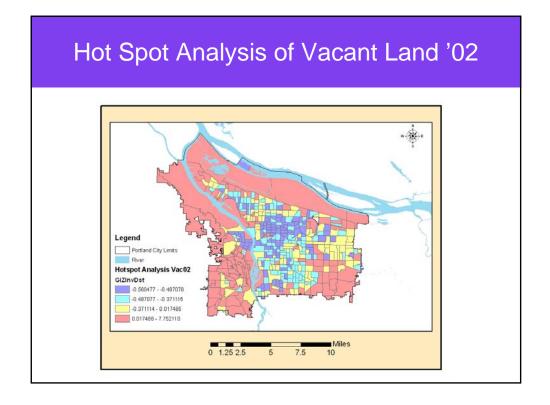


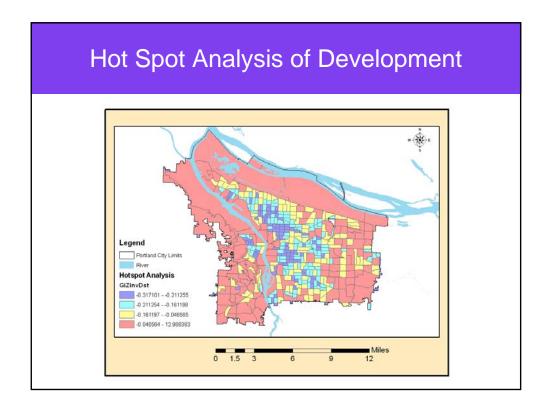


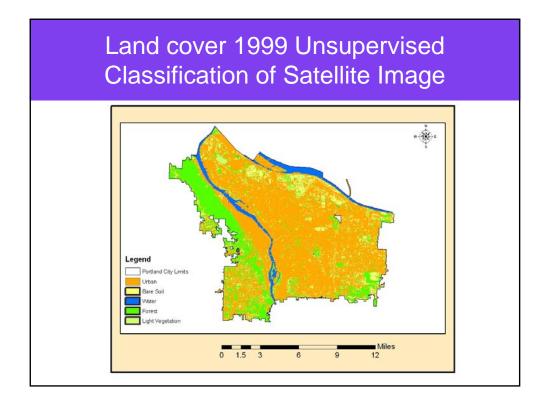


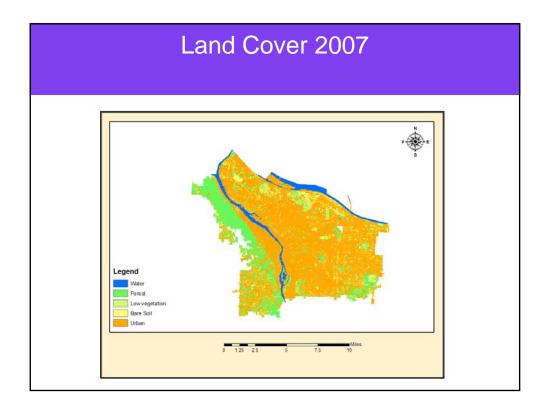
🖏 Spatial Autoco	orrelation (Global Moran's I)
Moran's I In Z Score = 1	dex = 0.04 2.15 standard deviations
Dispersed	Clustered
Significance Level Critical Values:	(-2.58) (-1.96) (-1.65) (1.65) (1.96) (2.58)
	There is less than 1% likelihood that this clustered pattern could be the result of random chance.
	Close



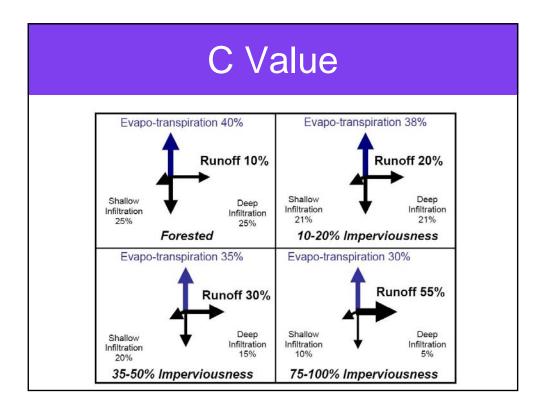








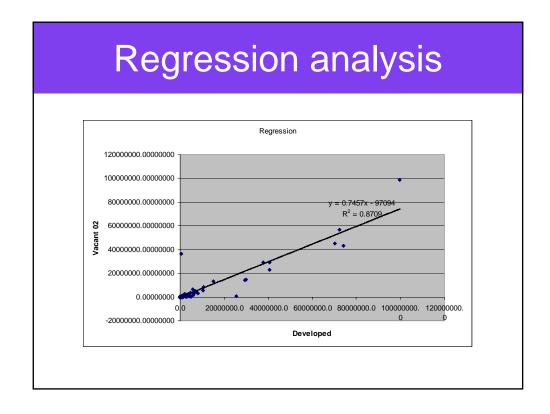




### C Value

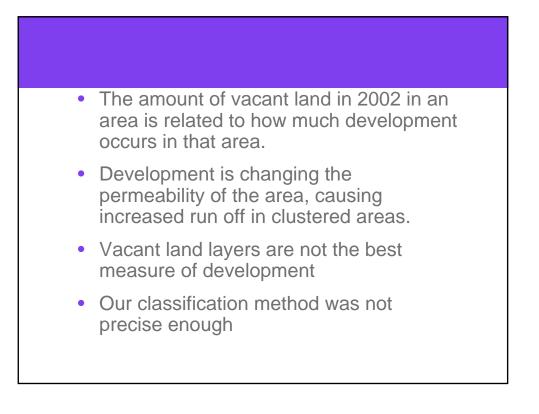
- R = C A I
- where R is the peak rate of runoff in cfs, A is area in acres, I is rainfall intensity in inches per hour, and C is the weighted C factor for the entire basin
- As Impervious surface increases 10-20%, runoff increases\*2, 35-50% \*3, 75-100%,\*5

C Value			
	Land Classes 07	If all vacant lands were developed	
Water			
	5 %	5 %	
Forest			
	16.8 %	14 %	
Light Vegetation			
	6 %	5.8 %	
Bare Soil			
	6.5 %	4.9 %	
Urban			
	65.7 %	70.3 %	





# Conclusions



### Next Steps?

- Track down actual rain fall data
- Using taxlot data, building foot print data and higher resolution satellite imagery, it would be possible to show more precise and accurate patterns in development.
- Track down a surface runoff model (expensive and need lots of data inputs)

## Data sources

- RLIS
- Landsat data Earth Science Data Interface (ESDI) at the Global Land Cover Facility
- Arnold CL, Gibbons CJ. 1996 Impervious surface coverage: the emergence of a key environmental indicator. American Planners Association Journal. 62:243-58.