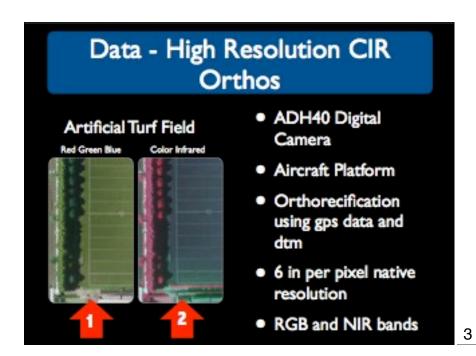
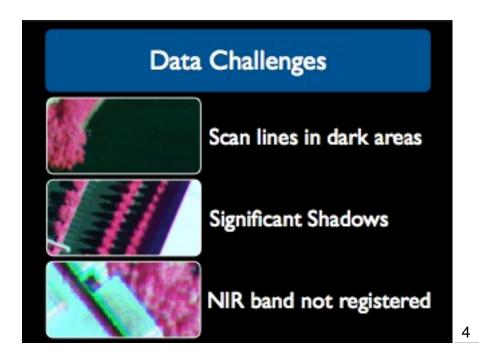


# **Todays Presentation**

- Project Goals Automation
- Data High Resolution Color Infrared Orthophotos
- Methods Object Oriented Extraction
- Results of Pilot Project
- Lessons Learned







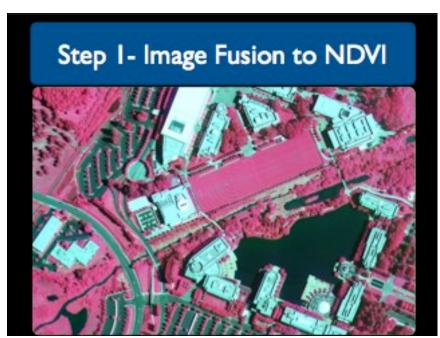
## Methods - Feature Analyst

- Visual Learning Systems Feature Analyst
  - Object based classification
  - Uses inductive learning algorithms to model feature recognition process
    - User gives a sample of the features to be extracted
  - Genetic Ensemble Feature Selection

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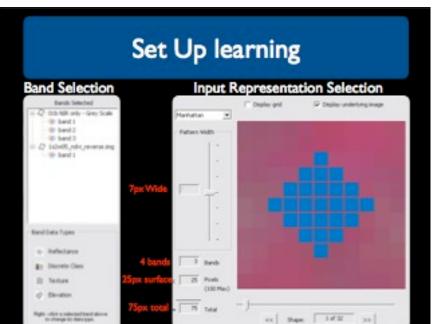
### Methods - 2 Processes

- Decision Tree
  - Used Multiple operation to maximize differences in the desired classes
  - Good for one image
- Multi Input Feature Extraction
  - One operation that makes use of a 4 class training layers
  - Can be batched to many images



-

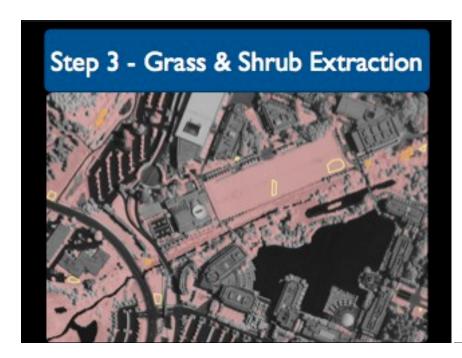
# Step 2- Extract Vegetation



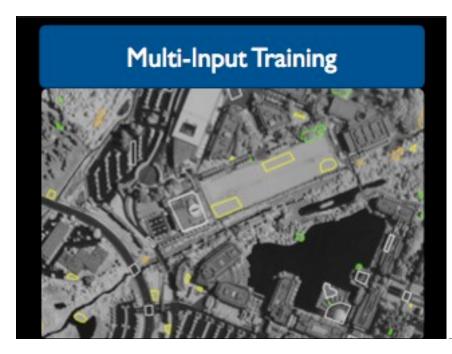


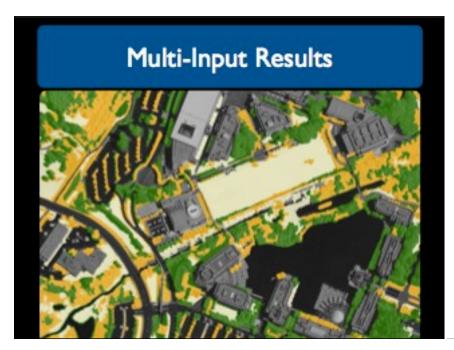












Deci	Decision Tree Accuracy						
	Reference Daça						
Classification Data	background	Grass	Shrub	Tree	Total	Users Accuracy %	K
background	93	0	0	0	93		1.00
Grass	0	19	0	-	20	95	.94
Shrub	0	2	20	3	25	80	27
Tree	0	2	3	57	62	92	.88
Total	93	23	23	61	200		
Producers Accuracy %		83	87	94			

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## **Lessons Learned**

- Need more reference points to asses accuracy
- · Need reference points based on field data
- The analysis would benefit from lidar to resolve vegetation in shadows and shrub area.
- At some point a method is needed to extract water and turn the "background" class into a credible impervious class.

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Thank You

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