

NGsolve::Come to the edge

Facet spaces and hybrid methods

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Download code (works only on version 6.0) for these notes [from here.](#)

“Come to the edge, he said/ We are afraid, they said” –Guillaume Apollinaire (French Poet)

Vector finite elements

- Unlike `ScalarFiniteElement`, vector finite elements have vector shape functions. These are needed, e.g., for flux computations ($H(\text{div})$), electromagnetic field computations ($H(\text{curl})$), etc.
- A typical example is the space built from `HDivFiniteElement`, accessible in a pde file using, e.g.,

```
fespace RT -type=hdivho -order=2
```

- Functions in the `hdivho` space have their normal components continuous across finite element interfaces.

Quiz 1: Project

Task: Given a vector function \vec{G} , compute its L^2 -projection into the `hdiv` finite element space.

- The projection \vec{q} in the `hdiv` finite element space satisfies

$$\int_{\Omega} \vec{q} \cdot \vec{r} = \int_{\Omega} \vec{G} \cdot \vec{r}$$

for all \vec{r} in the `hdiv` space.

- Make bilinear and linear forms out of the left and the right hand sides above using `pde` file commands. The integrators you will need are `masshdiv` and `sourcehdiv`.
- Write a complete `pde` file to compute the projection \vec{q} .

Quiz 2: Project into broken spaces

A **broken finite element space** is a finite element space whose continuity requirements across element interfaces have been removed. They are implemented in NGSolve using a “-discontinuous” flag:

```
fespace L -type=hdivho -order=2 -discontinuous
```

Task: Given a vector function \vec{G} , compute its L^2 -projection \vec{q}' into the above broken `hdivho` finite element space.

- Write a pde file to compute \vec{q}' .
- Check if $\|\vec{q}' - \vec{q}\|_{L^2(\Omega)} \neq 0$.

Quick introduction to “hybridization” of FE spaces

Noting that

$$\text{hdivho space} \subset \text{broken hdivho space},$$

we may compute the projection \vec{q} remaining within the broken hdivho space, provided we add the interelement continuity constraints of the hdivho space as additional equations in the definition of \vec{q} .

Computing \vec{q} using the broken hdivho space:

$$\sum_{\text{elements } K} \int_K \vec{q} \cdot \vec{r} + \sum_{\text{edges } E} \int_E \lambda \text{jump}(q \cdot n) = \int_{\Omega} \vec{G} \cdot \vec{r}$$
$$\sum_{\text{edges } E} \int_E \text{jump}(q \cdot n) \mu = 0$$

where \vec{q} and \vec{r} are in the broken hdivho space and λ, μ are in a Lagrange multiplier space. (Precise definitions are in the upcoming code.)

Facet finite element spaces

The Lagrange multipliers live on facets (edges in 2D, faces in 3D).

- Use class `FacetFESpace` and class `FacetVolumeFiniteElement` for implementing these spaces.
- Functions on different facets have no continuity across subfacets like vertices (or edges in 3D)
- `FacetFESpace` functions are accessed via the mesh elements which then can access their facets.
- In PDE file: `fespace M -type=facet -order=2`
- Need to write our own integrator for terms like

$$\sum_{edges\ E} \int_E \lambda \text{jump}(q \cdot n)$$

which is equivalent to

$$\sum_{elements\ K} \int_{\partial K} \lambda q \cdot n, \quad \lambda|_{\partial\Omega} = 0.$$

A hybridized implementation in pde file

```
# FILE: hybridproj.pde
fespace L -type=hdivho -order=2 -discontinuous
fespace M -type=facet -order=2 -dirichlet=[1]
fespace LM -type=compound -spaces=[L,M]

# ...

bilinearform a3 -fespace=LM -symmetric
masshdiv one -comp=1 # Integrator from NGSolve.
njump one # Integrator not provided by NGSolve!

linearform b3 -fespace=LM
sourcehdiv G -comp=1

gridfunction ql -fespace=LM -addcoef

numproc bvp nbvp3 -bilinearform=a3 -linearform=b3
                -symmetric -eliminate_internal
                -gridfunction=ql -solver=direct
```

Writing integrators in C++

```
template<int D> // FILE: njumpintegrator.cpp
class FacetNormalJump : public BilinearFormIntegrator {

    shared_ptr<CoefficientFunction> coef;

public:

    FacetNormalJump(const Array<shared_ptr<CoefficientFunction>> &
        : BilinearFormIntegrator() { coef = coeffs[0]; }

    virtual string Name () const { return "FacetNormalJump"; }
    virtual int DimElement () const { return D-1; }
    virtual int DimSpace () const { return D; }
    virtual bool BoundaryForm () const { return false; }
    void CalcElementMatrix(const FiniteElement& fel,
        const ElementTransformation& eltrans,
        FlatMatrix<double> elmat,
        LocalHeap& lh) const ;

    // Make the element matrix for the form
    //  $J((q,l), (r,m)) = \langle l, r.n \rangle + \langle q.n, m \rangle$  ....
```


Integrators

- Study line by line `njumpintegrator.cpp` (heavily commented).
 - Check out `my_little_nginxsolve` for other examples on writing your own integrators.
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Student Team Project: Learn about the “HDG method,” and implement it for the Helmholtz equation.