

# LIMITED DEPENDENT VARIABLES

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## 0. Introduction

This is intended to be an account of certain salient themes of the Limited Dependent Variable (LDV) literature. The object will be to acquaint the reader with the nature of the basic problems and the major results rather than recount just who did what when. An extended bibliography is given at the end, that attempts to list as many papers as have come to my attention—even if only by title.

By LDV we will mean instances of (dependent) variables—i.e. variables to be explained in terms of some economic model or rationalizing scheme for which (a) their range is intrinsically a finite discrete set and any attempt to extend it to the real line (or the appropriate multivariable generalization) not only does not lead to useful simplification, but befouls any attempt to resolve the issues at hand; (b) even though their range may be the real (half) line (or the appropriate multivariable generalization) their behavior is conditioned on another process(es).

Examples of the first type are models of occupational choice, entry into labor force, entry into college upon high school graduation, utilization of recreational facilities, utilization of modes of transport, childbearing, etc.

Examples of the latter are models of housing prices and wages in terms of the relevant characteristics of the housing unit or the individual—what is commonly referred to as hedonic price determination. Under this category we will also consider the case of truncated dependent observations.

In examining these issues we shall make an attempt to provide an economic rationalization for the model considered, but our main objective will be to show why common procedures such as least squares fail to give acceptable results; how one approaches these problems by maximum likelihood procedures and how one can handle problems of inference—chiefly by determining the limiting distributions of the relevant estimators. An attempt will be made to handle all problems in a reasonably uniform manner and by relatively elementary means.

## 1. Logit and probit

### 1.1. Generalities

Consider first the problem faced by a youth completing high school; or by a married female who has attained the desired size of her family. In the instance of the former the choice to be modelled is going to college or not; in the case of the latter we need to model the choice of entering the labor force or not.

Suppose that as a result of a properly conducted survey we have observations on  $T$  individuals, concerning their socioeconomic characteristics and the choices they have made.

In order to free ourselves from dependence on the terminology of a particular subject when discussing these problems, let us note that, in either case, we are dealing with binary choice; let us denote this by

Alternative 1 Going to College or Entering Labor Force

Alternative 2 Not Going to College or Not Entering Labor Force

Since the two alternatives are exhaustive we may make alternative 1 correspond to an abstract event  $\mathcal{E}$  and alternative 2 correspond to its complement  $\bar{\mathcal{E}}$ . In this context it will be correct to say that what we are interested in is the set of factors affecting the occurrence or nonoccurrence of  $\mathcal{E}$ . What we have at our disposal is some information about the *attributes of these alternatives* and the (*socioeconomic*) *attributes of the individual exercising choice*. Of course we also observe the choices of the individual agent in question. Let

$$y_t = 1 \quad \text{if individual } t \text{ chooses in accordance with event } \mathcal{E}, \\ = 0 \quad \text{otherwise.}$$

Let

$$w = (w_1, w_2, \dots, w_s),$$

be a vector of characteristics relative to the alternatives corresponding to the events  $\mathcal{E}$  and  $\bar{\mathcal{E}}$ ; finally, let

$$r_t = (r_{t1}, \dots, r_{tm}),$$

be the vector describing the socioeconomic characteristics of the  $t$ th individual economic agent.

We may be tempted to model this phenomenon as

$$y_t = x_t \cdot \beta + \varepsilon_t, \quad t = 1, 2, \dots, T, \quad (1)$$

where

$$x_t = (w, r_t).$$

$\beta$  is a vector of unknown constants and

$$\varepsilon_t; t = 1, 2, \dots, T,$$

is a sequence of suitably defined error terms.

The formulation in (1) and subsequent estimation by least squares procedures was a common occurrence in the empirical research of the sixties.

### 1.2. *Why a general linear model (GLM) formulation is inappropriate*

Although the temptation to think of LDV problems in a GLM context is enormous a close examination will show that this is also fraught with considerable problems. At an intuitive level, we seek to approximate the dependent variable by a linear function of some other observables; the notion of approximation is based on ordinary Euclidean distance. That is quite sensible, in the usual GLM context, since no appreciable violence is done to the essence of the problem by thinking of the dependent variable as ranging without restriction over the real line—perhaps after suitably centering it first.

Since the linear function by which we approximate it is similarly unconstrained, it is not unreasonable to think of Euclidean distance as a suitable measure of proximity. Given these considerations we proceed to construct a logically consistent framework in which we can optimally apply various inferential procedures.

In the present context, however, it is not clear whether the notion of Euclidean distance makes a great deal of sense as a proximity measure. Notice that the dependent variable can only assume two possible values, while no comparable restrictions are placed on the first component of the right hand side of (1). Second, note that if we insist on putting this phenomenon in the GLM mold, then for observations in which

$$y_t = 1,$$

we must have

$$\varepsilon_t = 1 - x_t \cdot \beta, \tag{2}$$

while for observations in which

$$y_t = 0,$$

we must have

$$\varepsilon_t = -x_t \cdot \beta. \tag{3}$$

Thus, the error term can only assume two possible values, and we are immediately led to consider an issue that is important to the proper conceptualization of such models, viz., that what we need is *not* a linear model “explaining” the choices

individuals make, but rather a model of the probabilities corresponding to the choices in question. Thus, if we ask ourselves: what is the expectation of  $\varepsilon_t$ , we shall be forced to think of the probabilities attaching to the relations described in (2) and (3) and thus conclude that

$$\varepsilon_t = 1 - x_t \cdot \beta,$$

with probability equal to

$$p_{t1} = P(y_t = 1), \quad (4)$$

and

$$\varepsilon_t = -x_t \cdot \beta,$$

with probability

$$p_{t2} = P(y_t = 0) = 1 - p_{t1}. \quad (5)$$

What we really should be asking is: what determines the probability that the  $t$ th economic agent chooses in accordance with event  $\mathcal{E}$ , and eq. (1) should be viewed as a clumsy way of going about it. We see that putting

$$p_{t1} = F(x_t \cdot \beta) = \int_{-\infty}^{x_t \cdot \beta} f(\xi) d\xi, \quad (6)$$

$$p_{t2} = 1 - F(x_t \cdot \beta) = \int_{x_t \cdot \beta}^{\infty} f(\xi) d\xi, \quad (7)$$

where  $f(\cdot)$  is a suitable density function with known parameters, formalizes the dependence of the probabilities of choice on the observable characteristics of the individual and/or the alternatives.

To complete the argumentation about why the GLM is inapplicable in the present context we note further

$$E(\varepsilon_t) = F(x_t \cdot \beta)(1 - x_t \cdot \beta) + [1 - F(x_t \cdot \beta)](-x_t \cdot \beta) = F(x_t \cdot \beta) - x_t \cdot \beta, \quad (8)$$

$$\text{Var}(\varepsilon_t) = F(x_t \cdot \beta)[1 - F(x_t \cdot \beta)]. \quad (9)$$

Hence, *prima facie*, least squares techniques are not appropriate, even if the formulations in (1) made intuitive sense.

We shall see that similar situations arise in other LDV contexts in which the absurdity of least squares procedures is not as evident as it is here.

Thus, to recapitulate, least squares procedures are inapplicable

- i. because we should be interested in estimating the probability of choice; however, we are using a linear function to predict actual choices, without ensuring that the procedure will yield "predictions" satisfying the conditions that probabilities ought to satisfy
- ii. on a technical level the conditions on the error term that are compatible with the desirable properties of least squares estimators in the context of the GLM are patently false in the present case.

### 1.3. A utility maximization motivation

As before, consider an individual,  $t$ , who is faced with the choice problem as in the preceding section but who is also hypothesized to behave so as to maximize his utility in choosing between the two alternatives. In the preceding it is assumed that the individual's utility contains a random component. It involves little loss in relevance to write the utility function as

$$U_t = u(w, r_t; \theta) + \varepsilon_t, \quad t = 1, 2, \dots, T,$$

where

$$u(w, r_t; \theta) \equiv E(U|w, r_t.), \quad \varepsilon_t \equiv U_t - u(w, r_t; \theta).$$

For the moment we shall dispense with the subscript  $t$  referring to the  $t$ th individual.

If the individual chooses according to event  $\mathcal{E}$ , his utility is (where now any subscripts refer to alternatives),

$$U_1 = u(w, r; \theta_1) + \varepsilon_1. \quad (10)$$

The justification for the parameter vector  $\theta$  being subscripted is that, since  $w$  is constant across alternatives,  $\theta$  must vary. While this may seem unnatural to the reader it is actually much more convenient, as the following development will make clear.

If the individual chooses in accordance with  $\bar{\mathcal{E}}$ , then

$$U_2 = u(w, r; \theta_2) + \varepsilon_2. \quad (11)$$

Hence, choice is in accordance with event  $\mathcal{E}$  if, say,

$$U_1 \geq U_2. \quad (12)$$

But (12) implies

Alternative 1 is chosen or choice is made in accordance with event  $\mathcal{E}$  if

$$\varepsilon_2 - \varepsilon_1 \leq u(w, r; \theta_1) - u(w, r; \theta_2), \quad (13)$$

which makes it abundantly clear that we can speak unambiguously *only* about the probabilities of choice. To “predict” choice we need an additional “rule” – such as, for example,

Alternative 1 is chosen when the probability attaching to event  $\mathcal{E}$  is 0.5 or higher.

If the functions  $u(\cdot)$  in (13) are linear, then the  $t$ th individual will choose Alternative 1 if

$$\varepsilon_{t2} - \varepsilon_{t1} \leq x_t \cdot \beta, \quad (14)$$

where

$$x_t = (w, r_t), \quad \beta = \theta_1 - \theta_2. \quad (15)$$

Hence, in the notation of the previous section

$$P(y_t = 1) = P(\varepsilon_{t2} - \varepsilon_{t1} \leq x_t \cdot \beta) = \int_{-\infty}^{x_t \cdot \beta} f_t(\xi) d\xi = F_t(x_t \cdot \beta), \quad (16)$$

where now  $f_t$  is the density function of  $\varepsilon_{t2} - \varepsilon_{t1}$ .

If

$$f_t(\cdot) = f_{t'}(\cdot), \quad t \neq t',$$

then we have a basis for estimating the parametric structure of our model. Before we examine estimation issues, however, let us consider some possible distribution for the errors, i.e. the random variables  $\varepsilon_{t1}, \varepsilon_{t2}$ .

Thus, suppose

$$\varepsilon_{t'} \sim N(0, \Sigma), \quad \Sigma = \begin{bmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{21} & \sigma_{22} \end{bmatrix}, \quad \Sigma > 0,$$

and the  $\varepsilon_t$ 's are independent identically distributed (i.i.d.). We easily find that

$$\varepsilon_{t2} - \varepsilon_{t1} \sim N(0, \sigma^2), \quad \sigma^2 = \sigma_{22} - 2\sigma_{12} + \sigma_{11}.$$

Hence

$$\Pr\{y_t = 1\} = \frac{1}{\sqrt{2\pi\sigma^2}} \int_{-\infty}^{x_t \cdot \beta} e^{-1/2\sigma^2\xi^2} d\xi = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{v_t} e^{-(1/2)\xi^2} d\xi = F(v_t),$$

where

$$v_t = \frac{x_t \cdot \beta}{\sqrt{\sigma^2}},$$

and  $F(\cdot)$  is the c.d.f. of the unit normal. Notice that in this context it is not possible to identify separately  $\beta$  and  $\sigma^2$  by observing solely the choices individuals make; we can only identify  $\beta/\sigma$ .

For reasons that we need not examine here, analysis based on the assumption that errors in (10) and (11) are normally distributed is called *Probit Analysis*.

We shall now examine another specification that is common in applied research, which is based on the logistic distribution. Thus, let  $q$  be an exponentially distributed random variable so that its density is

$$g(q) = e^{-q} \quad q \in (0, \infty), \quad (17)$$

and consider the distribution of

$$v = \ln(q)^{-1} = -\ln q. \quad (18)$$

The Jacobian of this transformation is

$$J(r \rightarrow q) = e^{-v}.$$

Hence, the density of  $v$  is

$$h(v) = \exp - v \exp - e^{-v} \quad v \in (-\infty, \infty). \quad (19)$$

If the  $\varepsilon_{ti}$ ,  $i = 1, 2$  of (14) are mutually independent with density as in (19), then the joint density is

$$h(\varepsilon_1, \varepsilon_2) = \exp - (\varepsilon_1 + \varepsilon_2) \exp - (e^{-\varepsilon_1} + e^{-\varepsilon_2}). \quad (20)$$

Put

$$\begin{aligned} v_1 + v_2 &= \varepsilon_2, \\ v_2 &= \varepsilon_1. \end{aligned} \quad (21)$$

The Jacobian of this transformation is 1; hence the joint density of the  $v_i$ ,  $i = 1, 2$ , is given by

$$\exp - (v_1 + 2v_2) \exp - (e^{-v_2} + e^{-v_1 - v_2}).$$



Since

$$v_1 = \varepsilon_2 - \varepsilon_1,$$

the desired density is found as

$$g(v_1) = \int_{-\infty}^{\infty} \exp-(v_1 + 2v_2) \exp-(e^{-v_2} + e^{-v_1 - v_2}) dv_2.$$

To evaluate this put

$$1 + e^{-v_1} = t, \quad s = te^{-v_2},$$

to obtain

$$g(v_1) = \frac{e^{-v_1}}{t^2} \int_0^{\infty} se^{-s} ds = \frac{e^{-v_1}}{(1 + e^{-v_1})^2}.$$

Hence, in this case the probability of choosing Alternative 1 is given by

$$P(y_t = 1) = \int_{-\infty}^{x_t \beta} \frac{e^{-\xi}}{(1 - e^{-\xi})^2} d\xi = \frac{1}{1 + e^{-\xi}} \Bigg|_{-\infty}^{x_t \beta} = \frac{1}{1 + e^{-x_t \beta}},$$

$$P(y_t = 0) = 1 - F(x_t \beta) = \frac{e^{-x_t \beta}}{1 + e^{-x_t \beta}}.$$

This framework of binary or *dichotomous* choice easily generalizes to the case of *polytomous* choice, without any appreciable complication—see, e.g. Dhrymes (1978a).

#### 1.4. Maximum likelihood estimation

Although alternative estimation procedures are available we shall examine only the maximum likelihood (ML) estimator, which appears to be the most appropriate, given the sorts of data typically available to economists.

To recapitulate: we have the problem of estimating the parameters in a dichotomous choice context, characterized by a density function  $f(\cdot)$ ; we shall deal with the case where  $f(\cdot)$  is the *unit normal* and the *logistic*.

As before we define

$$\begin{aligned} y_t = 1 & \quad \text{if choice corresponds to event } \bar{\mathcal{E}} \\ = 0 & \quad \text{if choice corresponds to event } \mathcal{E} \end{aligned}$$

The event  $\mathcal{E}$  may correspond to entering the labor force or going to college in the examples considered earlier.

$$P(y_t = 1) = F(x_t, \beta),$$

where

$$x_t = (w, r_t),$$

$w$  is the  $s$ -element row vector describing the relevant attributes of the alternatives and  $r_t$  is the  $m$ -element row vector describing the relevant socioeconomic characteristics of the  $t$ th individual.

We recall that a likelihood function may be viewed in two ways: for purposes of estimation we take the sample as given (here the  $y_t$ 's and  $x_t$ 's) and regard it as a function of the unknown parameters (here the vector  $\beta$ ) with respect to which it is to be maximized; for purposes of deriving the limiting distribution of estimators it is appropriate to think of it as a function of the dependent variable(s)—and hence as one that encompasses the probabilistic structure imposed on the model. This dual view of the likelihood function (LF) will become evident below.

The LF is easily determined to be

$$L^* = \prod_{t=1}^T F(x_t, \beta)^{y_t} [1 - F(x_t, \beta)]^{1 - y_t}. \quad (22)$$

As usual, we find it more convenient to operate with its logarithm

$$\ln L^* = L = \sum_{t=1}^T \{ y_t \ln F(x_t, \beta) + (1 - y_t) \ln [1 - F(x_t, \beta)] \}. \quad (23)$$

For purposes of estimation, this form is unduly complicated by the presence of the random variables,  $y_t$ 's. Given the sample, we will know that some of the  $y_t$ 's assume the value one and others assume the value zero. We can certainly rearrange the observations so that the first  $T_1 \leq T$  observations correspond to

$$y_t = 1, \quad t = 1, 2, \dots, T_1,$$

while the remaining  $T_2 < T$  correspond to

$$y_{T_1+t} = 0, \quad t = 1, 2, \dots, T_2,$$

If we give effect to these statements the log likelihood function becomes

$$L = \sum_{t=1}^{T_1} \ln F(x_t, \beta) + \sum_{t=T_1+1}^{T_1+T_2} \ln [1 - F(x_t, \beta)], \quad (24)$$

and as such it does not contain any random variables<sup>1</sup> – *even symbolically!* Thus, it is rather easy for a beginning scholar to become confused as to how, solving

$$\frac{\partial L}{\partial \beta} = 0,$$

will yield an estimator, say  $\hat{\beta}$ , with any probabilistic properties. At least the analogous situation in the GLM

$$y = X\beta + u,$$

using the standard notation yields

$$\hat{\beta} = (X'X)^{-1}X'y,$$

and  $y$  is recognized to be a random variable with a probabilistic structure induced by our assumption on the structural error vector  $u$ .

Thus, we shall consistently avoid the use of the form in (24) and use instead the form in (23). As is well known, the ML estimator is found by solving

$$\frac{\partial L}{\partial \beta} = \sum_{t=1}^T \left[ y_t \frac{f(x_t, \beta)}{F(x_t, \beta)} - (1 - y_t) \frac{f(x_t, \beta)}{1 - F(x_t, \beta)} \right] x_t = 0. \quad (25)$$

We note that, in general, (25) is a highly nonlinear function of the unknown parameter  $\beta$  and, hence, can only be solved by iteration.

Since by definition a ML estimator,  $\hat{\beta}$ , is one obeying

$$L(\hat{\beta}) \geq L(\beta), \text{ for all admissible } \beta, \quad (26)$$

it is important to ensure that solving (25) does, indeed, yield a maximum in the form of (26) and not merely a local stationary point – at least asymptotically.

The assumptions under which the properties of the ML estimator may be established are partly motivated by the reason stated above. These assumptions are

#### *Assumption A.1.1.*

The explanatory variables are uniformly bounded, i.e.  $x_t \in H_*$ , for all  $t$ , where  $H_*$  is a closed bounded subset of  $R_{s+m}$ , i.e. the  $(s+m)$ -dimensional Euclidean space.

#### *Assumption A.1.2.*

The (admissible) parameter space is, similarly, a closed bounded subset of  $R_{s+m}$ , say,  $P_*$  such that  $P_* \supset N(\beta^0)$ , where  $N(\beta^0)$  is an open neighborhood of the true parameter point  $\beta^0$ .

<sup>1</sup>For any sample, of course, the choice of  $T_1$  is random.

*Remark 1*

Assumption (A.1.1.) is rather innocuous and merely states that the socioeconomic variables of interest are bounded. Assumption (A.1.2.) is similarly innocuous. The technical import of these assumptions is to ensure that, at least asymptotically, the maximum maximum of (24) is properly located by the calculus methods of (25) and to also ensure that the equations in (25) are well defined by precluding a singularity due to

$$F(x_t, \beta) = 0 \quad \text{or} \quad 1 - F(x_t, \beta) = 0.$$

Moreover, these assumptions also play a role in the argument demonstrating the consistency of the ML estimator.

To the above we add another condition, well known in the context of the general linear model (GLM).

*Assumption A.1.3.*

Let

$$X = (x_{t.}) \quad t = 1, 2, \dots, T,$$

where the elements of  $x_{t.}$  are nonstochastic. Then

$$\text{rank}(X) = s + m, \quad \lim_{T \rightarrow \infty} \frac{X'X}{T} = M > 0.$$

With the aid of these assumptions we can easily demonstrate (the proof will not be given here) the validity of the following

*Theorem 1*

Given assumption A.1.1. through A.1.3. the log likelihood function,  $L$  of (24), is concave in  $\beta$ , whether  $F(\cdot)$  is the unit normal or the logistic c.d.f..

*Remark 2*

The practical implication of Theorem 1 is that, at any sample size, if we can satisfy ourselves that the LF of (24) does not attain its maximum on the boundary of the parameter space, then a solution to (25), say  $\hat{\beta}$ , obeys

$$L(\hat{\beta}) \geq L(\beta) \quad \text{for all admissible } \beta.$$

On the other hand as the sample size tends to infinity then with probability one the condition above is satisfied.

The (limiting) properties of the ML estimator necessary for carrying out tests of hypotheses are given in

*Theorem 2*

The ML estimator,  $\hat{\beta}$ , in the logistic as well as the normal case is strongly consistent and moreover it obeys

$$\sqrt{T}(\hat{\beta} - \beta) \sim N(0, C),$$

when

$$C^{-1} = - \lim_{T \rightarrow \infty} \frac{1}{T} E \left[ \frac{\partial^2 L}{\partial \beta \partial \beta} (\beta^0) \right].$$

*Corollary 1*

A consistent estimator of the covariance matrix of the limiting distribution is given, in the case of normal density,  $f$ , and c.d.f.,  $F$ , by

$$\hat{C} = \left\{ \frac{1}{T} \sum \left[ \frac{f^2(x_t, \hat{\beta})}{F(x_t, \hat{\beta})[1 - F(x_t, \hat{\beta})]} x'_t x_t \right] \right\}^{-1}, \quad (27)$$

For the logistic c.d.f. (logit) this reduces to

$$\hat{C} = \left[ \frac{1}{T} \sum_{t=1}^T f(x_t, \hat{\beta}) x'_t x_t \right]^{-1}. \quad (28)$$

### 1.5. Goodness of fit

In the context of the GLM the coefficient of determination of multiple regression ( $R^2$ ) has at least three useful interpretations.

- i. it stands in a one-to-one relation to the  $F$ -statistic for testing the hypothesis that the coefficients of the *bona fide* explanatory variables are zero;
- ii. it is a measure of the reduction of the variability of the dependent variable through the *bona fide* explanatory variables;
- iii. it is the square of the simple correlation coefficient between predicted and actual values of the dependent variable within the sample.

Unfortunately, in the case of the discrete choice models under consideration we do not have a statistic that fits all three characterizations above. We can, on the other hand, define one that essentially performs the first two functions.

In order to demonstrate these facts it will be convenient to represent the maximized (log) LF more informatively. Assuming that the ML estimator corresponds to an interior point of the admissible parameter space we can write

$$L(\hat{\beta}) = L(\beta^0) + \frac{\partial L}{\partial \beta}(\beta^0)(\hat{\beta} - \beta^0) + \frac{1}{2}(\hat{\beta} - \beta^0)' \frac{\partial^2 L}{\partial \beta \partial \beta}(\beta^0)(\hat{\beta} - \beta^0) + \text{third order terms.} \quad (29)$$

The typical third order term involves

$$\phi_T = \frac{1}{6} \frac{1}{T^{3/2}} \frac{\partial^3 L}{\partial \beta_i \partial \beta_j \partial \beta_k}(\beta^*) \sqrt{T}(\hat{\beta}_i - \beta_i^0) \sqrt{T}(\hat{\beta}_j - \beta_j^0) \sqrt{T}(\hat{\beta}_k - \beta_k^0).$$

It is our contention that

$$\text{plim}_{T \rightarrow \infty} \phi_T = 0. \quad (30)$$

Now,

$$\text{plim}_{T \rightarrow \infty} \frac{1}{T} \frac{\partial^3 L}{\partial \beta_i \partial \beta_j \partial \beta_k}(\beta^*) = \bar{L}_{ijk},$$

is a well defined, finite quantity, where

$$|\beta^* - \beta^0| \leq |\hat{\beta} - \beta^0|.$$

But then, (30) is obvious since it can be readily shown that

$$\text{plim}_{T \rightarrow \infty} \frac{1}{T^{3/2}} \frac{\partial^3 L}{\partial \beta_i \partial \beta_j \partial \beta_k} = 0,$$

and moreover that

$$\sqrt{T}(\hat{\beta}_i - \beta_i^0), \sqrt{T}(\hat{\beta}_j - \beta_j^0), \sqrt{T}(\hat{\beta}_k - \beta_k^0),$$

are a.c. finite. Hence, for large samples, approximately

$$L(\hat{\beta}) \sim L(\beta^0) + \frac{\partial L}{\partial \beta}(\beta^0)(\hat{\beta} - \beta^0) + \frac{1}{2}(\hat{\beta} - \beta^0)' \frac{\partial^2 L}{\partial \beta \partial \beta}(\beta^0)(\hat{\beta} - \beta^0).$$

On the other hand, expanding  $\frac{\partial L}{\partial \beta}$  by Taylor series we find

$$\frac{1}{\sqrt{T}} \frac{\partial L}{\partial \beta}(\beta^0) \sim - \left[ \frac{1}{T} \frac{\partial^2 L}{\partial \beta \partial \beta}(\beta^0) \right] \sqrt{T}(\hat{\beta} - \beta^0).$$

Thus,

$$\frac{\partial L}{\partial \beta}(\beta^0)(\hat{\beta} - \beta^0) \sim -(\hat{\beta} - \beta^0)' \frac{\partial^2 L}{\partial \beta \partial \beta}(\beta^0)(\hat{\beta} - \beta^0),$$

and, consequently, for large samples

$$L(\hat{\beta}) \sim L(\beta^0) - \frac{1}{2}(\hat{\beta} - \beta^0)' \frac{\partial^2 L}{\partial \beta \partial \beta}(\beta^0)(\hat{\beta} - \beta^0).$$

Hence

$$2[L(\hat{\beta}) - L(\beta^0)] \sim -(\hat{\beta} - \beta^0)' \frac{\partial^2 L}{\partial \beta \partial \beta}(\beta^0)(\hat{\beta} - \beta^0) \sim \chi_{s+m}^2. \quad (31)$$

Consider now the hypothesis

$$H_0: \quad \beta^0 = 0, \quad (32)$$

as against

$$H_1: \quad \beta^0 \neq 0.$$

Under  $H_0$

$$L(\beta^0) = \sum_{i=1}^T \{ y_i \ln F(0) + (1 - y_i) \ln [1 - F(0)] \} = T \ln \left( \frac{1}{2} \right),$$

and

$$2[L(\hat{\beta}) - T \ln \frac{1}{2}] \sim \chi_{s+m}^2,$$

is a test statistic for testing the null hypothesis in (32). On the other hand, this is not a useful basis for defining an  $R^2$  statistic, for it implicitly juxtaposes the economically motivated model that defines the probability of choice as a function of

$$x_t, \beta,$$

and the model based on the *principle of insufficient reason* which states that the probability to be assigned to choice corresponding to the event  $\mathcal{E}$  and that corresponding to its complement  $\bar{\mathcal{E}}$  are both  $\frac{1}{2}$ . It would be far more meaningful to consider the null hypothesis to be

$$\beta^0 = \begin{pmatrix} \beta_0^0 \\ 0 \end{pmatrix},$$

i.e. to follow for a nonzero constant term, much as we do in the case of the GLM. The null hypothesis as above would correspond to assigning a probability to choice corresponding to event  $\mathcal{E}$  by

$$\bar{y} = F(\tilde{\beta}_0) \quad \text{or} \quad \tilde{\beta}_0 = F^{-1}(\bar{y}),$$

where

$$\bar{y} = \frac{1}{T} \sum_{t=1}^T y_t.$$

Thus, for some null hypothesis  $H_0$ , let

$$L(\tilde{\beta}) = \sup_{H_0} L(\beta).$$

By an argument analogous to that leading to (31) we conclude that

$$\begin{aligned} 2[L(\hat{\beta}) - L(\tilde{\beta})] &\sim -(\hat{\beta} - \beta^0)' \frac{\partial^2 L}{\partial \beta \partial \beta}(\beta^0)(\hat{\beta} - \beta^0) \\ &\quad + (\tilde{\beta} - \beta^0)' \frac{\partial^2 L}{\partial \beta \partial \beta}(\beta^0)(\tilde{\beta} - \beta^0). \end{aligned} \quad (33)$$

In fact, (33) represents a transform of the likelihood ratio (LR) and as such it is a LR test statistic. We shall now show that in the case where

$$H_0: \beta_{(2)}^0 = 0, \quad \beta^0 = \begin{pmatrix} \beta_{(1)}^0 \\ \beta_{(2)}^0 \end{pmatrix},$$



the quantity in the right member of (33) reduces to a test<sup>2</sup> based on the marginal (limiting) distribution of

$$\sqrt{T}(\hat{\beta}_{(2)} - \beta_{(2)}^0).$$

To this effect put

$$\tilde{C}_* = \frac{1}{T} \frac{\partial^2 L}{\partial \beta \partial \beta}(\beta^0),$$

and note that

$$\frac{1}{\sqrt{T}} \frac{\partial L}{\partial \beta}(\beta^0) \sim -\tilde{C}_* \sqrt{T}(\hat{\beta} - \beta^0). \quad (34)$$

Partitioning

$$\tilde{C}_* = \begin{bmatrix} C_{*11} & C_{*12} \\ C_{*21} & C_{*22} \end{bmatrix},$$

conformably with

$$(\hat{\beta} - \beta^0) = \begin{bmatrix} \hat{\beta}_{(1)} - \beta_{(1)}^0 \\ \hat{\beta}_{(2)} - \beta_{(2)}^0 \end{bmatrix},$$

we find

$$\begin{aligned} \frac{1}{\sqrt{T}} \frac{\partial L}{\partial \beta_{(1)}}(\beta^0) &\sim -[\tilde{C}_{*11} \sqrt{T}(\hat{\beta}_{(1)} - \beta_{(1)}^0) + \tilde{C}_{*12} \sqrt{T}(\hat{\beta}_{(2)} - \beta_{(2)}^0)], \\ \frac{1}{\sqrt{T}} \frac{\partial L}{\partial \beta_{(2)}}(\beta^0) &\sim -[\tilde{C}_{*21} \sqrt{T}(\hat{\beta}_{(1)} - \beta_{(1)}^0) + \tilde{C}_{*22} \sqrt{T}(\hat{\beta}_{(2)} - \beta_{(2)}^0)]. \end{aligned} \quad (35)$$

Using (34) we can rewrite (33) as

$$\begin{aligned} -2[L(\hat{\beta}) - L(\tilde{\beta})] &\sim -(\hat{\beta} - \beta^0)' \frac{\partial L}{\partial \beta}(\beta^0) + (\tilde{\beta} - \beta^0)' \frac{\partial L}{\partial \beta}(\beta^0) \\ &= -\left\{ [(\hat{\beta}_{(1)} - \beta_{(1)}^0) - (\tilde{\beta}_{(1)} - \beta_{(1)}^0)]' \frac{\partial L}{\partial \beta_{(1)}}(\beta^0) \right. \\ &\quad \left. + (\hat{\beta}_{(2)} - \beta_{(2)}^0)' \frac{\partial L}{\partial \beta_{(2)}}(\beta^0) \right\}. \end{aligned}$$

<sup>2</sup>It should be remarked that a similar result in the context of the GLM is called, somewhat redundantly, a Chow test.

From (34) we find, bearing in mind that under  $H_0$  we estimate

$$\begin{aligned} \tilde{\beta} &= \begin{pmatrix} \tilde{\beta}_{(1)} \\ 0 \end{pmatrix}, \\ \sqrt{T}(\tilde{\beta}_{(1)} - \beta_{(1)}^0) &\sim -\tilde{C}_{*11}^{-1} \frac{1}{\sqrt{T}} \frac{\partial L}{\partial \beta_{(1)}}(\beta^0). \end{aligned} \quad (36)$$

From (35) we find

$$-\sqrt{T}(\hat{\beta}_{(1)} - \beta_{(1)}^0) \sim \tilde{C}_{*11}^{-1} \left[ \frac{1}{\sqrt{T}} \frac{\partial L}{\partial \beta_{(1)}}(\beta^0) + \tilde{C}_{*12} \sqrt{T}(\hat{\beta}_{(2)} - \beta_{(2)}^0) \right]. \quad (37)$$

Hence

$$\left[ \sqrt{T}(\tilde{\beta}_{(1)} - \beta_{(1)}^0) - \sqrt{T}(\hat{\beta}_{(1)} - \beta_{(1)}^0) \right] \sim \tilde{C}_{*11}^{-1} \tilde{C}_{*12} \sqrt{T}(\hat{\beta}_{(2)} - \beta_{(2)}^0),$$

and thus (33) may be further rewritten as

$$-2[L(\hat{\beta}) - L(\tilde{\beta})] \sim [\hat{\beta}_{(2)} - \beta_{(2)}^0]' \left[ \tilde{C}_{*21} \tilde{C}_{*11}^{-1} \frac{\partial L}{\partial \beta_{(1)}}(\beta^0) - \frac{\partial L}{\partial \beta_{(2)}}(\beta^0) \right]. \quad (38)$$

Again, from (35) we see that

$$\begin{aligned} &\tilde{C}_{*21} \tilde{C}_{*11}^{-1} \frac{1}{\sqrt{T}} \frac{\partial L}{\partial \beta_{(1)}}(\beta^0) - \frac{1}{\sqrt{T}} \frac{\partial L}{\partial \beta_{(2)}}(\beta^0) \\ &\sim [\tilde{C}_{*22} - \tilde{C}_{*21} \tilde{C}_{*11}^{-1} \tilde{C}_{*12}] \cdot \sqrt{T}(\hat{\beta}_{(2)} - \beta_{(2)}^0), \end{aligned}$$

and thus (38) reduces to

$$-2[L(\hat{\beta}) - L(\tilde{\beta})] \sim T(\hat{\beta}_{(2)} - \beta_{(2)}^0)' [\tilde{C}_{*22} - \tilde{C}_{*21} \tilde{C}_{*11}^{-1} \tilde{C}_{*12}] (\hat{\beta}_{(2)} - \beta_{(2)}^0). \quad (39)$$

But under  $H_0$ , (39) is exactly the test statistic based on the (limiting) marginal distribution of

$$\sqrt{T}(\hat{\beta}_{(2)} - \beta_{(2)}^0) \sim N(0, 1 - C_{22}), \quad (40)$$

where

$$C_{22} = \text{plim}_{T \rightarrow \infty} [\tilde{C}_{*22} - \tilde{C}_{*21} \tilde{C}_{*11}^{-1} \tilde{C}_{*12}]^{-1}. \quad (41)$$

In the special case where

$$\beta_{(1)} = \beta_0,$$

i.e. it is the constant term in the expression

$$x_t \cdot \beta,$$

so that no bona fide explanatory variables “explain” the probability of choice, we can define  $R^2$  by

$$R^2 = 1 - \frac{L(\hat{\beta})}{L(\tilde{\beta})}. \quad (42)$$

The quantity in (42) has the property

- i.  $R^2 \in [0, 1)$
- ii. the larger the contribution of the bona fide variables to the maximum of the LF the closer is  $R^2$  to 1
- iii.  $R^2$  stands in a one-to-one relation to the chi-square statistic for testing the hypothesis that the coefficients of the bona fide variables are zero. In fact, under  $H_0$

$$-2L(\tilde{\beta})R^2 \sim \chi_{s+m-1}^2.$$

It is desirable, in empirical practice, that a statistic like  $R^2$  be reported and that a constant term be routinely included in the specification of the linear functional

$$x_t \cdot \beta,$$

Finally, we should also stress that  $R^2$  as in (42) *does not* have the interpretation as the square of the correlation coefficient between “predicted” and “actual” observations.

## 2. Truncated dependent variables

### 2.1. Generalities

Suppose we have a sample conveying information on consumer expenditures; in particular, suppose we are interested in studying household expenditures on consumer durables. In such a sample survey it would be routine that many

households report zero expenditures on consumer durables. This was, in fact, the situation faced by Tobin (1958) and he chose to model household expenditure on consumer durables as

$$y_t = \begin{cases} x_t \cdot \beta + u_t, & \text{if } x_t \cdot \beta + u_t > 0 \\ = 0 & \text{otherwise} \end{cases} \quad (43)$$

The same model was later studied by Amemiya (1973). We shall examine below the inference and distributional problem posed by the manner in which the model's dependent variable is truncated.

## 2.2. Why simple OLS procedures fail

Let us append to the model in (43) the standard assumptions that

(A.2.1.) The  $\{u_t; t=1,2,\dots\}$  is a sequence of i.i.d. random variables with

$$u_t \sim N(0, \sigma^2), \quad \sigma^2 \in (0, \infty).$$

(A.2.2.) The elements of  $x_t$  are bounded for all  $t$ , i.e.

$$|x_{ti}| < k_i, \quad \text{for all } t, \quad i=1,2,\dots,n,$$

are linearly independent and

$$(p) \lim_{T \rightarrow \infty} \frac{X'X}{T} = M,$$

exists as a nonsingular nonstochastic matrix.

(A.2.3.) If the elements of  $x_t$  are stochastic, then  $x_t, u_t$  are mutually independent for all  $t, t'$ , i.e. the error and data generating processes are mutually independent.

(A.2.4.) The parameter space, say  $H \subset R_{n+2}$ , is compact and it contains an open neighborhood of the true parameter point  $(\beta^0, \sigma_0^2)'$ .

The first question that occurs is why not use the entire sample to estimate  $\beta$ ? Thus, defining

$$X = (x_t), \quad t=1,2,\dots,T,$$

$$u = (u_1, u_2, \dots, u_T)', \quad y^{(1)} = (y_1, y_2, \dots, y_{T1})', \quad y^{(2)} = (0, \dots, 0)',$$

$$y = (y^{(1)'}, y^{(2)'})'$$

we may write

$$y = X\beta + u,$$

and estimate  $\beta$  by

$$\tilde{\beta} = (X'X)^{-1}X'y. \quad (44)$$

A little reflection will show, however, that this leads to serious and palpable specification error *since in (43) we do not assert that the zero observations are generated by the same process that generates the positive observations*. Indeed, a little further reflection would convince us that it would be utterly inappropriate to insist that the same process that generates the zero observations should also generate the nonzero observations, since for the zero observations we should have that

$$u_t = -x_t \cdot \beta, \quad t = T_{1+1}, \dots, T_1 + T_2,$$

and this would be inconsistent with assumption (A.1.1).

We next ask, why not confine our sample solely to the nonzero observations,

$$y^{(1)} = X_1\beta + u_{(1)},$$

and thus estimate  $\beta$  by

$$\tilde{\beta} = (X_1'X_1)^{-1}X_1'y^{(1)}.$$

This may appear quite reasonable at first, even though it is also apparent that we are ignoring some (perhaps considerable) information. Deeper probing, however, will disclose a much more serious problem. After all, ignoring some sample elements would affect only the degrees of freedom and the  $t$ - and  $F$ -statistics alone. If we already have a large sample, throwing out even a substantial part of it will not affect matters much. But now it is in order to ask: What is the process by which some dependent variables are assigned the value zero? A look at (43) convinces us that it is a random process governed by the behavior of the error process and the characteristics relevant to the economic agent,  $x_t$ . Conversely, the manner in which the sample on the basis of which we shall estimate  $\beta$  is selected is governed by some aspects of the error process. In particular we note that for us to observe a positive  $y_t$ , according to

$$y_t = x_t \cdot \beta + u_t, \quad (45)$$

the error process should satisfy

$$u_t > -x_t \cdot \beta. \quad (46)$$

Thus, for the positive observations we should be dealing with the *truncated* distribution function of the error process. But, what is the mean of the truncated distribution? We have, if  $f(\cdot)$  is the density and  $F(\cdot)$  the c.d.f. of  $u_t$

$$E(u_t | u_t > -x_t \cdot \beta) = \frac{1}{1 - F(-x_t \cdot \beta)} \int_{-x_t \cdot \beta}^{\infty} \xi f(\xi) d\xi.$$

If  $f(\cdot)$  is the  $N(0, \sigma^2)$  density the integral can be evaluated as

$$f(x_t \cdot \beta),$$

and, in addition, we also find

$$1 - F(-x_t \cdot \beta) = F(x_t \cdot \beta).$$

Moreover, if we denote by  $\phi(\cdot)$ ,  $\Phi(\cdot)$  the  $N(0,1)$  density and c.d.f., respectively, and by

$$v_t = \frac{x_t \cdot \beta}{\sigma}, \quad (47)$$

then

$$E(u_t | u_t > +x_t \cdot \beta) = \sigma \frac{\phi(v_t)}{\Phi(v_t)} = \sigma \psi_t. \quad (48)$$

Since the mean of the error process in (45) is given by (48) we see that we are committing a misspecification error by leaving out the "variable"  $\phi(v_t)/\Phi(v_t)$  [see Dhrymes (1978a)].

Defining

$$v_t = u_t - \sigma \frac{\phi(v_t)}{\Phi(v_t)}, \quad (49)$$

we see that  $\{v_t: t=1,2,\dots\}$  is a sequence of independent *but non-identically distributed random variables*, since

$$\text{Var}(v_t) = \sigma^2(1 - v_t \psi_t - \psi_t^2). \quad (50)$$

Thus, there is no simple procedure by which we can obtain efficient and/or consistent estimators by confining ourselves to the positive subsample; consequently, we are forced to revert to the entire sample and employ ML methods.

## 2.3. Estimation of parameters with ML methods

We are operating with the model in (43), subject to (A.2.1.) through (A.2.4.) and the convention that the first  $T_1$  observations correspond to positive dependent variables, while the remaining  $T_2$ , ( $T_1 + T_2 = T$ ), correspond to zero observations.

Define

$$\begin{aligned} c_t &= 1 && \text{if } y_t > 0, \\ &= 0 && \text{otherwise,} \end{aligned} \quad (51)$$

and note that the (log) LF can be written as

$$L = \sum_{t=1}^T \left\{ (1 - c_t) \ln \Phi(-v_t) - c_t \left[ \frac{1}{2} \ln(2\pi) + \frac{1}{2} \ln \sigma^2 + \frac{1}{2\sigma^2} (y_t - x_t \beta)^2 \right] \right\}. \quad (52)$$

Differentiating with respect to  $\gamma = (\beta', \sigma^2)'$ , we have

$$\frac{\partial L}{\partial \beta} = -\frac{1}{\sigma} \sum_{t=1}^T \left\{ (1 - c_t) \frac{\phi(v_t)}{\Phi(-v_t)} - c_t \left( \frac{y_t - x_t \beta}{\sigma} \right) \right\} x_t = 0, \quad (53)$$

$$\frac{\partial L}{\partial \sigma^2} = -\frac{1}{2\sigma^2} \sum_{t=1}^T \left\{ c_t \left[ 1 - \frac{1}{\sigma^2} (y_t - x_t \beta)^2 \right] - (1 - c_t) \frac{v_t \phi(v_t)}{\Phi(-v_t)} \right\} = 0,$$

and these equations have to be solved in order to obtain the ML estimator. It is, first, interesting to examine how the conditions in (53) differ from the equations to be satisfied by simple OLS estimators applied to the positive component of the sample. By simple rearrangement we obtain, using the convention alluded to above,

$$X_1' X_1 \beta = X_1' y^{(1)} - \sigma \sum_{t=T_1+1}^T \psi(-v_t) x_t', \quad (54)$$

$$\sigma^2 = \frac{1}{T_1} (y^{(1)} - X_1 \beta)' (y^{(1)} - X_1 \beta) + \frac{\sigma^2}{T_1} \sum_{t=T_1+1}^T \psi(-v_t) v_t, \quad (55)$$

where

$$\psi(v_t) = \frac{\phi(v_t)}{\Phi(v_t)}, \quad \psi(-v_t) = \frac{\phi(v_t)}{\Phi(-v_t)}. \quad (56)$$

Since these expressions occur very frequently, we shall often employ the abbrevia-

ted notation

$$\psi_t = \psi(v_t), \quad \psi_t^* = \psi(-v_t).$$

Thus, if in some sense

$$z'_T = \sum_{t=T_1+1}^T \psi_t^* x'_t, \quad (57)$$

is negligible, the ML estimator, say  $\hat{\beta}$ , could yield results that are quite similar, from an applications point of view, to those obtained through the simple OLS estimator, say  $\tilde{\beta}$ , as applied to the positive component of the sample. From (54) it is evident that if  $z'_T$  of (57) is small then

$$\sigma^2 \sum_{t=T_1+1}^T \psi_t^* v_t = \sigma z_T \beta,$$

is also small. Hence, under these circumstances

$$\hat{\beta} = \tilde{\beta}, \quad \hat{\sigma}^2 = \tilde{\sigma}^2$$

which explains the experience occasionally encountered in empirical applications.

The eqs. (53) or (54) and (55) are highly nonlinear and can only be solved by iterative methods. In order to ensure that the root of

$$\frac{\partial L}{\partial \gamma} = 0, \quad \gamma = (\beta', \sigma^2)',$$

so located is the ML estimator it is necessary to show either that the equation above has only one root – which is difficult – or that we begin the iteration with an initial consistent estimator.

#### 2.4. An initial consistent estimator

Bearing in mind the development in the preceding section we can rewrite the model describing the positive component of the sample as

$$y_t = x_t \beta + \sigma \psi_t + v_t = \sigma(v_t + \psi_t) + v_t, \quad (58)$$

such that

$$\{v_t: t=1, 2, \dots\},$$



is a sequence of mutually independent random variables with

$$E(v_t) = 0, \quad \text{Var}(v_t) = \sigma^2(1 - v_t\psi_t - \psi_t^2), \quad (59)$$

and such that they are independent of the explanatory variables  $x_t$ .

The model in (58) cannot be estimated by simple means owing to the fact that  $\psi_t$  is not directly observable; thus, we are forced into nonstandard procedures.

We shall present below a modification and simplification of a consistent estimator due to Amemiya (1973). First we note that, confining our attention to the positive component of the sample

$$y_t^2 = \sigma^2(v_t + \psi_t)^2 + v_t^2 + 2v_t(v_t + \psi_t)\sigma. \quad (60)$$

Hence

$$\begin{aligned} E(y_t^2 | x_t, u_t > -x_t\beta) &= \sigma^2(v_t^2 + v_t\psi_t) + \sigma^2 \\ &= x_t\beta E(y_t | x_t, u_t > -x_t\beta) + \sigma^2. \end{aligned} \quad (61)$$

Defining

$$\varepsilon_t \equiv y_t^2 - E(y_t^2 | x_t, u_t > -x_t\beta), \quad (62)$$

we see that  $\{\varepsilon_t; t = 1, 2, \dots\}$  is a sequence of independent random variables with mean zero and, furthermore, we can write

$$w_t = y_t^2 = x_t\beta y_t + \sigma^2 + \varepsilon_t, \quad t = 1, 2, \dots, T_1. \quad (63)$$

The problem, of course, is that  $y_t$  is correlated with  $\varepsilon_t$  and hence simple regression will not produce a consistent estimator for  $\beta$  and  $\sigma^2$ .

However, we can employ an instrumental variables (I.V.) estimator<sup>3</sup>

$$\bar{y} = (\tilde{X}'_* X_*)^{-1} X'_* w, \quad w = (w_1, w_2, \dots, w_{T_1})', \quad (64)$$

<sup>3</sup>It is here that the procedure differs from that suggested by Amemiya (1973). He defines

$$\bar{y}_t = x_t (X'_1 X_1)^{-1} X'_1 y^{(1)},$$

while we define

$$\bar{y}_t = x_t a,$$

for nontrivial vector  $a$ .

where

$$X_{\star} = (D_y X_1, e), \quad \tilde{X}_{\star} = (D_{\tilde{y}} X_1, e), \quad (65)$$

and

$$\tilde{y}_t = x_t \cdot a, \quad D_{\tilde{y}} = \text{diag}(\tilde{y}_1, \tilde{y}_2, \dots, \tilde{y}_{T_1}), \quad D_y = (y_1, y_2, \dots, y_{T_1}), \quad (66)$$

for an arbitrary nontrivial vector  $a$ .

It is clear that by substitution we find

$$\tilde{\gamma} = \gamma + (\tilde{X}'_{\star} X_{\star})^{-1} \tilde{X}'_{\star} \varepsilon. \quad (67)$$

We easily establish that

$$\tilde{X}'_{\star} X_{\star} = \begin{bmatrix} X'_1 D_{\tilde{y}} D_y X_1 & X'_1 \tilde{y} \\ y' X_1 & e'e \end{bmatrix}.$$

Clearly

$$\begin{aligned} \lim_{T \rightarrow \infty} \frac{e'e}{T_1} &= 1, & \lim_{T \rightarrow \infty} \frac{1}{T_1} X'_1 \tilde{y} &= \left( \lim_{T \rightarrow \infty} \frac{X'_1 X_1}{T} \right) a, \\ \text{plim}_{T \rightarrow \infty} \frac{1}{T} X'_1 y &= \left( \lim_{T \rightarrow \infty} \frac{X'_1 X_1}{T_1} \right) \beta + \text{plim}_{T \rightarrow \infty} \frac{X'_1 u_{\cdot 1}}{T_1}. \end{aligned}$$

Now

$$\frac{1}{T_1} X'_1 u_{\cdot 1} = \frac{1}{T_1} \sum_{t=1}^{T_1} x'_t \cdot u_t,$$

and

$$\{x'_t \cdot u_t; t=1, 2, \dots\},$$

is a sequence of independent random variables with mean

$$E(x'_t \cdot u_t) = \sigma x'_t \cdot \psi_t, \quad (68)$$

and covariance matrix

$$\text{Cov}(x'_t \cdot u_t) = \sigma^2 (1 - \nu_t \psi_t - \psi_t) x'_t \cdot x_t = \omega_t x'_t \cdot x_t, \quad (69)$$

where

$$\omega_t = \sigma^2(1 - \nu_t \psi_t - \psi_t^2),$$

is uniformly bounded by assumption (A.2.2) and (A.2.4). Hence, by (A.2.2)

$$\lim_{T_1 \rightarrow \infty} \frac{1}{T_1} \sum_{t=1}^{T_1} \omega_t x'_t x_t,$$

converges to a matrix with finite elements. Further and similar calculations will show that

$$\frac{\tilde{X}'_* X_*}{T},$$

converges a.c. to a nonsingular matrix. Thus, we are reduced to examining the limiting behavior of

$$\frac{1}{\sqrt{T_1}} \tilde{X}'_* \varepsilon = \frac{1}{\sqrt{T_1}} \sum_{t=1}^{T_1} \begin{pmatrix} x_t' \alpha x'_t \\ 1 \end{pmatrix} \varepsilon_t. \quad (70)$$

But this is a sequence of independent nonidentically distributed random variables with mean zero and uniformly bounded (in  $x_t$  and  $\beta$ ) moments to any finite order. Now for any arbitrary  $(n+2 \times 1)$  vector  $\alpha^*$  consider

$$\frac{1}{\sqrt{T_1}} \alpha^{*'} \tilde{X}'_* \varepsilon = \frac{1}{\sqrt{T_1}} \sum_{t=1}^{T_1} \alpha_t \varepsilon_t, \quad (71)$$

where

$$\alpha_t = (x_t' \alpha)(x_t' a), \quad \alpha^* = (\alpha', \alpha_{n+2}),$$

and note that

$$\lim_{T_1 \rightarrow \infty} \frac{S_{T_1}^{*2}}{T_1} = S,$$

is well defined where

$$S_{T_1}^{*2} = \sum_{t=1}^{T_1} \alpha_t^2 \text{Var}(\varepsilon_t). \quad (72)$$

Define, further

$$S_{T_1}^2 = \frac{S_{T_1}^{*2}}{T_1},$$

and note that

$$S_{T_1}^* = T_1^{1/2} S_{T_1}.$$

But then it is evident that Liapounov's condition is satisfied, i.e. with  $K$  a uniform bound on  $E|\alpha_t \varepsilon_t|^{2+\delta}$

$$\lim_{T_1 \rightarrow \infty} \frac{\sum_{t=1}^{T_1} E|\alpha_t \varepsilon_t|^{2+\delta}}{S_{T_1}^{*2+\delta}} \leq K \lim_{T_1 \rightarrow \infty} \frac{T_1}{T_1^{1+\delta/2} S_{T_1}^{2+\delta}} = \lim_{T_1 \rightarrow \infty} \frac{K}{T_1^{\delta/2} S^{2+\delta}} = 0.$$

By a theorem of Varadarajan, see Dhrymes (1970), we conclude that

$$\frac{1}{\sqrt{T_1}} \tilde{X}'_* \varepsilon \sim N(0, H),$$

where

$$H = \lim_{T_1 \rightarrow \infty} \frac{1}{T_1} \begin{bmatrix} \sum_{t=1}^{T_1} (x_t \cdot a)^2 x'_t \cdot x_t \cdot \text{Var}(\varepsilon_t) & \sum_{t=1}^{T_1} (x_t \cdot a) x'_t \cdot \text{Var}(\varepsilon_t) \\ \sum_{t=1}^{T_1} (x_t \cdot a) x_t \cdot \text{Var}(\varepsilon_t) & \sum_{t=1}^{T_1} \text{Var}(\varepsilon_t) \end{bmatrix}. \quad (73)$$

Consequently we have shown that

$$\sqrt{T_1} (\tilde{\gamma} - \gamma) \sim N(0, Q^{-1} H Q^{-1}),$$

where

$$Q = \lim_{\text{a.c.}} \frac{(\tilde{X}'_* X_*)}{T_1}. \quad (74)$$

Moreover since

$$\sqrt{T_1} (\tilde{\gamma} - \gamma) \sim \zeta,$$

where  $\zeta$  is an a.c. finite random vector it follows that

$$\tilde{\gamma} - \gamma_0 \sim \frac{\zeta}{\sqrt{T_1}},$$

which shows that  $\tilde{\gamma}$  converges a.c. to  $\gamma_0$ .

We may summarize the development above in

*Lemma 1*

Consider the model in (43) subject to assumptions (A.2.1.) through (A.2.4.); further consider the I.V. estimator of the parameter vector  $\gamma$  in

$$w_t = (x_t, y_t, 1)\gamma + \varepsilon_t, \quad w_t = y_t^2,$$

given by

$$\tilde{\gamma} = (\tilde{X}'_* X_*)^{-1} \tilde{X}'_* w,$$

where  $\tilde{X}_*$ ,  $X_*$  and  $w$  are as defined in (65) and (66). Then

- i.  $\tilde{\gamma}$  converges to  $\gamma_0$  almost certainly,
- ii.  $\sqrt{T_1}(\tilde{\gamma} - \gamma_0) \sim N(0, Q^{-1}HQ'^{-1})$ ,

where  $Q$  and  $H$  are as defined in (74) and (73) respectively.

*2.5. Limiting properties and distribution of the ML estimator*

Returning now to eqs. (53) or (54) and (55) we observe that since the initial estimator, say  $\tilde{\gamma}$ , is strongly consistent, at each step of the iterative procedure we get a (strongly) consistent estimator. Hence, at convergence, the estimator so determined, say  $\hat{\gamma}$ , is guaranteed to be (strongly) consistent.

The perceptive reader may ask: Why did we not use the apparatus of Section 1.d. instead of going through the intermediate step of obtaining the initial consistent estimator? The answer is, essentially, that Theorem 1 (of Section 1.d.) does not hold in the current context. To see that, recall the (log) LF of our problem and write it as

$$L_T(\gamma) = \frac{1}{T} \sum_{t=1}^T \left\{ (1 - c_t) \ln \Phi(-v_t) - c_t \cdot \left[ \frac{1}{2} \ln(2\pi) + \frac{1}{2} \ln \sigma^2 + \frac{1}{2\sigma^2} (y_t - x_t \cdot \beta)^2 \right] \right\}. \quad (75)$$

Since  $L_T$  is at least twice differentiable it is concave if and only if its Hessian is negative (semi)definite over the space of admissible  $\gamma$ -parameters. After some manipulation we can show that

$$\frac{\partial^2 L_T}{\partial \sigma^2 \partial \sigma^2} = -\frac{1}{4\sigma^4} \frac{1}{T} \left\{ \sum_{i=1}^T (1-c_i) \frac{v_i \phi(v_i)}{\Phi(-v_i)} \left( 3 - v_i^2 + \frac{v_i \phi(v_i)}{\Phi(-v_i)} \right) + c_i \left[ 4 \frac{(y_i - x_i \cdot \beta)^2}{\sigma^2} - 2 \right] \right\}.$$

When  $\beta = 0$  the entire first term in brackets is null so that the derivative reduces to

$$-\frac{1}{\sigma^4} \frac{1}{T} \sum_{i=1}^T c_i \left( \frac{y_i^2}{\sigma^2} - \frac{1}{2} \right),$$

which could well be positive for some realizations. Hence, we cannot unambiguously assert that over some (large) compact subset of  $R_{n+2}$ , the Hessian of the (log) LF is negative semidefinite. Consequently, we have no assurance that, if we attempted to solve

$$\frac{\partial L_T}{\partial \gamma}(\gamma) = 0, \tag{76}$$

beginning with an arbitrary initial point, say  $\tilde{\gamma}$ , upon convergence we should arrive at the consistent root of (93). On the other hand, from the general theory of ML estimation we know that if the true parameter point is in the interior of the  $\gamma$ -admissible space then (76) has at most one consistent root. Of course, it may have many roots if the function  $L_T$  is nonconcave and herein lies the problem. In the previous Section, however, because of Theorem 1 we knew that the (log) likelihood function was concave and hence starting from an arbitrary point we could locate, upon convergence, the global maximizer and hence the ML estimator.

Many of the other results of Section 1.d., however, are available to us in virtue of

### Lemma 2

The (log) LF of the problem of this section as exhibited in (75) converges a.c. uniformly in  $\gamma$ . In particular

$$L_T(\gamma) \xrightarrow{\text{a.c.}} \lim_{T \rightarrow \infty} E[L_T(\gamma)],$$

uniformly in  $\gamma$ .

*Proof*

Consider the log LF of (75) and in particular its  $t$ th term

$$\xi_t = (1 - c_t) \ln \Phi(-\nu_t) - c_t \left[ \frac{1}{2} \ln(2\pi) + \frac{1}{2} \ln \sigma^2 + \frac{1}{2\sigma^2} (y_t - x_t \cdot \beta)^2 \right],$$

(77)

For any  $x$ -realization

$$\{\xi_t: t=1, 2, \dots\},$$

is a sequence of independent random variables with uniformly bounded moments in virtue of assumption (A.2.1) through (A.2.3). Thus, there exists a constant, say  $k$ , such that

$$\text{Var}(\xi_t) < k, \quad \text{for all } t.$$

Consequently, by Kolmogorov's criterion, for all admissible  $\gamma$ ,

$$\{L_T(\gamma) - E[L_T(\gamma)]\} \xrightarrow{\text{a.c.}} 0. \quad \text{Q.E.D.}$$

*Remark 3*

The device of beginning the iterative process for solving (76) with a consistent estimator ensures that for sufficiently large  $T$  we will be locating the estimator, say  $\hat{\gamma}_T$ , satisfying

$$L_T(\hat{\gamma}_T) = \sup_{\gamma} L_T(\gamma).$$

Lemma 2, can be shown to imply that

$$L_T(\hat{\gamma}_T) \xrightarrow{\text{a.c.}} \bar{L}(\bar{\gamma}, \gamma^0), \quad \bar{L}(\bar{\gamma}, \gamma^0) = \sup_{\gamma} \bar{L}(\gamma, \gamma^0).$$

Moreover, we can also show that

$$\bar{\gamma} = \gamma^0.$$

On the other hand, it is not possible to show routinely that  $\hat{\gamma}_T \xrightarrow{\text{a.c.}} \gamma^0$ . Essentially, the problem is the term corresponding to  $\sigma^2$  which contains expressions like

$$c_t \frac{(y_t - x_t \cdot \beta)^2}{\sigma^2},$$

which cannot be (absolutely) bounded. This does not prevent us from showing convergence a.c. of  $\hat{\gamma}_T$  to  $\gamma^0$ . By the iterative process we have shown that  $\hat{\gamma}_T$  converges to  $\gamma^0$  at least in probability. Convergence a.c. is shown easily once we obtain the limiting distribution of  $\hat{\gamma}_T$  – a task to which we now turn.

Thus, as before, consider the expansion

$$\frac{\partial L_T}{\partial \gamma}(\hat{\gamma}_T) = \frac{\partial L_T}{\partial \gamma}(\gamma^0) + \frac{\partial^2 L_T}{\partial \gamma \partial \gamma}(\gamma^*)(\hat{\gamma}_T - \gamma^0), \tag{78}$$

where  $\gamma^0$  is the true parameter point and

$$|\hat{\gamma}_T - \gamma^0| \leq |\gamma^* - \gamma^0|.$$

We already have an explicit expression in eq. (53) for the derivative  $\partial L_T / \partial \gamma$ . So let us obtain the Hessian of the LF. We find

$$\begin{aligned} \frac{\partial^2 L_T}{\partial \beta \partial \beta}(\gamma) &= -\frac{1}{\sigma^2} \frac{1}{T} \sum_{i=1}^T \left\{ (1 - c_i) \psi_i^*(\psi_i^* - \nu_i) + c_i \right\} x_i' x_i, \\ \frac{\partial^2 L_T}{\partial \beta \partial \sigma^2} &= -\frac{1}{2\sigma^3} \frac{1}{T} \sum_{i=1}^T \left\{ 2c_i \left( \frac{y_i - x_i \beta}{\sigma} \right) - (1 - c_i) \psi_i^*(1 + \nu_i \psi_i^* - \nu_i^2) \right\} x_i, \\ \frac{\partial^2 L_T}{\partial \sigma^2 \partial \sigma^2} &= -\frac{1}{4\sigma^4} \frac{1}{T} \sum_{i=1}^T \left\{ c_i^2 \left( \frac{y_i - x_i \beta}{\sigma} \right)^2 + (1 - c_i) \nu_i \psi_i^*(1 + \nu_i \psi_i^* - \nu_i^2) \right\} \\ &\quad + \frac{1}{2\sigma^4} \frac{1}{T} \sum_{i=1}^T \left\{ c_i \left[ 1 - \left( \frac{y_i - x_i \beta}{\sigma} \right)^2 \right] - (1 - c_i) \nu_i \psi_i^* \right\}. \end{aligned} \tag{79}$$

We may now define

$$\xi_{1i} = (1 - c_i) \frac{\phi(\nu_i^0)}{\Phi(-\nu_i^0)} - c_i \left( \frac{y_i - x_i \beta^0}{\sigma_0} \right), \tag{80}$$

$$\xi_{2i} = c_i \left[ 1 - \left( \frac{y_i - x_i \beta^0}{\sigma_0} \right)^2 \right] - (1 - c_i) \frac{\nu_i^0 \phi(\nu_i^0)}{\Phi(-\nu_i^0)},$$

and

$$\begin{aligned} \xi_{11i} &= (1 - c_i) \psi_i^{*0}(\psi_i^{*0} - \nu_i^0) + c_i, \\ \xi_{12i} = \xi_{21i} &= (1 - c_i) \psi_i^{*0}(1 + \nu_i^0 - \nu_i^0 \psi_i^{*0}), \\ \xi_{22i} &= c_i^2 \left( \frac{y_i - x_i \beta^0}{\sigma_0} \right)^2 + (1 - c_i) \nu_i^0 \psi_i^{*0}(1 + \nu_i^0 \psi_i^{*0} - \nu_i^{02}), \end{aligned} \tag{81}$$



where, evidently,

$$\psi_i^{*0} = \frac{\phi(\nu_i^0)}{\Phi(-\nu_i^0)}, \quad \nu_i^0 = \frac{x_i \cdot \beta^0}{\sigma_0}, \quad \psi_i^0 = \frac{\phi(\nu_i^0)}{\Phi(\nu_i^0)}.$$

With the help of the notation in (80) and (81) we find

$$\frac{\partial L_T}{\partial \gamma'}(\gamma^0) = -\frac{1}{\sigma_0} \frac{1}{T} \sum_{t=1}^T \begin{bmatrix} x'_{1t} & 0 \\ 0 & \frac{1}{2\sigma_0} \end{bmatrix} \begin{bmatrix} \xi_{1t} \\ \xi_{2t} \end{bmatrix}, \quad (82)$$

and

$$\frac{\partial^2 L_T}{\partial \gamma \partial \gamma}(\gamma^0) = -\frac{1}{\sigma_0^2} \frac{1}{T} \sum_{t=1}^T \begin{bmatrix} \xi_{11t} x'_{1t} x_{1t} & \frac{1}{2\sigma_0} \xi_{12t} x'_{1t} \\ \frac{1}{2\sigma_0} \xi_{21t} x_{1t} & \frac{1}{4\sigma_0^2} \xi_{22t} \end{bmatrix} + \Omega_{*T}, \quad (83)$$

where  $\Omega_{*T}$  is a matrix all of whose elements are zero except the last diagonal element, which is

$$\frac{1}{T} \sum_{t=1}^T \frac{1}{2\sigma_0^4} \xi_{2t \dots}$$

Thus, for every  $T$  we have

$$E(\Omega_{*T}) = 0. \quad (84)$$

Consequently, we are now ready to prove

### Theorem 3

Consider the model of eq. (43) subject to assumption (A.2.1.) through (A.2.4.); moreover, consider the ML estimator,  $\hat{\gamma}_T$ , obtained by iteration from an initial consistent estimator as a solution of (76). Then

$$\sqrt{T}(\hat{\gamma}_T - \gamma^0) \sim N(0, \sigma_0^2 C^{-1}),$$

where

$$C = \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \begin{bmatrix} \omega_{11t} x'_{1t} x_{1t} & \frac{1}{2\sigma_0} \omega_{12t} x'_{1t} \\ \frac{1}{2\sigma_0} \omega_{21t} x_{1t} & \frac{1}{4\sigma_0^2} \omega_{22t} \end{bmatrix},$$

and

$$\omega_{ijt} = E(\xi_{ijt}) \quad i, j = 1, 2.$$

*Proof*

From the expansion in (78) and the condition under which the ML estimator is obtained we find

$$\sqrt{T}(\hat{\gamma}_T - \gamma^0) = - \left[ \frac{\partial^2 L_T}{\partial \gamma \partial \gamma}(\gamma^*) \right]^{-1} \frac{1}{\sqrt{T}} \frac{\partial L}{\partial \gamma}(\gamma^0).$$

But

$$\frac{1}{\sqrt{T}} \frac{\partial L}{\partial \gamma}(\gamma^0) = - \frac{1}{\sigma_0} \frac{1}{\sqrt{T}} \sum_{t=1}^T \begin{bmatrix} x'_t & 0 \\ 0 & \frac{1}{2\sigma_0} \end{bmatrix} \begin{bmatrix} \xi_{1t} \\ \xi_{2t} \end{bmatrix}. \quad (85)$$

The right member of (85) involves the sum of a sequence of independent random variables with mean zero. Moreover, it is easily verified that such variables have uniformly bounded moments to order at least four. Hence, a Liapounov condition holds. Since the covariance matrix of each term is

$$\frac{1}{\sigma_0^2} \begin{bmatrix} x'_t \cdot x_t \cdot \omega_{11t} & \frac{1}{2\sigma_0} x'_t \cdot \omega_{12t} \\ \frac{1}{2\sigma_0} x_t \cdot \omega_{21t} & \frac{1}{4\sigma_0^2} \omega_{22t} \end{bmatrix},$$

with

$$\begin{aligned} \omega_{11t} &= E(\xi_{1t}^2) = \Phi(v_t^0) + \psi(v_t^0)[\psi_t^{*0} - v_t^0], \\ \omega_{12t} &= \omega_{21t} = E(\xi_{1t}\xi_{2t}) = \phi(v_t^0)[1 - v_t^0\psi_t^{*0} + v_t^{02}], \\ \omega_{22t} &= E(\xi_{2t}^2) = 2\Phi(v_t^0) - v_t^0\phi(v_t^0)[1 - v_t^0\psi_t^{*0} + v_t^{02}]. \end{aligned} \quad (86)$$

Thus we see that

$$\frac{1}{\sqrt{T}} \frac{\partial L}{\partial \gamma}(\gamma^0) \sim N\left(0, \frac{1}{\sigma_0^2} C\right).$$

From (79) we also verify that

$$\frac{\partial^2 L_T}{\partial \gamma \partial \gamma}(\gamma^*) - \frac{\partial^2 L_T}{\partial \gamma \partial \gamma}(\gamma^0),$$

converges in probability to the null matrix, element by element. But the elements of

$$\frac{\partial^2 L_T}{\partial \gamma \partial \gamma}(\gamma^0),$$

are seen to be sums of independent random variables with finite means and bounded variances; hence, they obey a Kolmogorov criterion and thus

$$\frac{\partial^2 L_T}{\partial \gamma \partial \gamma}(\gamma^*) \xrightarrow{\text{a.c.}} \lim_{T \rightarrow \infty} E \left[ \frac{\partial^2 L_T}{\partial \gamma \partial \gamma}(\gamma^0) \right].$$

We easily verify that

$$\begin{aligned} E(\xi_{11t}) &= \omega_{11t}, \quad E(\xi_{12t}) = E(\xi_{21t}) = \phi(v_t^0) [1 - v_t^0 \psi_t^{*0} + v_t^{02}] \\ &= \omega_{12t} = \omega_{21t}, \end{aligned}$$

$$E(\xi_{22t}) = \omega_{22t}.$$

Hence

$$\begin{aligned} \text{plim}_{T \rightarrow \infty} \frac{\partial^2 L_T}{\partial \gamma \partial \gamma}(\gamma^*) &= \lim_{T \rightarrow \infty} -\frac{1}{\sigma_0^2} \frac{1}{T} \sum_{t=1}^T \begin{bmatrix} \omega_{11t} x_t' \cdot x_t & \frac{1}{2\sigma_0} \omega_{12t} x_t' \\ \frac{1}{2\sigma_0} \omega_{21t} x_t & \frac{1}{4\sigma_0^2} \omega_{22t} \end{bmatrix} \\ &= -\frac{1}{\sigma_0^2} C, \end{aligned}$$

and, moreover,

$$\sqrt{T}(\hat{\gamma} - \gamma^0) \sim N(0, \sigma_0^2 C^{-1}) \quad (\text{Q.E.D.})$$

*Corollary 2*

The estimator  $\hat{\gamma}_T$  converges a.c. to  $\gamma_0$ .

*Proof*

From Theorem 3

$$\sqrt{T}(\hat{\gamma}_T - \gamma^0) \sim \zeta,$$

where  $\zeta$  is an a.c. finite random variable; hence,

$$\hat{\gamma}_T - \gamma^0 \sim \frac{\zeta}{\sqrt{T}},$$

and thus

$$\hat{\gamma}_T \xrightarrow{\text{a.c.}} \gamma^0.$$

*Corollary*

The marginal (limiting) distribution of  $\hat{\beta}_T$  is given by

$$\sqrt{T}(\hat{\beta}_T - \beta) \sim N(0, \sigma_0^2 P^{-1}),$$

where

$$P = \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \left( \omega_{11t} - \frac{\omega_{21t}^2}{\omega_{22t}} \right) x'_t x_t. \quad (87)$$

*Proof*

Evident from the definition of  $C$  in Theorem 3.

*Remark 4*

The unknown parameters of the limiting distribution of  $\hat{\gamma}_T$  can be estimated by the standard procedure as

$$-\frac{\partial^2 L_T(\hat{\gamma}_T)}{\partial \gamma \partial \gamma}.$$

However, it would be much preferable to estimate  $C$  as

$$\hat{C} = \frac{1}{\hat{\sigma}^2} \frac{1}{T} \sum_{t=1}^T \begin{bmatrix} \hat{\omega}_{11t} x'_t \cdot x_t & \frac{1}{2\hat{\sigma}} \hat{\omega}_{12t} x'_t \\ \frac{1}{2\hat{\sigma}} \hat{\omega}_{21t} x_t & \frac{1}{4\hat{\sigma}^2} \hat{\omega}_{22t} \end{bmatrix},$$

with  $\hat{\omega}_{ijt}$  given as in (86) evaluated at  $\hat{y}_t$ .

## 2.6. Goodness of fit

In the context of the truncated dependent variable model the question arises as to what we would want to mean by a "goodness of fit" statistic.

As analyzed in the Section on discrete choice models the usual  $R^2$ , in the context of the GLM, serves a multiplicity of purposes; when we complicate the process in which we operate it is not always possible to define a single statistic that would be meaningful in all contexts.

Since the model is

$$\begin{aligned} y_t &= x_t \cdot \beta + u_t && \text{if } x_t \cdot \beta + u_t > 0, \\ &= 0 && \text{if } u_t \leq -x_t \cdot \beta, \end{aligned}$$

the fitted model may "describe well" the first statement but poorly the second or vice versa. A useful statistic for the former would be the square of the simple correlation coefficient between predicted and actual  $y_t$ . Thus, e.g. suppose we follow our earlier convention about the numbering of observations; then for the positive component of the sample we put

$$\hat{y}_t = x_t \cdot \hat{\beta} + \hat{\sigma} \hat{\psi}_t, \quad t = 1, 2, \dots, T_1. \quad (88)$$

An intuitively appealing statistic is

$$r^2 = \frac{\left[ \sum_{t=1}^{T_1} (\hat{y}_t - \bar{\hat{y}})(y_t - \bar{y}) \right]^2}{\left[ \sum_{t=1}^{T_1} (\hat{y}_t - \bar{\hat{y}})^2 \right] \left[ \sum_{t=1}^{T_1} (y_t - \bar{y})^2 \right]}, \quad (89)$$

where

$$\bar{y} = \frac{1}{T_1} \sum_{t=1}^{T_1} y_t, \quad \bar{\hat{y}} = \frac{1}{T_1} \sum_{t=1}^{T_1} \hat{y}_t. \quad (90)$$

As to how well it discriminates between the zero and positive (dependent variable) observations we may compute  $\Phi(-\nu_t)$  for all  $t$ ; in the perfect discrimination case

$$\Phi(-\hat{\nu}_{t_2}) > \Phi(-\hat{\nu}_{t_1}), \quad t_1 = 1, 2, \dots, T_1, \quad t_2 = T_1 + 1, \dots, T. \quad (91)$$

The relative frequency of the reversal of ranks would be another interesting statistic, as would the average probability difference, i.e.

$$\frac{1}{T_2} \sum_{t_2 = T_1 + 1}^T \Phi(-\hat{\nu}_{t_2}) - \frac{1}{T_1} \sum_{t_1 = 1}^{T_1} \Phi(-\hat{\nu}_{t_1}) = d. \quad (92)$$

We have a “right” to expect as a minimum that

$$d > 0. \quad (93)$$

### 3. Sample selectivity

#### 3.1. Generalities

This is another important class of problems that relate specifically to the issue of how observations on a given economic phenomenon are generated. More particularly, we hypothesize that whether a certain variable, say  $y_{i1}^*$ , is observed or not depends on another variable, say  $y_{i2}^*$ . Thus, the observability of  $y_{i1}^*$  depends on the probability structure of the stochastic process that generates  $y_{i2}^*$ , as well as on that of the stochastic process that governs the behavior of  $y_{i1}^*$ . The variable  $y_{i2}^*$  may be inherently unobservable although we assert that we know the variables that enter its “systematic part.”

To be precise, consider the model

$$y_{i1}^* = x_{i1}^* \cdot \beta_{.1}^* + u_{i1}^*, \quad t = 1, 2, \dots, T, \quad (94)$$

$$y_{i2}^* = x_{i2}^* \cdot \beta_{.2}^* + u_{i2}^*,$$

where  $x_{i1}^*$ ,  $x_{i2}^*$  are  $r_1$ ,  $r_2$ -element row vectors of observable “exogenous” variables

which may have elements in common. The vectors

$$\mathbf{u}_t^* = (u_{i1}^*, u_{i2}^*), \quad t = 1, 2, \dots,$$

form a sequence of i.i.d. random variables with distribution

$$\mathbf{u}_t^* \sim N(0, \Sigma^*), \quad \Sigma^* > 0.$$

The variable  $y_{i2}^*$  is inherently unobservable, while  $y_{i1}^*$  is observable if and only if

$$y_{i1}^* \geq y_{i2}^*.$$

An example of such a model is due to Heckman (1979) where  $y_{i1}^*$  is an observed wage for the  $t$ th worker and  $y_{i2}^*$  is his reservation wage. Evidently,  $y_{i1}^*$  is the “market valuation” of his skills and other pertinent attributes, represented by the vector  $x_{i1}^*$ , while  $y_{i2}^*$  represents, through the vector  $x_{i2}^*$ , those personal and other relevant attributes that lead him to seek employment at a certain wage or higher.

Alternatively, in the market for housing  $y_{i1}^*$  would represent the “market valuation” of a given structure’s worth while  $y_{i2}^*$  would represent the current owner’s evaluation.

Evidently a worker accepts a wage for employment or a structure changes hands if and only if

$$y_{i1}^* \geq y_{i2}^*.$$

If the covariance matrix,  $\Sigma^*$ , is diagonal, then there is no correlation between  $y_{i1}^*$  and  $y_{i2}^*$  and hence in view of the assumption regarding the error process

$$\{\mathbf{u}_t^*: t = 1, 2, \dots\},$$

we could treat the sample

$$\{(y_{i1}^*, x_{i1}^*): t = 1, 2, \dots, T\},$$

as one of i.i.d. observations; consequently, we can estimate consistently the parameter vector  $\beta_1^*$  by OLS given the sample, irrespectively of the second relation in (94).

On the other hand, if the covariance matrix,  $\Sigma^*$ , is not diagonal, then the situation is far more complicated, since now there does exist a stochastic link between  $y_{i1}^*$  and  $y_{i2}^*$ . The question then becomes: If we apply OLS to the first equation in (94) do we suffer more than just the usual loss in efficiency?

### 3.2. Inconsistency of least squares procedures

In the current context, it would be convenient to state the problem in canonical form before we attempt further analysis. Thus, define

$$\begin{aligned} y_{i1} &= y_{i1}^*, & y_{i2} &= y_{i1}^* - y_{i2}^*, & x_{i1} &= x_{i1}^*, & x_{i2} &= (x_{i1}^*, x_{i2}^*), \\ \beta_{\cdot 1} &= \beta_{\cdot 1}^*, & \beta_{\cdot 2} &= \begin{pmatrix} \beta_{\cdot 1}^* \\ -\beta_{\cdot 2}^* \end{pmatrix}, & u_{i1} &= u_{i1}^*, & u_{i2} &= u_{i1}^* - u_{i2}^*, \end{aligned} \quad (95)$$

with the understanding that if  $x_{i1}^*$  and  $x_{i2}^*$  have elements in common, say,

$$x_{i1}^* = (z_{i1}, z_{i1}^*), \quad x_{i2}^* = (z_{i1}, z_{i2}^*),$$

then

$$x_{i2} = (z_{i1}, z_{i1}^*, z_{i2}^*), \quad \beta_{\cdot 2} = \begin{pmatrix} \beta_{\cdot 11}^* - \beta_{\cdot 12}^* \\ \beta_{\cdot 21}^* \\ -\beta_{\cdot 22}^* \end{pmatrix}, \quad (96)$$

where  $\beta_{\cdot 11}^*$ ,  $\beta_{\cdot 12}^*$  are the coefficients of  $z_{i1}$  in  $x_{i1}^*$  and  $x_{i2}^*$  respectively,  $\beta_{\cdot 21}^*$  is the coefficient of  $z_{i1}^*$  and  $\beta_{\cdot 22}^*$  is the coefficient of  $z_{i2}^*$ .

Hence, the model in (94) can be stated in the canonical form

$$\begin{cases} y_{i1} = x_{i1} \cdot \beta_{\cdot 1} + u_{i1}, \\ y_{i2} = x_{i2} \cdot \beta_{\cdot 2} + u_{i2}, \end{cases} \quad (97)$$

such that  $x_{i2}$  contains at least as many elements as  $x_{i1}$ ,

$$\{u'_t = (u_{t1}, u_{t2})' : t = 1, 2, \dots\},$$

is a sequence of i.i.d. random variables with distribution

$$u'_t \sim N(0, \Sigma), \quad \Sigma > 0,$$

and subject to the condition that  $y_{i1}$  is observable (observed) if and only if  $y_{i2} \geq 0$ .

If we applied OLS methods to the first equation in (97) do we obtain, at least, consistent estimators for its parameters? The answer hinges on whether that question obeys the standard assumptions of the GLM.

Clearly, and solely in terms of the system in (97),

$$\{u_{t1} : t = 1, 2, \dots\}, \quad (98)$$

is a sequence of i.i.d. random variables and if in (94) we are prepared to assert



that the standard conditions of the typical GLM hold, nothing in the subsequent discussion suggests a correlation between  $x_{t1}$  and  $u_{t1}$ ; hence, if any problem should arise it ought to be related to the probability structure of the sequence in (98) insofar as it is associated with observable  $y_{t1}$  – a problem to which we now turn. We note that the conditions hypothesized by the model imply that (potential) realizations of the process in (98) are conditioned on<sup>4</sup>

$$u_{t2} \geq -x_{t2} \cdot \beta_{\cdot 2}. \quad (99)$$

Or, perhaps more precisely, we should state that (implicit) realizations of the process in (98) associated with *observable realizations*

$$\{y_{t1}: t=1, 2, \dots\},$$

are conditional on (99). Therefore, in dealing with the error terms of (potential) samples the marginal distribution properties of (98) are not relevant; what *are relevant* are its conditional properties – as conditioned by (99).

We have

### Lemma 3

The distribution of realizations of the process in (98) as conditioned by (99) has the following properties:

- i. The elements  $\{u_{t1}, u_{t2}\}$  are mutually independent for  $t \neq t'$ .
- ii. The density of  $u_{t1}$ , given that the corresponding  $y_{t1}$  is observable (observed) is

$$f(u_{t1} | u_{t2} > -x_{t2} \cdot \beta_{\cdot 2}) = \frac{\Phi(\pi_t)}{\Phi(v_{t2})} \frac{1}{\sqrt{2\pi\sigma_{11}}} \exp - \frac{1}{2\sigma_{11}} u_{t1}^2, \quad (100)$$

where

$$\begin{aligned} v_{t2} &= \frac{x_{t2} \cdot \beta_{\cdot 2}}{\sigma_{22}^{1/2}}, & \pi_t &= \frac{1}{\alpha^{1/2}} \left( v_{t2} + \frac{\rho_{12}}{\sigma_{11}^{1/2}} u_{t1} \right), \\ \rho_{12}^2 &= \frac{\sigma_{12}^2}{\sigma_{11}\sigma_{22}} & \alpha &= 1 - \rho_{12}^2, \end{aligned} \quad (101)$$

and  $\Phi(\cdot)$  is the c.d.f. of a  $N(0, 1)$ .

<sup>4</sup>Note that in terms of the original variables (99) reads

$$u_{t1}^* \geq u_{t2}^* + x_{t2}^* \cdot \beta_{\cdot 2}^* - x_{t1}^* \cdot \beta_{\cdot 1}^*.$$

We shall not use this fact in subsequent discussion, however.

*Proof*

i. is quite evidently valid since by the standard assumptions of the GLM we assert that  $(x_{i1}^*, x_{i2}^*)$  and  $u_i^* = (u_{i1}^*, u_{i2}^*)$  are mutually independent and that

$$\{u_i^*: i = 1, 2, \dots\},$$

is a sequence of i.i.d. random variables.

As for part ii. we begin by noting that since the conditional density of  $u_{i1}$  given  $u_{i2}$  is given by

$$u_{i1}|u_{i2} \sim N\left(\frac{\sigma_{12}}{\sigma_{22}}u_{i2}, \sigma_{11}\alpha\right),$$

and since the restriction in (99) restricts us to the space

$$u_{i2} \geq -x_{i2} \cdot \beta_{\cdot 2},$$

the required density can be found as

$$f(u_{i1}|u_{i2} \geq -x_{i2} \cdot \beta_{\cdot 2}) = \frac{1}{\Phi(v_{i2})} \frac{1}{\sqrt{2\pi\alpha\sigma_{11}}} \frac{1}{\sqrt{2\pi\sigma_{22}}} \\ \cdot \int_{-x_{i2} \cdot \beta_{\cdot 2}}^{\infty} \exp - \frac{1}{2\sigma_{11}} \left(u_{i1} - \frac{\sigma_{12}}{\sigma_{22}}\xi\right)^2 \exp - \frac{1}{2\sigma_{22}}\xi^2 d\xi.$$

Completing the square (in  $\xi$ ) and making the change in variable

$$\zeta = \left(\xi - \frac{\sigma_{12}}{\sigma_{11}}u_{i1}\right)/(\sigma_{22}\alpha)^{1/2},$$

we find

$$f(u_{i1}|u_{i2} \geq -x_{i2} \cdot \beta_{\cdot 2}) = \frac{\Phi(\pi_i)}{\Phi(v_{i2})} \frac{1}{\sqrt{2\pi\sigma_{11}}} \exp - \frac{1}{2\sigma_{11}}u_{i1}^2.$$

To verify that this is, indeed, a density function we note that it is everywhere nonnegative and

$$\int_{-\infty}^{\infty} f(\xi_1|u_{i2} \geq -x_{i2} \cdot \beta_{\cdot 2}) d\xi_1 \\ = \frac{1}{\Phi(v_{i2})} \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\sigma_{11}}} \left[ \int_{-\infty}^{\pi_i} \frac{1}{\sqrt{2\pi}} \exp - \frac{1}{2}\xi_2^2 d\xi_2 \right] \cdot \exp - \frac{1}{2\sigma_{11}}\xi_1^2 d\xi_1.$$

## Making the transformation

$$\zeta_1 = \frac{1}{\sigma_{11}^{1/2}} \xi_1, \quad \zeta_2 = \alpha^{1/2} \xi_2 - \rho_{12} \zeta_1,$$

the integral is reduced to

$$\begin{aligned} & \frac{1}{\Phi(v_{i2})} \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\alpha}} \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{v_{i2}} \exp - \frac{1}{2\alpha} (\zeta_2 + \rho_{12}\zeta_1)^2 \exp - \frac{1}{2}\zeta_1^2 d\zeta_2 d\zeta_1 \\ &= \frac{1}{\Phi(v_{i2})} \int_{-\infty}^{v_{i2}} \frac{1}{\sqrt{2\pi}} \left[ \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\alpha}} \exp - \frac{1}{2\alpha} (\zeta_1 + \rho_{12}\zeta_2)^2 d\zeta_1 \right] \\ & \quad \cdot \exp - \frac{1}{2}\zeta_2^2 d\zeta_2 = 1. \end{aligned} \quad \text{Q.E.D.}$$

*Lemma 4*

The  $k$ th moment of realizations of the process in (98) corresponding to observable realizations  $\{v_{it} : t=1, 2, \dots\}$  is given, for  $k$  even ( $k=2, 4, 6, \dots$ ), by

$$\begin{aligned} I_{k,t} &= \sigma_{11} (k-1) I_{k-2,t} - \sigma_{11}^{k/2} \alpha^{(k-2)/2} \rho_{12}^2 v_{i2} \psi(v_{i2}) \sum_{r=0}^{(k-2)/2} \binom{k-1}{2r+1} \left( \frac{\rho_{12}^2 v_{i2}^2}{\alpha} \right)^r \\ & \quad \cdot \frac{\left[ 2 \left( \frac{k-2}{2} - r \right) \right]!}{2^{\frac{k-2}{2} - r} \left( \frac{k-2}{2} - r \right)!}, \end{aligned} \quad (102)$$

while for  $k$  odd ( $k=3, 5, 7, \dots$ ) it is given by

$$\begin{aligned} I_{k,t} &= \sigma_{11} (k-1) I_{k-2,t} + \sigma_{11}^{k/2} \alpha^{(k-1)/2} \rho_{12} \psi(v_{i2}) \sum_{r=0}^{(k-1)/2} \binom{k-1}{2r} \left( \frac{\rho_{12}^2 v_{i2}^2}{\alpha} \right)^r \\ & \quad \cdot \frac{\left[ 2 \left( \frac{k-1}{2} - r \right) \right]!}{2^{\frac{k-1}{2} - r} \left( \frac{k-1}{2} - r \right)!}, \end{aligned} \quad (103)$$

where

$$\psi(v_{i2}) = \frac{\phi(v_{i2})}{\Phi(v_{i2})}, \quad I_{0,t} = 1, \quad I_{1,t} = \sigma_{11}^{1/2} \rho_{12} \psi(v_{i2}). \quad (104)$$

*Remark 5*

It is evident, from the preceding discussion, that the moments of the error process corresponding to observable  $y_{i1}$  are uniformly bounded in  $\beta_{.1}$ ,  $\beta_{.2}$ ,  $\sigma_{11}$ ,  $\sigma_{12}$ ,  $\sigma_{22}$ ,  $x_{i1}$ , and  $x_{i2}$ , – provided the parameter space is compact and the elements of  $x_{i1}$ ,  $x_{i2}$ , are bounded.

*Remark 6*

It is also evident from the preceding that for (potential) observations from the model

$$y_{i1} = x_{i1} \cdot \beta_{.1} + u_{i1},$$

we have that

$$E(y_{i1}|x_{i1}) = x_{i1} \cdot \beta_{.1} + \sigma_{11}^{1/2} \rho_{12} \psi(v_{i2}). \quad (105)$$

We are now in a position to answer the question, raised earlier, whether OLS methods applied to the first equation in (97) will yield at least consistent estimators. In this connection we observe that the error terms of *observations* on the first equation of (97) obey

$$\begin{aligned} E(u_{i1}|u_{i2} \geq -x_{i2} \cdot \beta_{.2}) &= I_{1i} = \sigma_{11}^{1/2} \rho_{12} \psi(v_{i2}), \\ \text{Var}(u_{i1}|u_{i2} \geq -x_{i2} \cdot \beta_{.2}) &= I_{2i} - I_{1i}^2 = \sigma_{11} - \sigma_{11} \rho_{12}^2 v_{i2} \psi(v_{i2}) \\ &\quad - \sigma_{11} \rho_{12}^2 \psi^2(v_{i2}) \\ &= \sigma_{11} - \sigma_{11} \rho_{12}^2 \psi(v_{i2}) [v_{i2} + \psi(v_{i2})]. \end{aligned}$$

As is well known, the second equation shows the errors to be *heteroskedastic* – whence we conclude that OLS estimators *cannot be efficient*. The first equation above shows the errors to have a nonzero mean. As shown in Dhrymes (1978a) a nonconstant (nonzero) mean implies misspecification due to left out variables and hence *inconsistency*.

Thus, OLS estimators are inconsistent; hence, we must look to other methods for obtaining suitable estimators for  $\beta_{.1}$ ,  $\sigma_{11}$ , etc. On the other hand, if, in (105),  $\rho_{12} = 0$ , then OLS estimators would be consistent but inefficient.

### 3.3. The LF and ML estimation

We shall assume that in our sample we have entities for which  $y_{i1}$  is observed and entities for which it is not observed; if  $y_{i1}$  is not observable, then we know that

$y_{i2} < 0$ , hence that

$$u_{i2} < -x_{i2} \cdot \beta_{.2}.$$

Consequently, the probability attached to that event is

$$\Phi(-v_{i2}).$$

Evidently, the probability of observing  $y_{i1}$  is  $\Phi(v_{i2})$  and given that  $y_{i1}$  is observed the probability it will assume a value in some interval  $\Delta$  is

$$\frac{1}{\Phi(v_{i2})} \frac{1}{\sqrt{2\pi\sigma_{11}}} \int_{\Delta} \Phi(\pi_i) \exp - \frac{1}{2\sigma_{11}} \xi^2 d\xi.$$

Hence, the unconditional probability that  $y_{i1}$  will assume a value in the interval  $\Delta$  is

$$\frac{1}{\sqrt{2\pi\sigma_{11}}} \int_{\Delta} \Phi(\pi_i) \exp - \frac{1}{2\sigma_{11}} \xi^2 d\xi.$$

Define

$$\begin{aligned} c_i &= 1 && \text{if } y_{i1} \text{ is observed,} \\ &= 0 && \text{otherwise,} \end{aligned}$$

and note that the LF is given by

$$L^* = \prod_{i=1}^T [\Phi(v_{i2}) f(y_{i1} - x_{i1} \cdot \beta_{.1} | u_{i2} \geq -x_{i2} \cdot \beta_{.2})]^{c_i} [\Phi(-v_{i2})]^{1-c_i}. \quad (106)$$

Thus, e.g. if for a given sample we have no observations on  $y_{i1}$  the LF becomes

$$\prod_{i=1}^T \Phi(-v_{i2}),$$

while, if all sample observations involve observable  $y_{i1}$ 's the LF becomes

$$\prod_{i=1}^T \left\{ \frac{1}{\sqrt{2\pi\sigma_{11}}} \Phi \left[ \frac{1}{\alpha^{1/2}} \left( v_{i2} + \rho_{12} \left( \frac{y_{i1} - x_{i1} \cdot \beta_{.1}}{\sigma_{11}^{1/2}} \right) \right) \right] \right\} \exp - \frac{1}{2\sigma_{11}} (y_{i1} - x_{i1} \cdot \beta_{.1})^2.$$

Finally, if the sample contains entities for which  $y_{i1}$  is observed as well as entities

for which it is not observed, then we have the situation in (106). We shall examine the estimation problems posed by (106) in its general form.

*Remark 7*

It is evident that we can parametrize the problem in terms of  $\beta_{.1}, \beta_{.2}, \sigma_{11}, \sigma_{22}, \sigma_{12}$ ; it is further evident that  $\beta_{.2}$  and  $\sigma_{22}$  appear only in the form  $(\beta_{.2}/\sigma_{22}^{1/2})$ —hence, that  $\sigma_{22}$  cannot be, separately, identified. We shall, thus, adopt the convention

$$\sigma_{22} = 1. \quad (107)$$

A consequence of (107) is that (105) reduces to

$$E(y_{i1}|x_{i1}, u_{i2} \geq -x_{i2} \cdot \beta_{.2}) = x_{i1} \cdot \beta_{.1} + \sigma_{12} \psi(v_{i2}). \quad (108)$$

The logarithm of the LF is given by

$$\begin{aligned} L = \sum_{i=1}^T & \left\{ (1 - c_i) \ln \Phi(-v_{i2}) \right. \\ & + c_i \left[ -\frac{1}{2} \ln(2\pi) - \frac{1}{2} \ln \sigma_{11} - \frac{1}{2\sigma_{11}} (y_{i1} - x_{i1} \cdot \beta_{.1})^2 \right] \\ & \left. + \ln \Phi \left[ \frac{1}{\alpha^{1/2}} \left( v_{i2} + \rho_{12} \left( \frac{y_{i1} - x_{i1} \cdot \beta_{.1}}{\sigma_{11}^{1/2}} \right) \right) \right] \right\}. \quad (109) \end{aligned}$$

*Remark 8*

We shall proceed to maximize (109) treating  $\beta_{.1}, \beta_{.2}$  as free parameters. As pointed out in the discussion following eq. (95) the two vectors will, generally, have elements in common. While we shall ignore this aspect here, for simplicity of exposition, we can easily take account of it by considering as the vector of unknown parameters  $\gamma$  whose elements are the distinct elements of  $\beta_{.1}, \beta_{.2}$  and  $\sigma_{11}, \rho_{12}$ .

The first order conditions yield

$$\frac{\partial L}{\partial \beta_{.1}} = \frac{1}{\sigma_{11}^{1/2}} \sum_{i=1}^T c_i \left[ \frac{y_{i1} - x_{i1} \cdot \beta_{.1}}{\sigma_{11}^{1/2}} - \frac{\rho_{12}}{\alpha^{1/2}} \frac{\phi(\pi_i)}{\Phi(\pi_i)} \right] x_{i1}, \quad (110)$$

$$\frac{\partial L}{\partial \beta_{.2}} = \sum_{i=1}^T \left[ c_i \frac{\phi(\pi_i)}{\Phi(\pi_i)} \frac{1}{\alpha^{1/2}} - (1 - c_i) \frac{\phi(v_{i2})}{\Phi(-v_{i2})} \right] x_{i2}, \quad (111)$$

$$\frac{\partial L}{\partial \sigma_{11}} = \frac{1}{2\sigma_{11}} \sum_{i=1}^T c_i \left[ -1 + \left( \frac{y_{i1} - x_{i1} \cdot \beta_{.1}}{\sigma_{11}^{1/2}} \right)^2 - \frac{\phi(\pi_i)}{\Phi(\pi_i)} \frac{\rho_{12}}{\alpha^{1/2}} \left( \frac{y_{i1} - x_{i1} \cdot \beta_{.1}}{\sigma_{11}^{1/2}} \right) \right], \quad (112)$$

$$\frac{\partial L}{\partial \rho_{12}} = \frac{1}{\alpha^{3/2}} \sum_{i=1}^T c_i \frac{\phi(\pi_i)}{\Phi(\pi_i)} \left[ \rho_{12} v_{i2} + \left( \frac{y_{i1} - x_{i1} \cdot \beta_{.1}}{\sigma_{11}^{1/2}} \right) \right]. \quad (113)$$

## Putting

$$\gamma = (\beta'_{.1}, \beta'_{.2}, \sigma_{11}, \sigma_{12})', \quad (114)$$

we see that the ML estimator, say  $\hat{\gamma}$ , is defined by the condition

$$\frac{\partial L}{\partial \gamma}(\hat{\gamma}) = 0. \quad (115)$$

Evidently, this is a highly nonlinear set of relationships which can be solved only by iteration, from an initial consistent estimator, say  $\tilde{\gamma}$ .

## 3.4. An initial consistent estimator

To obtain an initial consistent estimator we look at the sample solely from the point of view of whether information is available on  $y_{i1}$ , i.e. whether  $y_{i1}$  is observed with respect to the economic entity in question. It is clear that this, at best, will identify only  $\beta_{.2}$ , since absent any information on  $y_{i1}$  we cannot possibly hope to estimate  $\beta_{.1}$ . Having estimated  $\beta_{.2}$  by this procedure we proceed to construct the variable

$$\tilde{\psi}_t = \tilde{\psi}_t(\tilde{v}_{t2}) = \frac{\phi(x_{t2} \cdot \tilde{\beta}_{.2})}{\Phi(x_{t2} \cdot \tilde{\beta}_{.2})}, \quad t = 1, 2, \dots, T. \quad (116)$$

Then, turning our attention to that part of the sample which contains observations on  $y_{i1}$ , we simply regress  $y_{i1}$  on  $(x_{i1}, \tilde{\psi}_t)$ . In this fashion we obtain estimators of

$$\delta = (\beta'_{.1}, \sigma_{12})' \quad (117)$$

as well as of  $\sigma_{11}$ .

Examining the sample from the point of view first set forth at the beginning of this section we have the log likelihood function

$$L_1 = \sum_{i=1}^T [c_i \ln \Phi(v_{i2}) + (1 - c_i) \ln \Phi(-v_{i2})], \quad (118)$$

which is to be maximized with respect to the unknown vector  $\beta_{.2}$ . In Section 1.d. we noted that  $L_1$  is strictly concave with respect to  $\beta_{.2}$ ; moreover, the matrix of

its second order derivatives is given by

$$\frac{\partial^2 L_1}{\partial \beta_{\cdot 2} \partial \beta_{\cdot 2}} = - \sum_{t=1}^T \phi(x_{t2} \cdot \beta_{\cdot 2}) \left[ c_t \frac{S_1(x_{t2} \cdot \beta_{\cdot 2})}{\Phi^2(x_{t2} \cdot \beta_{\cdot 2})} + (1 - c_t) \frac{S_2(x_{t2} \cdot \beta_{\cdot 2})}{\Phi^2(-x_{t2} \cdot \beta_{\cdot 2})} \right] \cdot x'_{t2} \cdot x_{t2} \quad (119)$$

where

$$S_1(x_{t2} \cdot \beta_{\cdot 2}) = \phi(x_{t2} \cdot \beta_{\cdot 2}) + (x_{t2} \cdot \beta_{\cdot 2}) \Phi(x_{t2} \cdot \beta_{\cdot 2}), \quad (120)$$

$$S_2(x_{t2} \cdot \beta_{\cdot 2}) = \phi(x_{t2} \cdot \beta_{\cdot 2}) - (x_{t2} \cdot \beta_{\cdot 2}) \Phi(-x_{t2} \cdot \beta_{\cdot 2}). \quad (121)$$

It is also shown in the discussion of Section 1.d. that asymptotically

$$\sqrt{T}(\hat{\beta}_{\cdot 2} - \beta_{\cdot 2}^0) \sim N\left(0, - \lim_{T \rightarrow \infty} \left\{ \frac{1}{T} E \left[ \frac{\partial^2 L}{\partial \beta_{\cdot 2} \partial \beta_{\cdot 2}}(\beta_{\cdot 2}^0) \right] \right\}^{-1} \right), \quad (122)$$

where  $\hat{\beta}_{\cdot 2}$  is the ML estimator, i.e. it solves

$$\frac{\partial L_1}{\partial \beta_{\cdot 2}}(\hat{\beta}_{\cdot 2}) = 0, \quad (123)$$

and  $\beta_{\cdot 2}^0$  is the true parameter point. It is evident from (122) that  $\hat{\beta}_{\cdot 2}$  converges a.c. to  $\beta_{\cdot 2}^0$ . Define now

$$\tilde{\psi}_t = \frac{\phi(x_{t2} \cdot \hat{\beta}_{\cdot 2})}{\Phi(x_{t2} \cdot \hat{\beta}_{\cdot 2})}, \quad t = 1, 2, \dots, T, \quad (124)$$

and consider the estimator

$$\tilde{\delta} = (X_1^{**'} X_1^{**})^{-1} X_1^{**'} y_{1\cdot}, \quad \delta = (\beta'_{\cdot 1}, \sigma_{12})', \quad (125)$$

where we have written

$$y_{1\cdot} = x_{1\cdot} \beta_1 + \sigma_{12} \psi_{\cdot} + v_{1\cdot}, \quad v_{1\cdot} = u_{1\cdot} - \sigma_{12} \psi_{\cdot}, \quad (126)$$

$$X_1^{**} = (X_1, \tilde{\psi}), \quad X_1 = (x_{1\cdot}), \quad \tilde{\psi} = (\tilde{\psi}_t), \quad t = 1, 2, \dots, T. \quad (127)$$

We observe that

$$(\tilde{\delta} - \delta^0) = (X_1^{**'} X_1^{**})^{-1} X_1^{**'} [v_{1\cdot} - \sigma_{12}(\tilde{\psi} - \psi)]. \quad (128)$$



It is our contention that the estimator in (125) is consistent for  $\beta_{\cdot 1}$  and  $\sigma_{12}$ ; moreover that it naturally implies a consistent estimator for  $\sigma_{11}$ , thus yielding the initial consistent estimator, say

$$\tilde{\gamma} = (\tilde{\beta}'_{\cdot 1}, \hat{\beta}'_{\cdot 2}, \tilde{\sigma}_{11}, \tilde{\rho}_{12})' \quad (129)$$

which we require for obtaining the LM estimator.

Formally, we will establish that

$$\sqrt{T}(\tilde{\delta} - \delta^0) = \left( \frac{X_1^{**'} X_1^{**}}{T} \right) \frac{1}{\sqrt{T}} X_1^{**'} [v_{\cdot 1} - \sigma_{12}(\tilde{\psi} - \psi)] \sim N(0, F), \quad (130)$$

for suitable matrix  $F$ , thus showing that  $\tilde{\delta}$  converges to  $\delta^0$  with probability one (almost surely).

In order that we may accomplish this task it is imperative that we must specify more precisely the conditions under which we are to consider the model<sup>5</sup> in (94), as expressed in (97). We have:

(A.3.1.) The basic error process

$$\{u'_t : t = 1, 2, \dots\}, \quad u_t = (u_{t1}, u_{t2}),$$

is one of i.i.d. random variables with

$$u'_t \sim N(0, \Sigma), \quad \Sigma > 0, \quad \sigma_{22} = 1,$$

and is independent of the process generating the exogenous variables  $x_{t1}, x_{t2}$ .

(A.3.2.) The admissible parameter space, say  $H \subset R_{n+3}$ , is closed and bounded and contains an open neighborhood of the true parameter point

$$\gamma^0 = (\beta^0_{\cdot 1}, \beta^0_{\cdot 2}, \sigma^0_{11}, \rho^0_{12})'.$$

(A.3.3.) The exogenous variables are nonstochastic and are bounded, i.e.

$$|x_{t2i}| < k_i, \quad i = 0, 1, 2, \dots, n$$

for all  $t$ .<sup>6</sup>

<sup>5</sup>As pointed out earlier, it may be more natural to state conditions in terms of the basic variables  $x^*_{t1}, x^*_{t2}, u^*_{t1}$  and  $u^*_{t2}$ ; doing so, however, will disrupt the continuity of our discussion; for this reason we state conditions in terms of  $x_{t1}, x_{t2}, u_{t1}$  and  $u_{t2}$ .

(A.3.4.) The matrix

$$X_2 = (x_{t2}) \quad t=1,2,\dots,T,$$

is of rank  $n+1$  and moreover

$$\lim_{T \rightarrow \infty} \frac{1}{T} X_2' X_2 = P, \quad P > 0.$$

*Remark 9*

It is a consequence of the assumptions above that, for any  $x_{t2}$  and admissible  $\beta_{.2}$ , there exists  $k$  such that

$$-r \leq x_{t2} \cdot \beta_{.2} \leq r, \quad 0 < r < k, \quad k < \infty,$$

so that, for example,

$$\begin{aligned} \phi(x_{t2} \cdot \beta_{.2}) &> \phi(-k) > 0, \\ \Phi(x_{t2} \cdot \beta_{.2}) &< \Phi(k) < 1, \\ \Phi(x_{t2} \cdot \beta_{.2}) &> \Phi(-k) > 0. \end{aligned} \tag{131}$$

Consequently,

$$\psi(v_t) = \frac{\phi(x_{t2} \cdot \beta_{.2})}{\Phi(x_{t2} \cdot \beta_{.2})}, \quad \psi^*(v_t) = \frac{\phi(x_{t2} \cdot \beta_{.2})}{\Phi(-x_{t2} \cdot \beta_{.2})},$$

are both bounded continuous functions of their argument.

To show the validity of (130) we proceed by a sequence of Lemmata.

*Lemma 5*

The probability limit of the matrix to be inverted is given by

$$\text{plim}_{T \rightarrow \infty} \frac{1}{T} X_1^* X_1^* = \lim_{T \rightarrow \infty} \frac{1}{T} X_1^0 X_1^0 = Q_0, \quad Q_0 > 0,$$

<sup>6</sup>We remind the reader that in the canonical representation of (97), the vector  $x_{t1}$  is a subvector of  $x_{t2}$ ; hence the boundedness assumptions on  $x_{t2}$  imply similar boundedness conditions on  $x_{t1}$ .

Incidentally, note that  $\beta_{.1}^0$  is not necessarily a subvector of  $\beta_{.2}^0$ , since the latter would contain  $\beta_{.11}^* - \beta_{.12}^0$  and in addition  $\beta_{.21}^0, -\beta_{.22}^0$ , while the former will contain  $\beta_{.11}^0, \beta_{.21}^*$ .

where

$$X_1^0 = (X_1, \psi^0), \quad \psi^0 = (\psi_i^0), \quad \psi_i^0 = \frac{\phi(x_{i2}, \beta_2^0)}{\Phi(x_{i2}, \beta_2^0)}.$$

*Proof*

We examine

$$S_T = \frac{1}{T} [X_1^{*'} X_1^* - X_1^{0'} X_1^0] = \frac{1}{T} \begin{bmatrix} 0 & X_1'(\tilde{\psi} - \psi^0) \\ (\tilde{\psi} - \psi^0)' X_1 & (\tilde{\psi} + \psi^0)(\tilde{\psi} - \psi^0) \end{bmatrix}, \quad (132)$$

and the problem is reduced to considering

$$\tilde{\psi}_i - \psi_i^0 = \alpha_i^0 x_{i2} \cdot (\hat{\beta}_{\cdot 2} - \beta_2^0) + s_i^* (\hat{\beta}_{\cdot 2} - \beta_2^0)' x_{i2} \cdot x_{i2} \cdot (\hat{\beta}_{\cdot 2} - \beta_2^0), \quad (133)$$

where

$$\alpha_i^0 = \frac{\partial \psi(v_{i2})}{\partial v_{i2}} \quad \text{evaluated at } \beta_{\cdot 2} = \beta_2^0,$$

$$s_i^* = \frac{\partial^2 \psi(v_{i2})}{\partial v_{i2}^2} \quad \text{evaluated at } \beta_{\cdot 2} = \beta_2^*,$$

$$|\beta_2^* - \beta_2^0| < |\beta_{\cdot 2} - \beta_2^0|.$$

It is evident that, when the expansion in (133) is incorporated in (132) quadratic terms in  $(\hat{\beta}_{\cdot 2} - \beta_2^0)$  will vanish with  $T$ .

Hence we need be concerned only with the terms of the form

$$\frac{1}{T} \sum_{i=1}^T x_{i1}' \cdot (\tilde{\psi}_i - \psi_i^0) \sim \frac{1}{T^{3/2}} \sum_{i=1}^T [\alpha_i^0 x_{i1}' \cdot x_{i2}] \sqrt{T} (\hat{\beta}_{\cdot 2} - \beta_2^0),$$

or of the form

$$\frac{1}{T} \sum_{i=1}^T (\tilde{\psi}_i + \psi_i^0)(\tilde{\psi}_i - \psi_i^0) \sim \frac{1}{T^{3/2}} \sum_{i=1}^T [\alpha_i^0 (\tilde{\psi}_i + \psi_i^0) x_{i2}] \sqrt{T} (\hat{\beta}_{\cdot 2} - \beta_2^0).$$

In either case we note that by assumption (A.3.4.) and Remark 9

$$\lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \alpha_t^0 x'_{t1} \cdot x_{t2},$$

has bounded elements; similarly, for

$$\lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T \alpha_t^0 (\tilde{\psi}_t + \psi_t^0) x_{t2}.$$

Consequently, in view of (122) and (132) we conclude

$$\text{plim}_{T \rightarrow \infty} S_T = 0,$$

which implies

$$\text{plim}_{T \rightarrow \infty} \frac{1}{T} X_1^{*'} X_1^* = \lim_{T \rightarrow \infty} \frac{1}{T} X_1^{0'} X_1^0 = Q_0. \quad (134)$$

#### Corollary 4

The limiting distribution of the left member of (130) is obtainable through

$$\sqrt{T}(\tilde{\delta} - \delta^0) \sim Q_0^{-1} X_1^{*'} [v_{\cdot 1} - \sigma_{12}(\tilde{\psi} - \psi^0)], \quad v_{\cdot 1} = (v_{11}, v_{21} \cdots v_{T1})'$$

Indeed, by standard argumentation we may establish

#### Theorem 4

Under assumption (A.3.1) through (A.3.4) the initial (consistent) estimator of this section has the limiting distribution

$$\sqrt{T}(\tilde{\delta} - \delta^0) \sim N(0, F), \quad F = Q_0^{-1} P Q_0^{-1},$$

where

$$P = \sigma_{11} \lim_{T \rightarrow \infty} \frac{1}{T} \begin{bmatrix} \sum_{t=1}^T \omega_{11t} x'_{t1} \cdot x_{t1} & \sum_{t=1}^T \omega_{11t} \psi_t^0 x'_{t1} \\ \sum_{t=1}^T \omega_{11t} \psi_t^0 x_{t1} & \sum_{t=1}^T \omega_{11t} \psi_t^{02} \end{bmatrix}$$

$Q_0$  is defined in (134) and

$$E(v_{11}^2) = \sigma_{11}\omega_{11t} = \sigma_{11} \left[ 1 - \rho_{12}^0 v_{12}^0 \psi_t^0 - \rho_{12}^0 \psi_t^0 \right].$$

*Corollary 5*

The initial estimator above is strongly consistent.

*Proof*

From the theorem above

$$\sqrt{T}(\tilde{\delta} - \delta^0) \sim \zeta,$$

where  $\zeta$  is an a.c. finite random vector.

Thus

$$\tilde{\delta} - \delta^0 \sim \frac{1}{\sqrt{T}} \zeta,$$

$\tilde{\delta}$  converges to  $\delta^0$  a.c.

Evidently, the parameter  $\sigma_{11}$  can be estimated (at least consistently) by

$$\tilde{\sigma}_{11} = \frac{1}{T} \left[ \tilde{v}_{11}^2 + \tilde{\sigma}_{12} \tilde{\psi}_t \tilde{v}_t + \tilde{\sigma}_{12} \tilde{\psi}_t^2 \right].$$

### 3.5. Limiting distribution of the ML estimator

In the previous section we outlined a procedure for obtaining an initial estimator, say

$$\tilde{\gamma} = (\tilde{\beta}_1, \tilde{\beta}_2', \tilde{\sigma}_{11}, \tilde{\sigma}_{12})',$$

and have shown that it converges to the true parameter point, say  $\gamma^0$ , with probability one (a.c.).

We now investigate the properties of the ML estimator, say  $\hat{\gamma}$ , obtained by solving

$$\frac{\partial L}{\partial \gamma}(\hat{\gamma}) = 0$$

through iteration, beginning with  $\hat{\gamma}$ . The limiting distribution of  $\hat{\gamma}$  may be found by examining

$$\sqrt{T}(\hat{\gamma} - \gamma^0) = \left[ -\frac{1}{T} \frac{\partial^2 L}{\partial \gamma \partial \gamma}(\gamma^*) \right]^{-1} \frac{1}{\sqrt{T}} \frac{\partial L}{\partial \gamma}(\gamma^0), \quad (135)$$

where  $\gamma^0$  is the true parameter point,  $\gamma^*$  obeys

$$|\gamma^* - \gamma^0| \leq |\hat{\gamma} - \gamma^0|,$$

and

$$\frac{\partial L}{\partial \gamma'}(\gamma^0) = \sum_{t=1}^T A_t \xi_{.t}, \quad (136)$$

where

$$A_t = \begin{bmatrix} \frac{1}{\sigma_{11}^{1/2}} x'_{t1} & 0 & 0 & 0 \\ 0 & x'_{t2} & 0 & 0 \\ 0 & 0 & \frac{1}{2\sigma_{11}} & 0 \\ 0 & 0 & 0 & \frac{1}{\alpha^{3/2}} \end{bmatrix} \quad (137)$$

$$\begin{aligned} \xi_{1t} &= c_t \left[ \frac{u_{t1}}{\sigma_{11}^{1/2}} - \frac{\rho_{12}}{\alpha^{1/2}} \frac{\phi(\pi_t)}{\Phi(\pi_t)} \right], \\ \xi_{2t} &= c_t \left[ \frac{1}{\alpha^{1/2}} \frac{\phi(\pi_t)}{\Phi(\pi_t)} \right] - (1 - c_t) \frac{\phi(v_{t2})}{\Phi(v_{t2})}, \\ \xi_{3t} &= c_t \left[ \left( \frac{u_{t1}}{\sigma_{11}^{1/2}} \right)^2 - \frac{\rho_{12}}{\alpha^{1/2}} \frac{\phi(\pi_t)}{\Phi(\pi_t)} \left( \frac{u_{t1}}{\sigma_{11}^{1/2}} \right) - 1 \right], \\ \xi_{4t} &= c_t \frac{\phi(\pi_t)}{\Phi(\pi_t)} \left[ \rho_{12} v_{t2} + \frac{u_{t1}}{\sigma_{11}^{1/2}} \right], \\ \xi_{.t} &= (\xi_{1t}, \xi_{2t}, \xi_{3t}, \xi_{4t})'. \end{aligned} \quad (138)$$

In order to complete the problem we also require an expression for the Hessian of the likelihood function in addition to the expressions in (110) through (113).

To this effect define

$$\begin{aligned}
 \xi_{11t} &= c_t \left[ 1 + \frac{\rho_{12}^2}{\alpha} \pi_t \frac{\phi(\pi_t)}{\Phi(\pi_t)} + \frac{\rho_{12}^2}{\alpha} \frac{\phi^2(\pi_t)}{\Phi^2(\pi_t)} \right], \\
 \xi_{21t} &= -c_t \left[ \frac{\rho_{12}}{\alpha} \frac{\phi(\pi_t)}{\Phi(\pi_t)} \pi_t + \frac{\rho_{12}}{\alpha} \frac{\phi^2(\pi_t)}{\Phi^2(\pi_t)} \right], \\
 \xi_{31t} &= c_t \left[ 2 \left( \frac{u_{t1}}{\sigma_{11}^{1/2}} \right) - \frac{\rho_{12}}{\alpha} \frac{\phi(\pi_t)}{\Phi(\pi_t)} + \frac{\rho_{12}^2}{\alpha} \frac{\phi(\pi_t)}{\Phi(\pi_t)} \pi_t \left( \frac{u_{t1}}{\sigma_{11}^{1/2}} \right) \right. \\
 &\quad \left. + \frac{\rho_{12}^2}{\alpha} \frac{\phi^2(\pi_t)}{\Phi^2(\pi_t)} \left( \frac{u_{t1}}{\sigma_{11}^{1/2}} \right) \right], \\
 \xi_{41t} &= c_t \left[ \frac{\phi(\pi_t)}{\Phi(\pi_t)} - \frac{\rho_{12}}{\alpha^{1/2}} \frac{\phi(\pi_t)}{\Phi(\pi_t)} \pi_t \left( \rho_{12} \nu_{t2} + \frac{u_{t1}}{\sigma_{11}^{1/2}} \right) \right. \\
 &\quad \left. - \frac{\rho_{12}}{\alpha^{1/2}} \frac{\phi^2(\pi_t)}{\Phi^2(\pi_t)} \left( \rho_{12} \nu_{t2} + \frac{u_{t1}}{\sigma_{11}^{1/2}} \right) \right], \\
 \xi_{22t} &= \frac{1}{\alpha} c_t \left[ \frac{\phi(\pi_t)}{\Phi(\pi_t)} \pi_t + \frac{\phi^2(\pi_t)}{\Phi^2(\pi_t)} \right] + (1 - c_t) \psi^*(\nu_{t2}) [\psi^*(\nu_{t2}) - \nu_{t2}], \\
 \xi_{32t} &= -c_t \left[ \frac{\rho_{12}}{\alpha} \frac{\phi(\pi_t)}{\Phi(\pi_t)} \pi_t \left( \frac{u_{t1}}{\sigma_{11}^{1/2}} \right) + \frac{\rho_{12}}{\alpha} \frac{\phi^2(\pi_t)}{\Phi^2(\pi_t)} \left( \frac{u_{t1}}{\sigma_{11}^{1/2}} \right) \right], \\
 \xi_{42t} &= -c_t \frac{1}{\alpha^{1/2}} \left[ \frac{\phi^2(\pi_t)}{\Phi^2(\pi_t)} \left( \rho_{12} \nu_{t2} + \frac{u_{t1}}{\sigma_{11}^{1/2}} \right) \right], \\
 \xi_{42t}^* &= c_t \left[ \rho_{12} \frac{\phi(\pi_t)}{\Phi(\pi_t)} - \frac{1}{\alpha^{1/2}} \frac{\phi(\pi_t)}{\Phi(\pi_t)} \pi_t \left( \rho_{12} \nu_{t2} + \frac{u_{t1}}{\sigma_{11}^{1/2}} \right) \right], \\
 \xi_{33t} &= c_t \left[ 2 \left( \frac{u_{t1}}{\sigma_{11}^{1/2}} \right)^2 - \frac{\rho_{12}}{\alpha^{1/2}} \frac{\phi(\pi_t)}{\Phi(\pi_t)} \frac{u_{t1}}{\sigma_{11}^{1/2}} + \frac{\rho_{12}^2}{\alpha} \frac{\phi(\pi_t)}{\Phi(\pi_t)} \pi_t \left( \frac{u_{t1}}{\sigma_{11}^{1/2}} \right)^2 \right. \\
 &\quad \left. + \frac{\rho_{12}^2}{\alpha} \frac{\phi^2(\pi_t)}{\Phi^2(\pi_t)} \left( \frac{u_{t1}}{\sigma_{11}^{1/2}} \right)^2 \right],
 \end{aligned} \tag{139}$$

$$\xi_{33t}^* = \xi_{3t},$$

$$\xi_{43t} = c_t \left[ \frac{\phi(\pi_t)}{\Phi(\pi_t)} \left( \frac{u_{t1}}{\sigma_{11}^{1/2}} \right) - \frac{\rho_{12}}{\alpha^{1/2}} \frac{\phi(\pi_t)}{\Phi(\pi_t)} \pi_t \left( \rho_{12} \nu_{t2} \left( \frac{u_{t1}}{\sigma_{11}^{1/2}} \right) + \frac{u_{t1}^2}{\sigma_{11}} \right) - \frac{\rho_{12}}{\alpha^{1/2}} \frac{\phi^2(\pi_t)}{\Phi^2(\pi_t)} \left( \rho_{12} \nu_{t2} \left( \frac{u_{t1}}{\sigma_{11}^{1/2}} \right) + \frac{u_{t1}^2}{\sigma_{11}} \right) \right],$$

$$\xi_{44t} = \xi_{4t}^2,$$

$$\xi_{44t}^* = \frac{3\rho_{12}}{\alpha} \xi_{4t} + c_t \left[ \frac{\phi(\pi_t)}{\Phi(\pi_t)} \nu_{t2} - \frac{1}{\alpha^{3/2}} \frac{\phi(\pi_t)}{\Phi(\pi_t)} \pi_t \left( \rho_{12} \nu_{t2} + \frac{u_{t1}}{\sigma_{11}^{1/2}} \right)^2 \right].$$

In the expressions of (138) and (139) we have replaced, for reasons of notational economy only,

$$\left( \frac{y_{t1} - x_t \cdot \beta_{\cdot 1}}{\sigma_{11}^{1/2}} \right),$$

by

$$\left( \frac{u_{t1}}{\sigma_{11}^{1/2}} \right).$$

#### Remark 10

The starred symbols, for example,  $\xi_{42t}^*$ ,  $\xi_{33t}^*$ ,  $\xi_{44t}^*$ , all correspond to components of the Hessian of the log LF *having mean zero*. Hence, such components can be ignored both in determining the limiting distribution of the ML estimator and in its numerical derivation, given a sample. We can, then, represent the Hessian of the log of the LF as

$$\frac{\partial^2 L}{\partial \gamma \partial \gamma} = \sum_{t=1}^T \Omega_t + \sum_{t=1}^T \Omega_t^*,$$

where  $\Omega_t^*$  contains only zeros or elements having mean zero. It is also relatively straightforward to verify that

$$A_t \text{Cov}(\xi_{\cdot t}) A_t' = E(\Omega_t),$$

where the elements of  $A_t$ ,  $\xi_{\cdot t}$  and  $\Omega_t$  have been evaluated at the true parameter point  $\gamma^0$ .

To determine the limiting distribution of the ML estimator (i.e. the converging iterate beginning with an initial consistent estimator) we need



*Lemma 6*

Let  $A_t, \xi_{\cdot t}$  be as defined in (139) and (138); then,

$$\frac{1}{\sqrt{T}} \frac{\partial L}{\partial \gamma'}(\gamma^0) = \frac{1}{\sqrt{T}} \sum_{t=1}^T A_t \xi_{\cdot t} \sim N(0, C_*),$$

where

$$C_* = \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T A_t \text{Cov}(\xi_{\cdot t}) A_t' = \lim_{T \rightarrow \infty} \frac{1}{T} \sum_{t=1}^T E(\Omega_t). \quad (141)$$

*Proof*

The sequence

$$\{A_t \xi_{\cdot t}; t = 1, 2, \dots\},$$

is one of independent nonidentically distributed random vectors with mean zero and uniformly bounded moments to any finite order; moreover, the sequence obeys a Liapounov condition. Consequently

$$\frac{1}{\sqrt{T}} \frac{\partial L}{\partial \gamma}(\gamma^0) \sim N(0, C_*). \quad (\text{Q.E.D.})$$

An explicit representation of  $\Omega_t$  or  $C_*$  is omitted here because of its notational complexity. To complete the argument concerning the limiting distribution of the ML estimator we obtain the limit of

$$\frac{1}{T} \frac{\partial^2 L}{\partial \gamma \partial \gamma}(\gamma), \quad \gamma \in H.$$

Again for the sake of brevity of exposition we shall only state the result without proof

*Lemma 7*

Under assumptions (A.3.1) through (A.3.4)

$$\frac{1}{T} \frac{\partial^2 L}{\partial \gamma \partial \gamma}(\gamma) \xrightarrow{\text{a.c.}} \lim_{T \rightarrow \infty} \frac{1}{T} E \left[ \frac{\partial^2 L}{\partial \gamma \partial \gamma}(\gamma) \right],$$

uniformly in  $\gamma$ .

*Remark 11*

We note that for  $\gamma = \gamma^0$

$$\lim_{T \rightarrow \infty} \frac{1}{T} E \left[ \frac{\partial^2 L}{\partial \gamma \partial \gamma'} (\gamma) \right] = -C_*$$

We finally have

*Theorem 5*

(Asymptotic Normality): Consider the model of (97) subject to the condition in (107) and assumptions (A.3.1.) through (A.3.4.). Let  $\hat{\gamma}$  be the ML estimator of  $\gamma^0$  – the true parameter point. Then

$$\sqrt{T} (\hat{\gamma} - \gamma^0) \sim N(0, C),$$

where

$$C = C_*^{-1},$$

and  $C_*$  is as is defined in (141).

*Proof*

From the expansion in (135)

$$\sqrt{T} (\hat{\gamma} - \gamma^0) \sim C_*^{-1} \frac{1}{\sqrt{T}} \frac{\partial L}{\partial \gamma'} (\gamma^0).$$

From Lemma 6 we then conclude

$$\sqrt{T} (\hat{\gamma} - \gamma^0) \sim N(0, C).$$

Q.E.D.

*Corollary 6*

The ML estimator  $\hat{\gamma}$  obeys

$$\hat{\gamma} \xrightarrow{\text{a.c.}} \gamma^0.$$

*Proof*

By Theorem 5

$$\sqrt{T} (\hat{\gamma} - \gamma^0) \sim \xi,$$

where  $\zeta$  is a well defined a.c. finite random variable. Hence,

$$\tilde{\gamma} - \gamma^0 \sim \frac{\zeta}{\sqrt{T}} \xrightarrow{\text{a.c.}} 0.$$

### Corollary 7

The matrix in the expansion of (135) obeys

$$\frac{1}{T} \frac{\partial^2 L}{\partial \gamma \partial \gamma}(\gamma^*) \xrightarrow{\text{a.c.}} \lim_{T \rightarrow \infty} \frac{1}{T} E \left[ \frac{\partial^2 L}{\partial \gamma \partial \gamma}(\gamma^0) \right].$$

### Proof

Lemma 7 and Corollary 6.

### 3.6. A test for selectivity bias

A test for selectivity bias is formally equivalent to the test of

$$H_0: \rho_{12} = 0 \quad \text{or} \quad \gamma = (\beta'_{.1}, \beta'_{.2}, \sigma_{11}, 0)'$$

as against the alternative

$H_1: \gamma$  unrestricted (except for the obvious conditions,  $\sigma_{11} > 0$ ,  $\rho_{12}^2 \in [0, 1]$ ). From the likelihood function in eq. (109) the (log) LF under  $H_0$  becomes

$$\begin{aligned} L(\gamma|H_0) = \sum_{t=1}^T & \left\{ (1 - c_t) \ln \Phi(-v_{t2}) + c_t \ln \Phi(v_{t2}) \right. \\ & \left. - \frac{1}{2} c_t \left[ \ln(2\pi) + \ln \sigma_{11} + \frac{1}{\sigma_{11}} (y_{t1} - x_{t1} \cdot \beta_{.1})^2 \right] \right\}. \end{aligned} \quad (142)$$

We note that (142) is separable in the parameters  $(\beta'_{.1}, \sigma_{11})'$  and  $\beta_{.2}$ . Indeed, the ML estimator of  $\beta_{.2}$  is the "probit" estimator,  $\hat{\beta}_{.2}$ , obtained in connection with eq. (118) in Section 3.d.; the ML estimator of  $(\beta'_{.1}, \sigma_{11})'$  is the usual one obtained by least squares except that  $\sigma_{11}$  is estimated with bias – as all maximum likelihood procedures imply in the normal case. Denote the estimator of  $\gamma$  obtained under  $H_0$ , by  $\tilde{\gamma}$ . Denote by  $\hat{\gamma}$  the ML estimator whose limiting distribution was obtained in the preceding section.

Thus

$$\lambda = L(\hat{\gamma}|H_1) - L(\hat{\gamma}|H_0). \quad (143)$$

is the usual likelihood ratio test statistic. It may be shown that

$$-2\lambda \sim \chi_1^2. \quad (144)$$

We have thus proved

#### *Theorem 6*

In the context of the model of this section a test for the absence of selectivity bias can be carried out by the likelihood ratio (LR) principle. The test statistic is

$$-2\lambda \sim \chi_1^2,$$

where

$$\lambda = \sup_{H_0} L(\gamma) - \sup_{H_1} L(\gamma).$$

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