

An HDG method for the velocity-vorticity formulation

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- Hybridizable DG methods (HDG) were discovered in
 - ▶ [Cockburn, G., Lazarov, 2009] “Unified hybridization of DG, mixed, and CG methods for second order elliptic problems”, SINUM.
 - ▶ Many authors analyzed HDG, and extended to various applications.

- This talk is on an HDG method for Stokes flow:
 - ▶ [Cockburn, & G., 2009] “The derivation of hybridizable discontinuous Galerkin methods for Stokes flow”, SINUM.

$$\begin{aligned} -\Delta \mathbf{u} + \mathbf{grad} p &= \mathbf{f}, && \text{on } \Omega, \\ \operatorname{div} \mathbf{u} &= 0, && \text{on } \Omega, \\ \mathbf{u} &= \mathbf{0}, && \text{on } \partial\Omega. \end{aligned}$$

Since $-\Delta \mathbf{u} = \mathbf{curl} \mathbf{curl} \mathbf{u} - \mathbf{grad} \operatorname{div} \mathbf{u}$, the Stokes equations can be rewritten using vorticity ω :

$$\begin{aligned} \omega - \mathbf{curl} \mathbf{u} &= \mathbf{0}, && \text{on } \Omega, \\ \mathbf{curl} \omega + \mathbf{grad} p &= \mathbf{f}, && \text{on } \Omega, \\ \operatorname{div} \mathbf{u} &= 0, && \text{on } \Omega. \end{aligned}$$

$$\begin{aligned}\boldsymbol{\omega} - \mathbf{curl} \mathbf{u} = 0 &\implies (\boldsymbol{\omega}, \boldsymbol{\tau})_{\Omega} - (\mathbf{u}, \mathbf{curl} \boldsymbol{\tau})_{\Omega} = 0 \\ \mathbf{curl} \boldsymbol{\omega} + \mathbf{grad} p = \mathbf{f} &\implies (\mathbf{v}, \mathbf{curl} \boldsymbol{\omega})_{\Omega} = (\mathbf{v}, \mathbf{f})_{\Omega} \\ \mathbf{div} \mathbf{u} = 0 &\implies (\text{imposed in the space}).\end{aligned}$$

$$\begin{aligned}\boldsymbol{\omega}, \boldsymbol{\tau} &\in H(\mathbf{curl}) \\ \mathbf{u}, \mathbf{v} &\in \{\mathbf{v} \in H(\mathbf{div}) : \mathbf{div} \mathbf{v} = 0, \quad \mathbf{v} \cdot \mathbf{n}|_{\partial\Omega} = 0\}.\end{aligned}$$

Known approaches:

- Use stream function [Girault & Raviart, 1986]
- Use a double hybridization [Cockburn & G., 2000]
- Use DG [Carrero, Cockburn, Schötzau, 2006]

This talk's approach: hybrid DG

$$\boldsymbol{\omega} - \mathbf{curl} \mathbf{u} = \mathbf{0} \quad \implies$$

$$(\boldsymbol{\omega}_h, \boldsymbol{\tau})_K - (\mathbf{u}_h, \mathbf{curl} \boldsymbol{\tau})_K + \langle \widehat{\mathbf{u}}_h, \mathbf{n} \times \boldsymbol{\tau} \rangle_{\partial K} = 0,$$

$$\mathbf{curl} \boldsymbol{\omega} + \mathbf{grad} p = \mathbf{f} \quad \implies$$

$$(\boldsymbol{\omega}_h, \mathbf{curl} \mathbf{v})_K + \langle \widehat{\boldsymbol{\omega}}_h, \mathbf{v} \times \mathbf{n} \rangle_{\partial K} - (p_h, \mathbf{div} \mathbf{v})_K + \langle \widehat{p}_h, \mathbf{v} \cdot \mathbf{n} \rangle_{\partial K} = (\mathbf{f}, \mathbf{v})_K,$$

$$\mathbf{div} \mathbf{u} = 0 \quad \implies$$

$$-(\mathbf{u}_h, \mathbf{grad} q)_K + \langle \widehat{\mathbf{u}}_h \cdot \mathbf{n}, q \rangle_{\partial K} = 0,$$

- Numerical traces: $\widehat{\mathbf{u}}_h \times \mathbf{n}$, $\widehat{\boldsymbol{\omega}}_h \times \mathbf{n}$, \widehat{p}_h , $\widehat{\mathbf{u}}_h \cdot \mathbf{n}$.
- Element spaces: $\boldsymbol{\omega}_h, \boldsymbol{\tau} \in \mathbf{W}(K)$, $\mathbf{u}_h, \mathbf{v} \in \mathbf{V}(K)$, $p_h, q \in P(K)$.

Various DG methods are obtained by prescribing various numerical traces and element spaces.

Q: Are there choices of numerical traces $\hat{\mathbf{u}}_h \times \mathbf{n}$, $\hat{\boldsymbol{\omega}}_h \times \mathbf{n}$, \hat{p}_h , $\hat{\mathbf{u}}_h \times \mathbf{n}$ that yield a *hybridizable* method? A: (our main result) Yes!

Q: Are there choices of numerical traces $\hat{\mathbf{u}}_h \times \mathbf{n}$, $\hat{\boldsymbol{\omega}}_h \times \mathbf{n}$, $\hat{\rho}_h$, $\hat{\mathbf{u}}_h \times \mathbf{n}$ that yield a *hybridizable* method? A: (our main result) **Yes!**

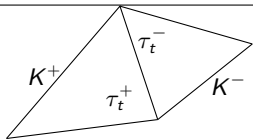
$$(\hat{\boldsymbol{\omega}}_h)_t = \left(\frac{\tau_t^- (\boldsymbol{\omega}_h^+)_t + \tau_t^+ (\boldsymbol{\omega}_h^-)_t}{\tau_t^- + \tau_t^+} \right) + \left(\frac{\tau_t^+ \tau_t^-}{\tau_t^- + \tau_t^+} \right) [\mathbf{u}_h \times \mathbf{n}],$$

$$(\hat{\mathbf{u}}_h)_t = \left(\frac{\tau_t^+ (\mathbf{u}_h^+)_t + \tau_t^- (\mathbf{u}_h^-)_t}{\tau_t^- + \tau_t^+} \right) + \left(\frac{1}{\tau_t^- + \tau_t^+} \right) [\mathbf{n} \times \boldsymbol{\omega}_h],$$

$$(\hat{\mathbf{u}}_h)_n = \left(\frac{\tau_n^+ (\mathbf{u}_h^+)_n + \tau_n^- (\mathbf{u}_h^-)_n}{\tau_n^- + \tau_n^+} \right) + \left(\frac{1}{\tau_n^- + \tau_n^+} \right) [\rho_h \mathbf{n}],$$

$$\hat{\rho}_h = \left(\frac{\tau_n^- \rho_h^+ + \tau_n^+ \rho_h^-}{\tau_n^- + \tau_n^+} \right) + \left(\frac{\tau_n^+ \tau_n^-}{\tau_n^- + \tau_n^+} \right) [\mathbf{u}_h \cdot \mathbf{n}],$$

- $[\dots]$ \rightarrow jump, $(\cdot)_t \rightarrow$ tangential, $(\cdot)_n \rightarrow$ normal
- $\tau_t, \tau_n \rightarrow$ two stabilization parameters
- \pm indicate values from adjacent elements K^\pm .



Theorem

Assume that τ_t and τ_n are positive everywhere. Assume also that

$$\begin{aligned}\mathbf{curl} \mathbf{V}(K) &\subset \mathbf{W}(K), \\ \mathbf{grad} P(K) &\subset \mathbf{V}(K), \\ \mathbf{div} \mathbf{V}(K) &\subset P(K),\end{aligned}$$

for every element $K \in \Omega_h$. Then there is one and only one $(\omega_h, \mathbf{u}_h, p_h)$ satisfying the equations of the method (including the numerical trace expressions and boundary conditions).

If $\mathbf{W}(K)$, $\mathbf{V}(K)$, $P(K)$ are set to polynomials of degree d_W, d_V, d_P , resp., then for any $k \geq 1$, we may choose (d_W, d_V, d_P) to

$$\begin{array}{lll} (k-1, & k-1, & k), & (k, & k-1, & k), & (k+1, & k-1, & k), \\ (k-1, & k, & k), & (k, & k, & k), & (k+1, & k, & k), \\ (k, & k+1, & k), & (k+1, & k+1, & k), & (k+1, & k+1, & k). \end{array}$$

There are 4 transmission conditions for Stokes flow:

$$[[\boldsymbol{\omega} \times \mathbf{n}]] = 0, \quad [[\mathbf{u} \times \mathbf{n}]] = 0, \quad [[\mathbf{u} \cdot \mathbf{n}]] = 0, \quad [[p \mathbf{n}]] = 0.$$

Hybridization strategy:

- Pick two as unknowns, and find equations by the remaining two!

Type I:	Unknowns:	$\hat{\mathbf{u}}_h \times \mathbf{n},$	$\hat{p}_h \mathbf{n}$
	Equations:	$[[\hat{\boldsymbol{\omega}}_h \times \mathbf{n}]] = 0,$	$[[\hat{\mathbf{u}}_h \cdot \mathbf{n}]] = 0$
Type II:			
Type III:			
Type IV:			

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Type IV:	Unknowns:	$\hat{\boldsymbol{\omega}}_h \times \mathbf{n},$	$\hat{p}_h \mathbf{n}$
	Equations:	$[[\hat{\mathbf{u}}_h \times \mathbf{n}]] = 0,$	$[[\hat{\mathbf{u}}_h \cdot \mathbf{n}]] = 0$

Discard the remaining two choices.

Results on Type I hybridization

Type I:	Unknowns:	$\hat{\mathbf{u}}_h \times \mathbf{n},$	$\hat{\rho}_h \mathbf{n}$
	Equations:	$[[\hat{\boldsymbol{\omega}}_h \times \mathbf{n}]] = 0,$	$[[\hat{\mathbf{u}}_h \cdot \mathbf{n}]] = 0$

Type I:	Unknowns:	λ_t	
	Equations:	$[[\hat{\omega}_h \times \mathbf{n}]] = 0,$	$[[\hat{\mathbf{u}}_h \cdot \mathbf{n}]] = 0$

- The “Equations” give a uniquely solvable **condensed** system

$$\begin{pmatrix} A & B^t \\ B & C \end{pmatrix} \begin{pmatrix} \lambda_t \\ \rho \end{pmatrix} = \text{r.h.s.}, \quad (\text{plus one eq. for mean}(\rho))$$

with locally computable operators A , B , C , on appropriate piecewise polynomial spaces on element interfaces.

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- The solution (λ_t, ρ) gives the **same** numerical traces stated earlier.

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with locally computable operators A, B, C , on appropriate piecewise polynomial spaces on element interfaces.

- The solution (λ_t, ρ) gives the **same** numerical traces stated earlier.
- On any element K , all variables are recovered **locally** from (λ_t, ρ) by:

$$\text{Solve for } \omega_h, \mathbf{u}_h, p_h \text{ using the HDG discretization of } \left\{ \begin{array}{ll} \omega - \mathbf{curl} \mathbf{u} = 0 & \text{in } K, \\ \mathbf{curl} \omega + \mathbf{grad} p = \mathbf{f} & \text{in } K, \\ \mathbf{div} \mathbf{u} = 0 & \text{in } K, \\ (\mathbf{u})_t = \lambda_t & \text{on } \partial K, \\ \rho = \rho & \text{on } \partial K. \end{array} \right.$$

Results on Type II hybridization

Type II:	Unknowns:	$\hat{\mathbf{u}}_h \times \mathbf{n},$	$\hat{\mathbf{u}}_h \cdot \mathbf{n}$
	Equations:	$[[\hat{\boldsymbol{\omega}}_h \times \mathbf{n}]] = 0,$	$[[\hat{\boldsymbol{\rho}}_h \mathbf{n}]] = 0$

Type II:	Unknowns:	λ_t	λ_n
	Equations:	$[[\hat{\omega}_h \times \mathbf{n}]] = 0,$	$[[\hat{p}_h \mathbf{n}]] = 0$

- Local recovery from $\lambda \equiv (\lambda_t, \lambda_n)$?

Solving for $\omega_h, \mathbf{u}_h, p_h$ using the HDG discretization of

$$\left\{ \begin{array}{ll} \omega - \mathbf{curl} \mathbf{u} = 0 & \text{in } K, \\ \mathbf{curl} \omega + \mathbf{grad} p = \mathbf{f} & \text{in } K, \\ \mathbf{div} \mathbf{u} = 0 & \text{in } K, \\ (\mathbf{u})_t = \lambda_t & \text{on } \partial K, \\ (\mathbf{u})_n = \lambda_n & \text{on } \partial K. \end{array} \right.$$

is possible only if

$$\int_{\partial K} \lambda \cdot \mathbf{n} = 0 \quad \dots!$$

Type II:	Unknowns:	λ_t	λ_n
	Equations:	$[[\hat{\omega}_h \times \mathbf{n}]] = 0,$	$[[\hat{\rho}_h \mathbf{n}]] = 0$

- Revised local solver:

Solve for $\omega_h, \mathbf{u}_h, p_h$ using the HDG discretization of

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after solving a condensed system for $(\boldsymbol{\lambda}, \bar{\rho})$:

$$\begin{pmatrix} A_2 & B_2^t \\ B_2 & 0 \end{pmatrix} \begin{pmatrix} \boldsymbol{\lambda} \\ \bar{\rho} \end{pmatrix} = \text{r.h.s}$$

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- The solution $\boldsymbol{\lambda}$ gives the same numerical traces stated earlier.

- There is an HDG method for velocity-vorticity formulation of Stokes flow.
- While it may appear that there are four ways to hybridize, all four ways give the same global HDG method.
- Proof of error estimates is an open question, as of now.