

*Definition 1* (Conventions and notations in this course). The “base” inner product in a Hilbert space  $V$  (over  $\mathbb{C}$  or  $\mathbb{R}$ ) under consideration is denoted by  $(\cdot, \cdot)_V$ , or simply  $(\cdot, \cdot)$  when no confusion can arise. The corresponding norm is  $\|x\| = (x, x)^{1/2}$ . If  $V = \mathbb{C}^N$  or  $\mathbb{R}^N$ , then the base inner product is  $(x, y) = y^*x$ . The set of continuous linear operators from  $V$  to another Hilbert space  $W$  is denoted by  $\mathcal{L}(V, W)$ . When  $V = W$ , we abbreviate it to  $\mathcal{L}(V)$ , and denote its subset of bijective operators by  $\mathcal{B}(V)$ . An operator  $A \in \mathcal{L}(V)$  is **self adjoint** if  $(Ax, y) = (x, Ay)$  for all  $x, y \in V$ , and is **positive definite** if in addition  $(Ax, x) > 0$  for all  $0 \neq x \in V$ . A self adjoint and positive definite operator  $M$  in  $\mathcal{B}(V)$  defines another inner product  $(x, y)_M = (Mx, y)$  on  $V$  and a corresponding norm  $\|x\|_M = (x, x)_M^{1/2}$ . (Do not confuse the different meanings of  $(\cdot, \cdot)_S$  when  $S$  is a space and when  $S$  is an operator.)

**Theorem 2.** *If  $A \in \mathcal{B}(\mathbb{R}^N)$  is self adjoint and positive definite and  $e_n$  is the error in the  $n$ -th iterate of the steepest descent algorithm for solving  $Ax = b$ , then*

$$\|e_n\|_A \leq \left( \frac{\kappa(A) - 1}{\kappa(A) + 1} \right)^n \|e_0\|_A.$$

where  $\kappa(A) = \max \sigma(A) / \min \sigma(A)$ .

**Theorem 3.** *If  $A \in \mathcal{B}(\mathbb{R}^N)$  is self adjoint and positive definite and  $e_n$  is the error in the  $n$ -th iterate of the conjugate gradient algorithm for solving  $Ax = b$ , then*

$$\|e_n\|_A \leq 2 \left( \frac{\sqrt{\kappa(A)} - 1}{\sqrt{\kappa(A)} + 1} \right)^n \|e_0\|_A.$$

**Proposition 4.** *Suppose  $A \in \mathcal{L}(V)$  is bounded and self adjoint in  $(\cdot, \cdot)$ . Then its spectrum  $\sigma(A) \subseteq \mathbb{R}$  and both  $\inf \sigma(A)$  and  $\sup \sigma(A)$  are in  $\sigma(A)$ . Moreover, for any  $C_0, C_1 > 0$ , the following are equivalent statements:*

- (1)  $C_0(x, x) \leq (Ax, x) \leq C_1(x, x)$ , for all  $x \in V$ .
- (2)  $C_0 \leq \inf \sigma(A)$  and  $\sup \sigma(A) \leq C_1$ .

**Proposition 5.** *Suppose  $A, B \in \mathcal{B}(V)$  are self adjoint and positive definite in  $(\cdot, \cdot)$  and  $C_0, C_1 > 0$ . Then the following are equivalent statements:*

- (1) For all  $v \in V$ 

$$C_0(B^{-1}v, v) \leq (Av, v) \leq C_1(B^{-1}v, v).$$
- (2) For all  $v \in V$ ,
$$C_0(A^{-1}v, v) \leq (Bv, v) \leq C_1(A^{-1}v, v).$$
- (3) The spectrum of the product  $BA$  is real and satisfies

$$C_0 \leq \inf \sigma(BA) \quad \text{and} \quad \sup \sigma(BA) \leq C_1.$$

*Exercise 6.* Suppose  $A \in \mathcal{L}(V)$  is self adjoint and positive definite. Then  $A \in \mathcal{B}(V)$  if and only if there exists a  $C_0 > 0$  such that  $C_0(x, x) \leq (Ax, x)$  for all  $x \in V$ .

*Exercise 7.* Suppose  $A \in \mathcal{L}(V)$  is self adjoint in  $(\cdot, \cdot)$ . Define

$$\rho(A) = \sup_{\lambda \in \sigma(A)} |\lambda|, \quad \|A\| = \sup_{0 \neq x \in V} \frac{(Ax, Ax)^{1/2}}{(x, x)^{1/2}}, \quad r(A) = \sup_{0 \neq x \in V} \frac{|(Ax, x)|}{(x, x)}.$$

Prove that  $\rho(A) = \|A\| = r(A)$ .

*Definition 8.* Given  $x_0, b \in V$ , suppose a sequence  $x_n \in V$  is constructed by the one-step **iteration**

$$x_{n+1} = J(x_n, b) \tag{1}$$

using a continuous map  $J : V \times V \rightarrow V$ .

(1) If  $J$  is a linear map on the product space  $V \times V$ , i.e.,

$$J(\alpha x + \beta y, \alpha b + \beta d) = \alpha J(x, b) + \beta J(y, d)$$

then (1) is said to be a **linear iteration**.

(2) Iteration (1) is said to be **consistent** with the system  $Ax = b$  for some  $A \in \mathcal{L}(V)$  if  $x$  is a fixed point in the sense

$$x = J(x, b).$$

(3) Iteration (1) is **convergent** if  $x_n \rightarrow x$  in  $V$  as  $n \rightarrow \infty$ .

**Proposition 9.** Suppose  $A \in \mathcal{B}(V)$ ,  $b \in V$ , and  $x = A^{-1}b$ . For any linear iteration (1) the following are equivalent statements:

- (1) The iteration is consistent with  $Ax = b$ .
- (2) There is a linear operator  $E \in \mathcal{L}(V)$  such that the error  $e_n = x - x_n$  satisfies

$$e_{n+1} = Ee_n, \quad \forall n = 0, 1, \dots$$

(The operator  $E$  is called the **reducer** of the algorithm and  $Ez = J(z, 0)$ .)

(3) There is a linear operator  $B \in \mathcal{L}(V)$  such that

$$x_{n+1} = x_n + B(b - Ax_n), \quad \forall n = 0, 1, \dots \tag{2}$$

(The operator  $B$  is called the **iterator** and  $Bb = (I - E)A^{-1}b = J(0, b)$ .)

**Proposition 10** (Iterator as a preconditioner). Consider the iteration (2), suppose  $A$  and  $B$  are self adjoint in  $(\cdot, \cdot)$ . If  $A \in \mathcal{B}(V)$  is positive definite and

$$\eta = \|I - BA\|_A < 1,$$

then

- (1)  $B$  is positive definite,
- (2) the iteration (2) is convergent,
- (3) the condition number  $\kappa(BA) = \frac{\sup \sigma(BA)}{\inf \sigma(BA)}$  satisfies  $\kappa(BA) \leq \frac{1 + \eta}{1 - \eta}$ ,
- (4) the asymptotic convergence rate of the conjugate gradient method for  $Ax = b$  preconditioned by  $B$  is faster than the rate of convergence of (2).

*Definition 11.* Suppose  $A$  is self adjoint in  $(\cdot, \cdot)$ . If  $B$  is also self adjoint in the same inner product, then the iteration

$$u_{n+1} = u_n + B(b - Au_n), \quad \forall n = 0, 1, \dots \quad (3)$$

is called a **symmetric** iteration. When  $B \neq B^t$ , we often symmetrize the algorithm by revising it to compute  $u_{n+1}$  from  $u_n$  in these two steps:

$$u_{n+1/2} = u_n + B(b - Au_n) \quad (4a)$$

$$u_{n+1} = u_{n+1/2} + B^t(b - Au_{n+1/2}). \quad (4b)$$

These two steps define the **symmetrization** of (2).

**Proposition 12.** *Suppose  $A \in \mathcal{L}(V)$  is self adjoint. Then iteration (4) defines a consistent and symmetric linear iteration. Its self adjoint iterator is given by*

$$\bar{B} = B^t + B - B^t A B.$$

*If in addition  $A \in \mathcal{B}(V)$  is also positive definite, then the reducer satisfies these:*

- (1)  $\|I - \bar{B}A\|_A < 1 \iff \bar{B}$  is in  $\mathcal{B}(V)$  and is self adjoint and positive definite.
- (2)  $\rho(I - BA)^2 \leq \rho(I - \bar{B}A) = \|I - \bar{B}A\|_A = \|I - BA\|_A^2 = 1 - \inf \sigma(\bar{B}A)$ .

*Definition 13.* Recall that the Hilbert **adjoint** of  $A \in \mathcal{L}(V, W)$  is the operator  $A^t \in \mathcal{L}(W, V)$  satisfying  $(Av, w)_W = (v, A^t w)_V$  for all  $v \in V$  and  $w \in W$ . (This is related but not equal to the operator dual on Banach spaces.)

*Exercise 14.* Suppose  $X$  and  $Y$  are Hilbert and  $A \in \mathcal{L}(X, Y)$ . Prove that the following are equivalent statements:

- (1)  $A$  is surjective.
- (2)  $A^t$  is injective and  $\text{ran } A^t$  is closed.
- (3) There exists an  $\alpha > 0$  such that  $\|A^t y\|_X \geq \alpha \|y\|_Y$  for all  $y \in Y$ .

*Assumption 15.* Suppose  $V$  and  $\hat{V}$  are Hilbert spaces with inner products  $(\cdot, \cdot)_V$  and  $(\cdot, \cdot)_{\hat{V}}$ , resp. Assume that  $\hat{A} \in \mathcal{B}(\hat{V})$  is self adjoint and positive definite in  $(\cdot, \cdot)_{\hat{V}}$  and  $R \in \mathcal{L}(\hat{V}, V)$  is surjective.

*Definition 16.* In the setting of Assumption 15, the operator

$$B_2 = R\hat{A}^{-1}R^t \quad (5)$$

is called a **two-level** or **auxiliary space** preconditioner.

*Assumption 17.* Suppose  $\hat{A}$  and  $R$  are as in Assumption 15 and assume additionally that there is an  $A \in \mathcal{B}(V)$ , self adjoint and positive definite in  $(\cdot, \cdot)_V$ , and satisfying

$$(AR\hat{v}, R\hat{v})_V \leq C_R(\hat{A}\hat{v}, \hat{v})_{\hat{V}}, \quad \forall \hat{v} \in \hat{V}.$$

*Assumption 18.* Suppose  $\hat{A}$  and  $R$  are as in Assumption 15 and assume additionally that we have an operator  $S \in \mathcal{L}(V, \hat{V})$  such that  $RS = I$  (where  $I$  is the identity on  $V$ ) and

$$C_S(\hat{A}Sv, Sv)_{\hat{V}} \leq (Av, v)_V, \quad \forall v \in V$$

for some  $A \in \mathcal{B}(V)$  that is self adjoint and positive definite in  $(\cdot, \cdot)_V$ .

**Lemma 19.** *Suppose Assumption 15 holds. Then the two-level operator  $B_2$  in (5) is a bijection in  $\mathcal{B}(V)$  and the operator  $T = \hat{A}^{-1}R^t B_2^{-1} : V \rightarrow \hat{V}$  is a continuous right inverse of  $R$  (i.e.,  $RT = I$ ).*

**Lemma 20.** *Suppose Assumption 15 holds. Then, for all  $v \in V$ ,*

$$(B_2^{-1}v, v)_V = \inf_{\hat{v} \in R^{-1}\{v\}} (\hat{A}\hat{v}, \hat{v})_{\hat{V}}$$

where the set  $R^{-1}\{v\} = \{\hat{v} \in \hat{V} : R\hat{v} = v\}$ .

**Lemma 21.** *Assumptions 15 and 17 imply that the  $B_2$  in (5) satisfies*

$$(Av, v)_V \leq C_R(B_2^{-1}v, v)_V, \quad \forall v \in V.$$

**Lemma 22.** *Assumptions 15 and 18 imply that the  $B_2$  in (5) satisfies*

$$C_S(B_2^{-1}v, v)_V \leq (Av, v)_V \quad \forall v \in V.$$

**Theorem 23** (Fictitious space lemma of Nepomnyaschikh). *Suppose Assumptions 15, 17, and 18 hold. Then  $B_2 = R\hat{A}^{-1}R^t$  satisfies*

$$C_S(B_2^{-1}v, v)_V \leq (Av, v)_V \leq C_R(B_2^{-1}v, v)_V, \quad \forall v \in V,$$

and consequently  $\kappa(B_2A) \leq C_R/C_S$ .

*Example 24.* Use an enclosing fictitious domain to precondition the Neumann problem.

**Corollary 25.** *Suppose Assumptions 15 and 17 hold with  $V \subset \hat{V}$  and with  $R : \hat{V} \rightarrow V$  equal to a projection onto  $V$ . Then*

$$\sigma(B_2A) \subseteq [1, C_R].$$

*Assumption 26* (Subspace correction setting). Let  $A \in \mathcal{B}(V)$  be self adjoint and positive definite. Suppose  $V_i$ ,  $i = 1, \dots, J$ , are closed subspaces of the Hilbert space  $\{V, (\cdot, \cdot)\}$  and suppose  $A_i \in \mathcal{B}(V_i)$ .

*Definition 27.* In setting of Assumption 26, let  $Q_i : V \rightarrow V_i$  denote the  $(\cdot, \cdot)$ -orthogonal projection onto  $V_i$ . The operator

$$B_a = \sum_{i=1}^J A_i^{-1} Q_i \tag{6}$$

is called the **additive preconditioner** based on subspaces  $V_i$  and operators  $A_i \in \mathcal{B}(V_i)$ .

*Algorithm 28* (Additive Schwarz Method/Parallel Subspace Correction). Given an approximation  $u_n \in V$  to  $u = A^{-1}f$ , compute  $u_{n+1}$  as follows:

- (1) Project the residual onto  $V_j$  and compute  $r_j = Q_j r = Q_j(f - Au_n)$ .
- (2) Find  $\varepsilon_j \in V_j$  by solving  $A_j \varepsilon_j = r_j$ .
- (3) Correct  $u_n$  on each subspace by  $u_{n+1} = u_n + \omega \sum_{i=1}^J \varepsilon_j$ ,

where  $\omega > 0$  is a ‘‘relaxation’’ parameter.

**Proposition 29.** *Suppose  $\Lambda_i$  are self adjoint. Then Algorithm 28 is a linear symmetric consistent iteration that can be rewritten as*

$$u_{n+1} = u_n + \omega B_a (f - Au_n) \quad (7)$$

whose iterator and reducer are given, respectively, by

$$\omega B_a = \omega \sum_{i=1}^J \Lambda_i^{-1} Q_i, \quad E = I - \omega B_a A = I - \omega \left( \sum_{j=1}^J T_j \right), \quad \text{where } T_j = \Lambda_j^{-1} Q_j A.$$

*Algorithm 30* (Multiplicative Schwarz Method/Successive Subspace Correction). Given an approximation  $u_n \in V$  to  $u = A^{-1}f$ , compute  $u_{n+1}$  as follows:

- (1) Set  $u_n^{(0)} = u_n$ .
- (2) For  $j = 1, \dots, J$  do:
  - (a) Solve for  $\varepsilon_j \in V_j$  satisfying  $\Lambda_j \varepsilon_j = Q_j (f - Au_n^{(j-1)})$ .
  - (b) Compute  $u_n^{(j)} = u_n^{(j-1)} + \varepsilon_j$ .
- (3) Set  $u_{n+1} = u_n^{(J)}$ .

**Proposition 31.** *Algorithm 30 is a linear consistent iteration that can be rewritten as*

$$u_{n+1} = u_n + B_m (f - Au_n),$$

whose iterator and reducer are given by

$$B_m = (I - E)A^{-1}, \quad E = (I - T_J)(I - T_{J-1}) \cdots (I - T_1). \quad (8)$$

*Definition 32.*  $B_m$  is called the **multiplicative preconditioner** based on subspaces  $V_i$  and operators  $\Lambda_i \in \mathcal{B}(V_i)$ . Also define

$$\bar{B}_m = B_m^t + B_m - B_m^t A B_m, \quad A_{ij} = Q_i A I_j, \quad M_j = \Lambda_j^t + \Lambda_j - A_{jj},$$

where  $I_j : V_j \rightarrow V$  denotes the natural embedding.

*Assumption 33.* In the subspace correction setting of Assumption 26, assume further that  $\hat{V} = V_1 \times V_2 \times \cdots \times V_J$  with inner product  $(\hat{v}, \hat{w})_{\hat{V}} = \sum_{j=1}^J ([\hat{v}]_j, [\hat{w}]_j)_V$  and set  $R : \hat{V} \rightarrow V$  by  $R\hat{v} = \sum_{j=1}^J [\hat{v}]_j$ . Write elements of  $\hat{V}$  as column vectors of its  $V_j$ -components and write an operator on  $\hat{V}$  as a matrix of operators on the component spaces, e.g.,

$$\begin{bmatrix} [\hat{v}]_1 \\ \vdots \\ [\hat{v}]_J \end{bmatrix} \equiv \hat{v} \in \hat{V}, \quad R = [I_1 \quad I_2 \quad \cdots \quad I_J], \quad R^t = \begin{bmatrix} Q_1 \\ \vdots \\ Q_J \end{bmatrix}.$$

Continuing in such notations of matrices of operators, set

$$\mathbb{A} = \begin{bmatrix} A_{11} & A_{12} & \cdots & A_{1J} \\ A_{21} & A_{2,2} & & A_{2J} \\ \vdots & & \ddots & \vdots \\ A_{J1} & \cdots & A_{J,J-1} & A_{JJ} \end{bmatrix}, \quad \mathbb{L} = \begin{bmatrix} 0 & 0 & \cdots & 0 \\ A_{21} & 0 & & \vdots \\ \vdots & \ddots & \ddots & 0 \\ A_{J1} & \cdots & A_{J,J-1} & 0 \end{bmatrix}, \quad \mathbb{D} = \begin{bmatrix} A_{11} & 0 & \cdots & 0 \\ 0 & A_{22} & \cdots & 0 \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & A_{JJ} \end{bmatrix},$$

$$\mathbb{A} = \text{diag}(A_1, \dots, A_J), \quad \mathbb{B}_a = \mathbb{A}^{-1}, \quad \mathbb{B}_m = (\mathbb{A} + \mathbb{L})^{-1},$$

$$\bar{\mathbb{B}}_m = \mathbb{B}^t + \mathbb{B} - \mathbb{B}^t \mathbb{A} \mathbb{B}, \quad \mathbb{M} = \mathbb{A}^t + \mathbb{A} - \mathbb{D}, \quad \mathbb{U} = (\mathbb{A} + \mathbb{L})^t.$$

**Lemma 34** ( $B_m$  and  $B_a$  take the form of  $B_2$ ). *Suppose Assumptions 26 and 33 hold. Then  $\mathbb{A} = R^t A R$  is self adjoint in  $(\cdot, \cdot)_{\hat{V}}$  and the following identities hold:*

$$\begin{aligned} B_a &= R \mathbb{B}_a R^t \\ B_m &= R \mathbb{B}_m R^t \\ \bar{B}_m &= R \bar{\mathbb{B}}_m R^t. \end{aligned}$$

*Example 35.* The classical Jacobi and Gauss-Seidel iteration for a symmetric positive definite matrix fits Algorithm 28 with  $V = \mathbb{R}^N$  and  $V_i = \text{Span}(e_i)$ .

**Lemma 36.** *Suppose  $\sum_{j=1}^J V_j$  is dense in  $V$  and  $\Lambda_i$  are self adjoint and positive definite. Then the following are equivalent:*

(1) *The sum of the subspaces is closed, i.e.,*

$$V = \sum_{j=1}^J V_j. \quad (9)$$

(2)  *$B_a$  is a bijection on  $V$ .*

**Theorem 37.** *Suppose  $\Lambda_i$  are self adjoint and positive definite, Assumption 26 and (9) hold. Then*

$$(B_a^{-1}v, v) = \inf_{\{\sum_{i=1}^J v_i = v\}} \sum_{i=1}^J (\Lambda_i v_i, v_i),$$

where the infimum is taken over all decompositions of form  $v = v_1 + v_2 + \dots + v_J$  with  $v_i \in V_i$ .

*Assumption 38.* Suppose Assumption 26 holds and

$$\|I - \Lambda_i^{-1} A_{ii}\|_{A_{ii}} < 1, \quad \forall i = 1, \dots, J.$$

**Lemma 39.** *Suppose Assumptions 26, 33, 38 and (9) hold. Then  $\bar{\mathbb{B}}_m$  and  $\mathbb{M}$  are bijections on  $\hat{V}$  and the following identities hold:*

$$\begin{aligned} \bar{\mathbb{B}}_m^{-1} &= \mathbb{U}^t \mathbb{M}^{-1} \mathbb{U}, \\ \bar{\mathbb{B}}_m^{-1} &= \mathbb{A} + (\mathbb{L}^t + \mathbb{D} - \mathbb{A})^t \mathbb{M}^{-1} (\mathbb{L}^t + \mathbb{D} - \mathbb{A}). \end{aligned}$$

**Theorem 40.** *Suppose Assumptions 26, 38 and (9) hold. Then  $\bar{B}_m$  is a self adjoint and positive definite operator in  $\mathcal{B}(V)$ , and for all  $v \in V$ ,*

$$(\bar{B}_m^{-1}v, v) = \inf_{\{\sum_{i=1}^J v_i = v\}} \sum_{i=1}^J \left\| \Lambda_i^t v_i + Q_i A \sum_{j=i+1}^J v_j \right\|_{M_i^{-1}}^2 = \|v\|_A^2 + \inf_{\{\sum_{i=1}^J v_i = v\}} \sum_{i=1}^J \left\| Q_i A \left( \sum_{j=i}^J v_j \right) - \Lambda_i v_i \right\|_{M_i^{-1}}^2$$

where the infimum is taken over all decompositions of form  $v = v_1 + v_2 + \dots + v_J$  with  $v_i \in V_i$ .

**Corollary 41** (XZ identity). *Suppose Assumptions 26, 38 and (9) hold. Then*

$$\|(I - T_J) \cdots (I - T_2)(I - T_1)\|_A^2 = 1 - \frac{1}{1 + c_0}$$

where

$$c_0 = \sup_{\|v\|_A=1} \inf_{\{\sum_{i=1}^J v_i = v\}} \sum_{i=1}^J \left\| Q_i A \left( \sum_{j=i}^J v_j \right) - \Lambda_i v_i \right\|_{M_i^{-1}}^2.$$

*Definition 42.* Let  $P_i : V \rightarrow V_i$  be the  $A$ -orthogonal projector defined by

$$(P_i v, w_i)_A = (v, w_i)_A, \quad \forall w_i \in V_i$$

for any self adjoint and positive definite  $A$ . Note that  $A_{ii}P_i = Q_i A$ .

**Corollary 43** (XZ identity for  $A$ -orthogonal projectors of a subspace decomposition). *Suppose  $V_i$ ,  $i = 1, \dots, J$ , are closed subspaces of the Hilbert space  $V$  satisfying (9) and  $A$  is a self adjoint and positive definite operator in  $\mathcal{B}(V)$ . Then*

$$\|(I - P_J) \cdots (I - P_2)(I - P_1)\|_A^2 = 1 - \frac{1}{1 + c_1} \quad (10)$$

where

$$c_1 = \sup_{\|v\|_A=1} \inf_{\{\sum_{i=1}^J v_i=v\}} \sum_{i=1}^J \left\| P_i \left( \sum_{j=i+1}^J v_j \right) \right\|_A^2.$$

*Definition 44.* In the setting of Assumption 26, define

$$\mathcal{J} = \left[ \sum_{i=1}^J P_i \right] A^{-1}, \quad \mathcal{G} = \left[ I - (I - P_J) \cdots (I - P_2)(I - P_1) \right] A^{-1}.$$

Note that  $\mathcal{J}$  and  $\mathcal{G}$  coincides with  $B_a$  and  $B_m$ , respectively, if we set  $\Lambda_i = A_{ii}$  for all  $i$ .

*Condition 45 (Strengthened Cauchy Schwarz inequality).*  $\beta > 0$  is a number such that for all  $v_i$  and  $w_i$  in  $V_i$ ,

$$\sum_{i=1}^J \sum_{j=1}^J |(w_i, v_j)_A| \leq \beta^{1/2} \left( \sum_{i=1}^J \|w_i\|_A^2 \right)^{1/2} \left( \sum_{j=1}^J \|v_j\|_A^2 \right)^{1/2}.$$

**Lemma 46.** *In the subspace correction setting of Assumption 26,*

$$\begin{aligned} \text{Condition 45} &\implies \sum_{i=1}^J \left\| P_i \left( \sum_{i=1}^J v_j \right) \right\|_A^2 \leq \beta \sum_{i=1}^J \|v_i\|_A^2, & \forall v_i \in V_i, \\ &\implies (\bar{\mathcal{G}}^{-1} v, v) \leq \beta (\mathcal{J}^{-1} v, v), & \forall v \in V, \end{aligned}$$

which also implies  $(\mathcal{J} A v, v)_A \leq \beta (\bar{\mathcal{G}} A v, v)_A$  for all  $v \in V$ . Here  $\bar{\mathcal{G}} = \mathcal{G}^t + \mathcal{G} - \mathcal{G}^t A \mathcal{G}$ .

*Condition 47 (Stable Decomposition).*  $\exists \alpha > 0$  such that  $\forall v \in V$ , a decomposition

$$v = \sum_{i=1}^J v_i, \quad \text{with } v_i \in V_i,$$

exists and satisfies

$$\sum_{i=1}^J \|v_i\|_A^2 \leq \alpha \|v\|_A^2.$$

**Theorem 48.** *In the subspace correction setting of Assumption 26, if Conditions 45 and 47 are verified, then*

$$\alpha^{-1}(v, v)_A \leq (\mathcal{J} A v, v)_A \leq \beta^{1/2}(v, v)_A,$$

or equivalently

$$\beta^{-1/2}(A v, v) \leq \mathcal{J}^{-1} v, v \leq \alpha(A v, v),$$

for all  $v \in V$ .

*Exercise 49* (Case of  $\Lambda_i \neq A_{ii}$ ). Suppose  $\beta_1 > 0$  is a number such that for all  $v_i$  and  $w_i$  in  $V_i$ ,

$$\sum_{i=1}^J \sum_{j=1}^J |(w_i, v_j)_A| \leq \beta_1^{1/2} \left( \sum_{i=1}^J \|w_i\|_{\Lambda_i}^2 \right)^{1/2} \left( \sum_{j=1}^J \|v_j\|_{\Lambda_j}^2 \right)^{1/2}. \quad (11)$$

and suppose  $\exists \alpha_1 > 0$  such that  $\forall v \in V$ , a decomposition  $v = \sum_{i=1}^J v_i$  with  $v_i \in V_i$  exists and satisfies

$$\sum_{i=1}^J \|v_i\|_{\Lambda_i}^2 \leq \alpha_1 \|v\|_A^2. \quad (12)$$

Then show that

$$\beta_1^{-1/2} (Av, v) \leq (B_a^{-1}v, v) \leq \alpha_1 (Av, v), \quad \forall v \in V. \quad (13)$$

**Theorem 50.** *In the subspace correction setting of Assumption 26, if Conditions 45 and 47 are verified, then*

$$\|I - \mathcal{G}A\|_A^2 \leq 1 - \frac{1}{1 + \alpha\beta},$$

and moreover, for the Jacobi case, setting relaxation parameter  $\omega$  such that  $0 < \omega < 2/\beta^{1/2}$ ,

$$\sigma(I - \omega \mathcal{J}A) \subseteq [-\theta, \gamma] \subseteq (-1, 1)$$

where  $-\theta \equiv 1 - \omega\beta^{1/2} \leq \gamma \equiv 1 - (\omega/\alpha)$ .

*Assumption 51* (A setting using Lagrange finite elements). Set  $V =$  Lagrange finite element subspace of  $H_0^1(\Omega)$ , of order  $p \geq 1$ , on a simplicial quasiuniform mesh  $\mathcal{T}_h$  (of mesh size  $h$ ) subdividing a domain  $\Omega \subseteq \mathbb{R}^d$ , and

$$(u, v)_V = \int_{\Omega} uv, \quad (Au, v) = \int_{\Omega} \text{grad } u \cdot \text{grad } v \quad (14)$$

for all  $u, v \in V$ . Let  $\{\Omega_i : i = 1, \dots, J\}$  be a finite cover of  $\Omega$  such that each  $\bar{\Omega}_i$  is a union of elements of  $\mathcal{T}_h$ . Assume that there is a  $W_{\infty}^1$  partition of unity  $\{\theta_i\}$  subordinate to the covering and suppose  $\Theta > 0$  is a number satisfying  $\|\text{grad } \theta_i\|_{L^{\infty}(\Omega)} \leq \Theta$  for all  $i = 1, 2, \dots, J$ . Assume that the cover has the **limited overlap property**: there is an integer  $r$  such that each point of  $\Omega$  is contained in no more than  $r$  of the sets  $\Omega_i$ . Set

$$V_i = \{v \in V : \text{supp}(v) \subseteq \Omega_i\}, \quad i = 1, 2, \dots, J. \quad (15)$$

**Theorem 52.** *Assumption 51  $\implies$*

- (1) *Condition 45 holds with  $\beta = r^2$ ,*
- (2) *Condition 47 also holds:  $\exists C > 0$  independent of  $h$  such that  $\forall v \in V$ , there is a decomposition  $v = \sum_{i=1}^J v_i$  with  $v_i \in V_i$  and*

$$\sum_{i=1}^J \|v_i\|_A^2 \leq Cr (\Theta^2 \|v\|^2 + \|v\|_A^2).$$

*Exercise 53.* For the  $A$  and  $V$  set in Assumption 51, prove that there is a mesh-independent constant  $C > 0$  such that  $\rho(A) \leq Ch^{-2}$ .



*Example 54.* Block Gauss-Seidel and Jacobi iterations with the overlapping blocks obtained when  $\Omega_i$  is set to vertex patches.

*Definition 55* (Real method of interpolation). If  $X_0$  and  $X_1$  are normed linear space are subspaces of a larger linear space, then  $X \equiv [X_0, X_1]$  is called a **compatible pair** of spaces. If  $Y \equiv [Y_0, Y_1]$  is also a compatible pair, then two bounded linear operators  $L_i \in \mathcal{L}(X_i, Y_i)$ ,  $i = 0, 1$ , are called a pair of **compatible operators** whenever

$$L_0u = L_1u \quad \forall u \in X_0 \cap X_1.$$

The  **$K$ -functional** (of Peetre) for the compatible pair  $X$  is defined by

$$K(t, u) = \inf_{u_0+u_1=u} \left( \|u_0\|_{X_0}^2 + t^2 \|u_1\|_{X_1}^2 \right)^{1/2}, \quad \forall u \in X_0 + X_1, \forall t > 0.$$

Define, for  $0 < s < 1$ ,

$$\|u\|_{X_s} = \left( 2s(1-s) \int_0^\infty t^{-2s} K(t, u)^2 \frac{dt}{t} \right)^{1/2}$$

and define the **interpolation space**  $X_s \equiv [X_0, X_1]_s \equiv \{u \in X_0 + X_1 : \|u\|_{X_s} < \infty\}$ .

**Theorem 56.** *If  $[X_0, X_1]$  is a compatible pair, then for all  $0 < s < 1$ ,*

$$X_0 \cap X_1 \hookrightarrow X_s \hookrightarrow X_0 + X_1,$$

and moreover:

$$\begin{aligned} \|u\|_{X_s} &\leq \|u\|_{X_0}^{1-s} \|u\|_{X_1}^s \leq \|u\|_{X_0 \cap X_1} & \forall u \in X_0 \cap X_1, \\ K(t, u) &\leq t^s \|u\|_{X_s} & \forall u \in X_s, \\ \|u\|_{X_0+X_1} &\leq \|u\|_{X_s} & \forall u \in X_s. \end{aligned}$$

**Theorem 57** (Interpolation of operators). *Suppose  $[X_0, X_1]$ ,  $[Y_0, Y_1]$  and  $L_i \in \mathcal{L}(X_i, Y_i)$ ,  $i = 0, 1$ , are compatible. Then, for all  $0 < s < 1$ ,  $\exists!$  linear operator  $L_s \in \mathcal{L}(X_s, Y_s)$  satisfying*

$$L_s u = L_0 u = L_1 u \quad \forall u \in X_0 \cap X_1.$$

Moreover, if  $C_i > 0$  are such that

$$\|L_i u\|_{Y_i} \leq C_i \|u\|_{X_i}, \quad i = 0, 1,$$

then

$$\|L_s u\|_{Y_s} \leq C_0^{1-s} C_1^s \|u\|_{X_s}, \quad \forall u \in X_s.$$

**Fact 58.** *On any nonempty open  $\Omega \subseteq \mathbb{R}^d$ ,  $d \geq 1$ , for all  $s_0, s_1 \in \mathbb{R}$ ,*

$$[H^{s_0}(\Omega), H^{s_1}(\Omega)]_s = H^\sigma(\Omega)$$

where  $0 < s < 1$  and  $\sigma = (1-s)s_0 + ss_1$ .

*Example 59.* The error in  $L^2(\Omega)$  projection of functions in  $H^s(\Omega)$  into the Lagrange finite element space.

**Lemma 60.** Let  $K_{02}(t, u)$  denote the  $K$ -functional for the compatible pair  $[L^2(\mathbb{R}^d), H^2(\mathbb{R}^d)]$ . Then,  $\forall \eta > 0, \eta \neq 1, \exists C > 0$  such that

$$\sum_{\ell=-\infty}^{\infty} \eta^{-\ell} K_{02}(\eta^\ell, u)^2 \leq C \|u\|_{H^1(\mathbb{R}^d)}^2, \quad \forall u \in H^1(\mathbb{R}^d).$$

The same result holds if  $\mathbb{R}^d$  is replaced by a bounded open  $\Omega \subset \mathbb{R}^d$  with Lipschitz boundary.

**Lemma 61** (Stability of the  $L^2$  projection in  $H^1$ ). Suppose  $V$  is the Lagrange finite element subspace of  $H_0^1(\Omega)$ , of order  $p \geq 1$  on a quasiuniform mesh  $\mathcal{T}_h$  (of mesh size  $h$ ) subdividing a domain  $\Omega \subset \mathbb{R}^d$ . Let  $Q_h : L^2(\Omega) \rightarrow V$  denote the  $L^2(\Omega)$  orthogonal projector into  $V$ . Then there is a  $C > 0$  independent of  $h$  such that

$$\|v - Q_h v\|_{L^2(\Omega)} + h \|Q_h v\|_{H^1(\Omega)} \leq Ch \|v\|_{H^1(\Omega)}, \quad \forall v \in H^1(\Omega).$$

**Lemma 62** (Elliptic projection under full regularity). Suppose, in addition to the assumptions of Lemma 61, that  $\Omega$  is convex. Let  $P_h : H^1(\Omega) \rightarrow V$  denote the orthogonal projector in the  $(A, \cdot)$  inner product set in (14). Then there is a  $C > 0$  independent of  $h$  such that

$$\|v - P_h v\|_{L^2(\Omega)} + h \|P_h v\|_{H^1(\Omega)} \leq Ch \|v\|_{H^1(\Omega)}, \quad \forall v \in H^1(\Omega).$$

*Assumption 63* (A setting for Overlapping Schwarz Methods). Suppose  $\Omega$  is subdivided by a simplicial quasiuniform ‘‘coarse’’ mesh  $\mathcal{T}_H$  (of mesh size  $H$ ) with  $J$  elements  $K_j$ , as well as by a simplicial quasiuniform ‘‘fine’’ mesh  $\mathcal{T}_h$  that is a refinement of  $\mathcal{T}_H$  (so  $h \ll H$ ). For each coarse element  $K_j$ , set  $\Omega_j$  to be the domain formed by  $K_j$  and all its neighboring elements, i.e.,  $\bar{\Omega}_j = \bigcup \{K \in \mathcal{T}_H : K \cap K_j \text{ is nonempty}\}$ . Set  $V =$  Lagrange finite element space of order  $p$  on  $\mathcal{T}_h$ , set  $(\cdot, \cdot), (A, \cdot)$  by (14) and set  $V_i$  by (15) for all  $i = 1, \dots, J$ . In addition, we now also set a **coarse space**  $V_{J+1}$  to be the Lagrange finite element space of order  $p$  on the coarse mesh  $\mathcal{T}_H$ .

*Definition 64.* For the subspace decomposition including the coarse space,

$$V = V_1 + V_2 + \dots + V_J + V_{J+1},$$

define the additive and multiplicative overlapping Schwarz preconditioners by

$$B_a^{\text{os}} = \left[ \sum_{i=1}^{J+1} P_i \right] A^{-1}, \quad B_m^{\text{os}} = \left[ I - (I - P_{J+1})(I - P_J) \dots (I - P_2)(I - P_1) \right] A^{-1}.$$

**Theorem 65** (Uniform preconditioning & convergence of Overlapping Schwarz method). *Assumption 63*  $\implies \exists C_1, C_2 > 0$  independent of  $H$  and  $h$  such that

$$\begin{aligned} \kappa(B_a^{\text{os}} A) &\leq C_1, \\ \|I - B_m^{\text{os}} A\|_A^2 &\leq 1 - \frac{1}{C_2}. \end{aligned}$$

*Assumption 66* (General geometric multilevel setting). Suppose  $A \in \mathcal{B}(V)$  be self adjoint and positive definite and suppose we have a nested sequence of closed subspaces

$$V_1 \subset V_2 \subset \dots \subset V_L \equiv V.$$

Furthermore, suppose each  $V_k$  has closed subspaces  $V_{k,i}$  such that

$$V_k = \sum_{i=1}^{J_k} V_{k,i}. \quad (16)$$

*Definition 67.* The decomposition (16) of  $V_k$  is often called a **micro decomposition** of a multilevel space, while the sum

$$V = V_1 + V_2 + \cdots + V_L \quad (17)$$

is called a **macro decomposition**. Let  $Q_k$  and  $Q_{k,i}$  be the  $(\cdot, \cdot)$ -projections into  $V_k$  and  $V_{k,i}$ , respectively. Let  $P_k$  and  $P_{k,i}$  be  $(\cdot, \cdot)_A$ -projection into  $V_k$  and  $V_{k,i}$ , respectively. Let  $A_k \in \mathcal{B}(V_k)$  be defined by  $(A_k v, w) = (v, w)_A$  for all  $w \in V_k$  and similarly let  $A_{k,i} \in \mathcal{B}(V_{k,i})$  be defined by  $(A_{k,i} v, w) = (v, w)_A$  for all  $w \in V_{k,i}$ . The **BPX preconditioner** (also known as the additive multigrid preconditioner) based on the **full multilevel subspace decomposition**

$$V = \sum_{k=1}^L \sum_{i=1}^{J_k} V_{k,i}, \quad (18)$$

is defined by

$$B_{\text{BPX}} = \left[ \sum_{k=1}^L \sum_{i=1}^{J_k} P_{k,i} \right] A^{-1} = \sum_{k=1}^L \sum_{i=1}^{J_k} A_{k,i}^{-1} Q_{k,i}.$$

It is the same as the additive preconditioner  $B_a$  (see (6) and Algorithm 28) obtained by setting the subspaces  $\{V_i\}$  to  $\{V_{k,i}\}$  and operators  $\{A_i\}$  to  $\{A_{k,i}\}$ .

*Algorithm 68* (The `\cycle`:  $u_{n+1} = \text{Slash}_L(u_n, f)$ ). We define the map  $\text{Slash}_k : V_k \times V_k \rightarrow V_k$  for all  $1 \leq k \leq L$ , inductively, namely  $w = \text{Slash}_k(v, g)$  is set as follows:

- (1) If  $k = 1$ , set  $w = A_1^{-1}g$ .
- (2) If  $k > 1$ , set  $w = \text{Slash}_k(v, g)$  recursively using  $\text{Slash}_{k-1}(\cdot, \cdot)$ , as follows:
  - (a) Set  $v^{(0)} = v$ .
  - (b) For  $i = 1, \dots, J_k$ , do:
    - (i)  $v^{(i)} = v^{(i-1)} + A_{k,i}^{-1}Q_{k,i}(g - Av^{(i-1)})$
  - (c) Set output  $w = v^{(J_k)} + \text{Slash}_{k-1}(0, Q_{k-1}(g - Av^{(J_k)}))$ .

*Exercise 69.* Show that  $u_{n+1} = \text{Slash}_L(u_n, f)$  can be written as  $u_{n+1} = u_n + B_{\text{cycle}}(f - Au_n)$  where  $B_{\text{cycle}}$  is the same as the multiplicative preconditioner  $B_m$  (see Algorithm 30 and (8)) obtained by setting the subspaces  $\{V_i\}$  to  $\{V_{k,i}\}$  and operators  $\{A_i\}$  to  $\{A_{k,i}\}$ .

*Assumption 70* (Multilevel Lagrange finite element setting). Suppose a bounded  $\Omega \subset \mathbb{R}^d$  is subdivided by a simplicial quasiuniform mesh  $\mathcal{T}_1$  (of meshsize  $h_1$ ). Suppose that  $\mathcal{T}_k$  (of meshsize  $h_k$ ) for  $1 < k \leq L$ , is obtained by a uniform refinement of  $\mathcal{T}_{k-1}$ . Set  $V_k$  to the linear ( $p = 1$ ) Lagrange finite element subspace of  $H_0^1(\Omega)$  on  $\mathcal{T}_k$ . Let  $\Omega_{k,i}$  denote the vertex patch composed of all elements of  $\mathcal{T}_k$  connected to  $i$ th vertex of  $\mathcal{T}_k$  and set  $V_{k,i} = \{v \in V_k : \text{supp}(v) \subseteq \Omega_{k,i}\}$ . Finally, set  $(\cdot, \cdot)$ ,  $(A \cdot, \cdot)$  by (14).

*Definition 71.* Let  $\mathcal{H} \in \mathcal{B}(V)$  be defined by

$$(\mathcal{H}^{-1}v, v) = \inf_{\sum_{k=1}^L v_k = v} \sum_{k=1}^L h_k^{-2}(v_k, v_k),$$

i.e.,  $\mathcal{H}$  is the same as the additive operator  $B_a$  (see Theorem 37) obtained using the macro decomposition (17) and setting  $\Lambda_k v = h_k^{-2}v$  for all  $v \in V_k$ .

**Lemma 72.** *Assumption 70*  $\implies$  There are  $L$ -independent constants  $C_1, C_2 > 0$  such that

$$C_1(\mathcal{H}^{-1}v, v) \leq (B_{\text{BPX}}^{-1}v, v) \leq C_2(\mathcal{H}^{-1}v, v) \quad \forall v \in V.$$

**Lemma 73.** *Assumption 70*  $\implies \exists C_1 > 0$ , and  $0 \leq \delta < 1$ , both independent of  $\{h_m\}$ , such that whenever  $k \leq l$ ,

$$(w_k, v_l)_A \leq C_1 \delta^{l-k} \|w_k\|_A (h_l^{-1} \|v_l\|), \quad \forall w_k \in V_k, \forall v_l \in V_l.$$

Hence, the condition (11) holds with  $\Lambda_k = h_k^{-2}I$  and an  $\{h_k\}$ -independent  $\beta_1$ .

**Lemma 74.** Suppose Assumption 70 holds and  $\partial\Omega$  is Lipschitz. If there is a  $C_\Pi > 0$  and linear operators  $\Pi_k : L^2(\Omega) \rightarrow V_k$  such that for all  $k$ ,

$$\|\Pi_k u\|_{L^2(\Omega)} \leq C_\Pi \|u\|_{L^2(\Omega)} \quad \forall u \in L^2(\Omega), \quad (19a)$$

$$\|(I - \Pi_k)v\|_{L^2(\Omega)} \leq C_\Pi h_k^2 \|v\|_{H^2(\Omega)} \quad \forall v \in H^2(\Omega), \quad (19b)$$

then there is a  $C > 0$ , depending only on  $C_\Pi$ ,  $\Omega$ , and  $h_1$ , such that

$$\sum_{k=2}^L h_k^{-2} \|(\Pi_k - \Pi_{k-1})v\|_{L^2(\Omega)}^2 \leq C \|v\|_{H^1(\Omega)}^2 \quad \forall v \in H^1(\Omega).$$

In particular, since  $Q_k$  satisfies (19), taking  $L \rightarrow \infty$ ,

$$\sum_{k=2}^{\infty} h_k^{-2} \|(Q_k - Q_{k-1})v\|_{L^2(\Omega)}^2 \leq C \|v\|_{H^1(\Omega)}^2 \quad \forall v \in H^1(\Omega).$$

Hence the condition (12) holds with  $\Lambda_k = h_k^{-2}I$  and an  $\{h_k\}$ -independent constant  $\alpha_1$ .

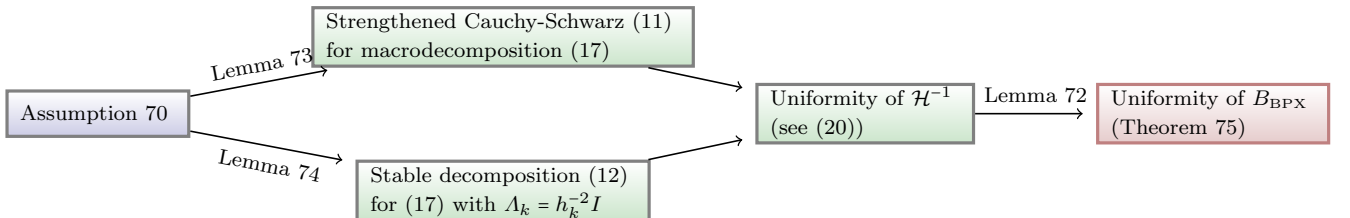
**Theorem 75** (Uniformity of BPX preconditioner). *In the setting of Assumption 70, additionally assume that  $\partial\Omega$  is Lipschitz. Then (applying Exercise 49), there are  $L$ -independent positive constants  $\alpha_1$  and  $\beta_1$  such that*

$$\beta_1^{-1/2}(Av, v) \leq (\mathcal{H}^{-1}v, v) \leq \alpha_1(Av, v), \quad \forall v \in V. \quad (20)$$

Hence  $\exists C_1 > 0$  independent of  $L$  such

$$\kappa(B_{\text{BPX}}A) \leq C_1.$$

*Remark 76.* Chain of arguments in regularity-free multigrid theory:



**Lemma 77.** *Assumption 70  $\implies \exists C > 0$ , depending only on the  $C_1$  and  $\delta$  in Lemma 73, such that*

$$\sum_{k=1}^L \|(P_k - Q_k)v\|_A^2 \leq C \sum_{k=1}^L h_k^{-2} \|(Q_k - Q_{k-1})v\|^2$$

**Theorem 78** (Uniform convergence of \(\backslash\text{cycle}\)). *In the setting of Assumption 70, additionally assume that  $\partial\Omega$  is Lipschitz. Then the  $c_1$  in the XZ identity (10) for the subspace decomposition (18) is bounded independent of  $L$  and hence*

$$\|I - B_{\backslash\text{cycle}}A\|_A^2 \leq 1 - \frac{1}{1 + c_1}.$$

*Remark 79.* Ingredients in the proof of Theorem 78:



*Algorithm 80* (The **Vcycle**:  $u_{n+1} = \text{Vcycle}_L(u_n, f)$ ). Given “smoothers”  $S_k \in \mathcal{L}(V_k)$ , for all  $1 \leq k \leq L$ , we define the map  $\text{Vcycle}_k : V_k \times V_k \rightarrow V_k$  inductively. Set  $w = \text{Vcycle}_k(v, g)$  as follows:

- (1) If  $k = 1$ , set  $w = A_1^{-1}g$ .
- (2) If  $k > 1$ , set  $w = \text{Vcycle}_k(v, g)$  recursively:
  - (a) Pre-smoothing step:  $v' = v + S_k(g - A_k v)$ .
  - (b) Coarse correction:  $v'' = v' + \text{Vcycle}_{k-1}(0, Q_{k-1}(g - Av'))$ .
  - (c) Post-smoothing step:  $w = v'' + S_k^t(g - A_k v'')$ .

*Exercise 81.* Show that the symmetrization (see Definition 11) of  $u_{n+1} = \text{Slash}_L(u_n, f)$  is the Vcycle algorithm with  $S_k$  set to  $\mathcal{G}$  at each  $V_k$ .

**Proposition 82.** *Algorithm 80 is a consistent linear iteration whose reducer  $E \equiv E_L$  is given recursively by  $E_1 = 0$  and*

$$E_k = K_k^*(I - P_{k-1} + E_{k-1}P_{k-1})K_k, \quad \forall k > 1,$$

where  $K_k = I - S_k A_k$  and  $K_k^*$  is the  $(\cdot, \cdot)_A$ -adjoint of  $K_k$ .

*Condition 83* (Regularity & Approximation Property).  $\exists \alpha_0 > 0$  such that for all  $k \geq 1$  and for all  $u \in V_k$ ,

$$\|(I - P_{k-1})K_k u\|_A^2 \leq \alpha_0 (\|u\|_A^2 - \|K_k u\|_A^2).$$

*Remark 84.* Condition 83 quantifies the following folkloric prerequisite for V-cycle to work: Errors undamped by smoothing at any refinement level must be well representable at the next coarser level. Interpret

$$\| \underbrace{(I - P_{k-1})K_k e}_{\substack{V_k\text{-component of error} \\ \text{after smoothing by } K_k}} \|_A^2 \leq \alpha_0 \left( \underbrace{\|e\|_A^2 - \|K_k e\|_A^2}_{\substack{\text{quantifies damping of} \\ \text{error } e \text{ by } K_k}} \right).$$

Clearly, if  $\|e\|_A \approx \|K_k e\|$  (i.e., if  $e$  is left undamped), then the above implies that  $K_k e$  must almost be in  $V_{k-1}$ . Condition 83 is usually verified using regularity estimates.

**Theorem 85.** *In the geometric multilevel setting of Assumption 66, Condition 83 implies*

$$0 \leq (E_k v, v)_A \leq \delta (v, v)_A, \quad \forall v \in V_k,$$

$$\text{with } \delta = \frac{\alpha_0}{1 + \alpha_0}.$$

**Lemma 86.** *Suppose  $V_k$  is finite dimensional and suppose there are constants  $0 \leq \theta < 1$  and  $C_1 > 0$  such that  $S_k$  satisfies these properties for all  $k$ :*

$$S_k \text{ is self adjoint in } (\cdot, \cdot), \quad (21a)$$

$$\sigma(I - S_k A_k) \subseteq [-\theta, 1), \quad (21b)$$

$$(S_k^{-1} e, e) \leq C_1 (Ae, e), \quad \forall e \in (I - P_{k-1})V_k. \quad (21c)$$

*Then, Condition 83 holds with  $\alpha_0 = C_1 \max(1, \theta^2/(1 - \theta))$ . (Note that (21a) and (21b) imply that  $S_k$  is a bijection, so  $S_k^{-1}$  makes sense in (21c).)*

**Lemma 87.** *Suppose there is a  $C_1 > 0$  such that  $S_k$  satisfies these properties for all  $k$ :*

$$\|I - S_k A_k\|_A < 1, \quad (22a)$$

$$(\bar{S}_k^{-1} e, e) \leq C_1 (Ae, e), \quad \forall e \in (I - P_{k-1})V_k, \quad (22b)$$

*where  $\bar{S}_k = S_k + S_k^t - S_k^t A_k S_k$  (which is a bijection by Proposition 12). Then Condition 83 holds with  $\alpha_0 = C_1$ .*

**Definition 88.** In the setting of Assumption 70 define the Gauss-Seidel smoother

$$\mathcal{G}_k = \left[ I - (I - P_{k, J_k}) \cdots (I - P_{k, 1}) (I - P_{k, 1}) \right] A_k^{-1}$$

and the Jacobi smoother

$$\mathcal{J}_k = \left[ \sum_{i=1}^{J_k} P_{k, i} \right] A_k^{-1}.$$

**Theorem 89** (Braess-Hackbusch). *Suppose Assumption 70 holds and suppose  $\Omega \subset \mathbb{R}^d$  is convex. Set  $S_k$  in the Vcycle (Algorithm 80) to be either the Gauss-Seidel smoother  $\mathcal{G}_k$  or the damped Jacobi smoother  $\omega \mathcal{J}_k$  with  $0 < \omega < 2/(d + 1)$ . Then there is a  $0 < \delta < 1$  independent of  $L$  such that*

$$0 \leq (E_k v, v)_A \leq \delta (v, v)_A, \quad \forall v \in V_k,$$

*so the Vcycle converges at a rate independent of number of refinements.*

**Remark 90.** Chain of arguments in regularity-based multigrid theory:

