

1.3 Limits of Accuracy

(eg. linear/quadratic converge)

Goals of "Numerical Analysis": ① Efficiency (i.e. quickly) compute an answer (eg: solve: $x^2+x+1=0$); ② Find answer within a specified level of accuracy.

Recall: $|x_a - r| = \text{Error}$ AND $\frac{|x_a - r|}{|r|} = \text{relative error}$
Approx. sol. True solution

Definition: Assume that f is a function with root r , so that: $f(r)=0$, and x_a is an approximate solution of $f(x)=0$, (so $r \approx x_a$). For the root-finding problem, Re (Backward error) of the approximation x_a is $|f(x_a)|$ and Fe (forward error) is $|r - x_a|$.

Q: why "backward"/"forward"?

Process of root-finding:



↑ "Backward" error refers to error in equation/problem.
 $|f(x_a)|$

↑ "Forward" error refers to error post-algorithm.
 $|x_a - r|$

EX. Let $f(x) = \sin x - x$; Find the **FE** (forward error) & **BE** (backward error) for $|x_c| = .001$.

$$FE = |r - x_a| = 10^{-3} \quad (r=0)$$

$$BE = |f(x_a)| = |\sin(.001) - (.001)| \approx \underline{1.6667 \times 10^{-10}}$$

Note That The Magnitudes of FE & BE can vary dramatically, as the previous example illustrates.

Recall That in Computational Mathematics, "stopping criteria" provide a set of conditions that elicit a termination to a computational process/algorithm - generally speaking, there are **Three** types of stopping conditions (relevant to our course).

1 **FE**: make $|x_a - r|$ as small as possible: e.g.
 $|x_a - r| < \text{Tolerance}$ (say: $\text{TOL} = 10^{-9}$ or $\text{TOL} = \text{Machine}$).

Note: If r is not known directly, as is often the case,

we commonly check: $|x_{i+1} - x_i| < \text{TOL}$ for **iterative algorithms**.

2 **BE**: Make $|f(x_a)|$ small.

3 Impose limit on computation time/# of computations.

e.g. Halt algorithm after 1 minute, etc.

• One common difficulty for root-finding algorithms relates to the inflation of BE for **multiple roots** of a function.

Definition

Assume that r is a root of a differentiable function f , so $f(r) = 0$. Then, if $f(r) = 0, f'(r) = 0, f''(r) = 0, \dots,$ and $f^{(m-1)}(r) = 0$, But $f^{(m)}(r) \neq 0$, we say that The root r (of f) has multiplicity m . If the multiplicity of a root is 2, we call this root a simple root.

Ex.

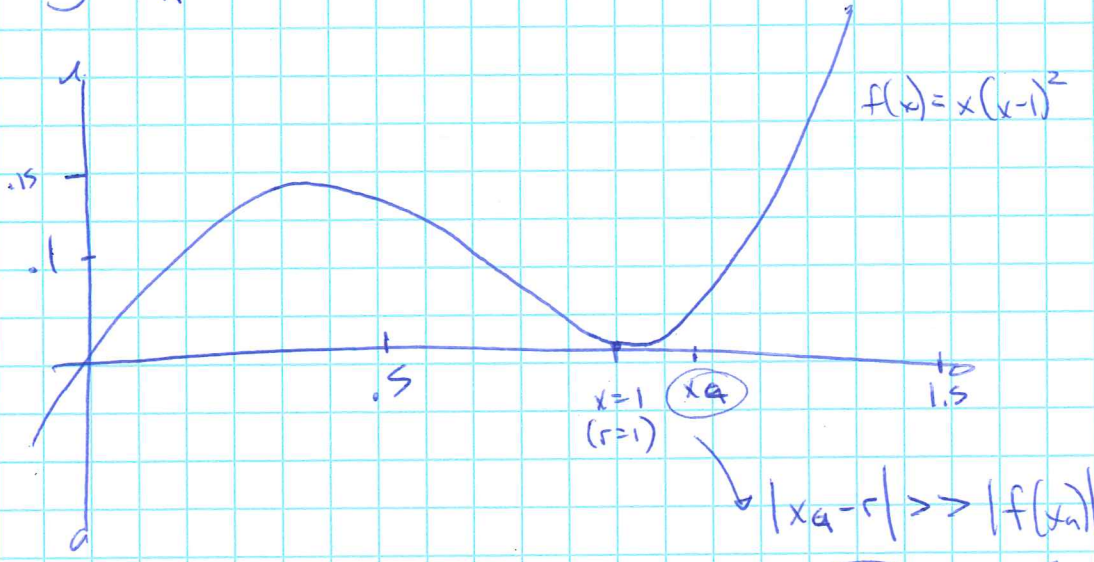
Let $f(x) = x(x-1)^2$. $f(x)$ has a root of multiplicity 2

@ $x=1$, and a root of multiplicity 1 @ $x=0$.

Check: $f(0) = 0, f'(0) = 0$, But $f''(0) \neq 0$. ✓

$f(1) = 0, f'(1) = 0, f''(1) = 0$, But $f'''(1) \neq 0$. ✓

o) Note: Because the graph of a function relatively flat near a multiple root, a great disparity exists between BE & FE for nearly approximate solutions.



(*) FE much larger than BE

A classic example of a function with simple roots that are hard to find numerically is the so-called Wilkinson Polynomial:

$$W(x) = (x-1)(x-2)\dots(x-20)$$
 ($W(x)$ has simple roots for $x=1, \dots, 20$)

Using CAS: find zeros of $W(x)$ with $x_0 = 16$ (actual result).

→ CAS output: 16.014650... only accurate to one decimal place!

Big Idea: Large error inflation (FE) for finding roots due to small relative errors in storing coeffs of $W(x)$ (BE).

So, for $W(x)$, (small BE) → (large FE)!

Analysis of the Sensitivity of Root-Finding

1) A problem is called sensitive if small errors in the input (This case: the equation) yield large errors in the output or solution.

2) To better understand the phenomenon of "sensitivity," we establish a formula for predicting how far a root "moves" when the equation is altered.

Set-up: Assume the goal is to find the root r , where $f(r) = 0$.

Also suppose that a "small" change: $\epsilon g(x)$ is made to the equation.

Let Δr denote the corresponding change in r .

Thus, $f(r) = 0 \rightarrow f(r + \Delta r) + \epsilon g(r + \Delta r) = 0$

(Note: $r + \Delta r$ satisfies the "perturbed" equation: $f(x) + \epsilon g(x) = 0$)

We use the first degree Taylor expansions of $f(x)$ & $g(x)$ around the center: r .

whence, $f(r + \Delta r) \approx f(r) + (\Delta r)f'(r) + \mathcal{O}(\Delta r^2)$
& $g(r + \Delta r) \approx g(r) + (\Delta r)g'(r) + \mathcal{O}(\Delta r^2)$ ($\mathcal{O} = \text{Big-O}$ notation)

So, $f(r + \Delta r) + \epsilon g(r + \Delta r) = f(r) + (\Delta r)f'(r) + \epsilon g(r) + \epsilon (\Delta r)g'(r) + \mathcal{O}(\Delta r^2) = 0$
(Note for Δr small, $(\Delta r)^2 \approx 0$)

Now we solve for Δr :

$(\Delta r)(f'(r) + g'(r)) \approx -f(r) - \epsilon g(r) = -\epsilon g(r)$

Consequently, $\Delta r \approx \frac{-\epsilon g(r)}{f'(r) + \epsilon g'(r)} \approx -\epsilon \left(\frac{g(r)}{f'(r)} \right)$

we assume: $\epsilon \ll f'(r)$ & $f'(r) \neq 0$.

In summary, if r is a root of $f(x)$ & $r + \Delta r$ is a root of $f(x) + \epsilon g(x)$. Then:

$\Delta r \approx -\epsilon \cdot \left(\frac{g(r)}{f'(r)} \right)$
sensitivity formula for roots. where $\epsilon \ll \frac{f'(r)}{f'(r) \neq 0}$.

Ex. Estimate the largest root of $P(x) = (x-1)(x-2)\dots(x-6) - 10^{-6}x^7$ (6)

Note: Without the $\epsilon g(x)$ term, $r=6$ is the largest root of $P(x)$.

So, we now check how much the root: $r=6$ is affected,

when we "shift" the original equation with the "extra" $\epsilon g(x)$ term?

Using the Sensitivity Formula, we can readily approximate

This quantity:
$$\Delta r \approx -\epsilon \left(\frac{g(r)}{f'(r)} \right) \quad \left(\begin{array}{l} g(x) = x^7 \\ f(x) = (x-1)\dots(x-6) \end{array} \right)$$

$$= -\epsilon \left(\frac{6^7}{5!} \right) = \boxed{-2332.8\epsilon}$$

This shows that "input" errors $\approx \epsilon$ are magnified 2000-fold,
roughly, in output errors!

Check: $r + \Delta r = 6 - 2332.8\epsilon = \underline{6.0023328}$ $\epsilon = 10^{-6}$

CAS: Solve: $P(x) = 0 \rightarrow \underline{6.0023268}$ ✓

The previous example showed us how errors propagate in the root-finding problem; an error in the sixth digit of the problem caused an error in the third digit of the answer.

This error magnification is formalized as follows:

Def. Error magnification factor = $\frac{\text{relative FE}}{\text{relative BE}}$

$$\text{Error Magnification Factor} = \frac{\text{relative FE}}{\text{relative BE}} = \left| \frac{\Delta r/r}{\epsilon g(r)/g'(r)} \right|$$

$$= \left| \frac{-\epsilon g(r)/r f'(r)}{\epsilon} \right| = \left| \frac{g(r)}{r f'(r)} \right|$$

[Ex.] EMF for the previous problem:

$$\left| \frac{g(r)}{r f'(r)} \right| = \frac{6^7}{6 \cdot 5!} = \boxed{389} = 3.89 \times 10^2$$

Now, since $\epsilon = 10^{-6}$, the emf $\approx 10^2$ shows that we expect to lose 2 of the 6 decimal places of precision, as the previous example demonstrated.

[Ex.] Use the sensitivity formula to investigate the effect of changes in the x^{15} term of $w(x)$ for $r=16$.

Define the perturbed function: $w_\epsilon(x) = w(x) + \epsilon \cdot g(x)$

with $g(x) = -\frac{1,672,280,820}{\epsilon''} x^{15}$. Note: $w'(16) = 15! \cdot 4!$ (Why?)

Then $\Delta r \approx \frac{16^{15} (1,672,280,820) \epsilon}{15! \cdot 4!} \approx 6.1432 \times 10^{13} \epsilon$

changes in root

$$\text{emf} = \frac{|g(r)|}{|r f'(r)|} = \frac{16^{15} \cdot 1,672,280,820}{15! \cdot 4! \cdot 16} \approx 3.84 \times 10^{12}$$

($\epsilon = 10^{-16}$)
12 digits of 16 lost!

Conditioning & Stability

The condition number: Measure of error magnification.

Stability: Magnification of small input errors due to algorithm
↳ interest in problem

Condition number: Maximum error magnification over all input changes.

Ill-conditioned: Large condition #

Well-conditioned: condition # ≈ 1 .

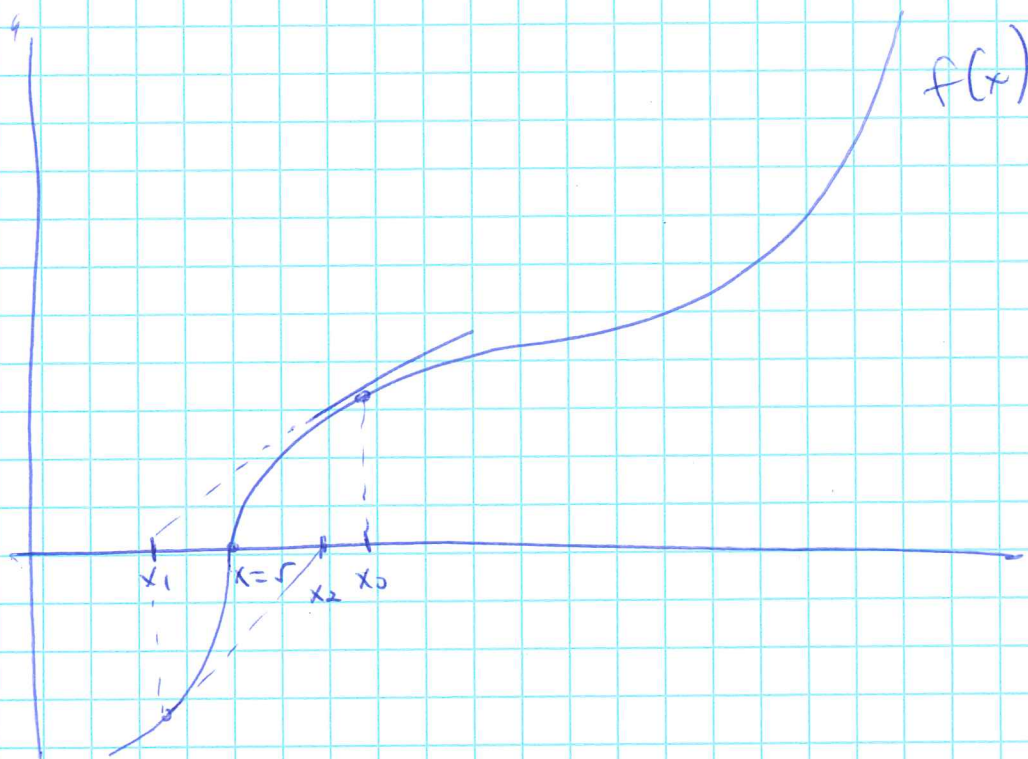
1.4 Newton's Method

9

Newton's Method is an iterative, root-finding algorithm that generally converges faster than Bisection & FPI.

To find a root of $f(x) = 0$, a starting guess (x_0) is given, and the tangent line to the function @ x_0 is drawn; the intersection (x-intercept) of this tangent line is assigned the value x_1 ; the function is iterated likewise.

Newton's Method



Pseudo-code for Newton's Method

10

$x_0 =$ initial guess

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)} \quad \text{for } i = 0, 1, 2, \dots$$

Derivation of NM's formula:

Given an initial guess x_0 , we solve for the x -intercept of the tangent line passing through $(x_0, f(x_0))$.

Using point-slope form of a line:

$$y - y_0 = m(x - x_0) \rightarrow 0 - f(x_0) = f'(x_0)(x - x_0)$$

$$\rightarrow x - x_0 = -\frac{f(x_0)}{f'(x_0)}$$

$$\rightarrow x = x_0 - \frac{f(x_0)}{f'(x_0)}$$

In general, then,
$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$

Ex. With $x_0 = -0.7$, use NM's to approximate a root of $x^3 + x - 1 = 0$.

$$f'(x) = 3x^2 + 1$$

(11)

$$\text{So, } x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$

$$x_1 = x_0 - \frac{f(x_0)}{f'(x_0)} \approx \boxed{.1271}$$

$$x_2 = x_1 - \frac{f(x_1)}{f'(x_1)} \approx \boxed{.9577}$$

$$\vdots$$
$$\boxed{x_7 = .68232780}$$

correct to eight decimal places!

Note: As we see, the convergence of NMs is qualitatively faster than Bisection & FPI; in general NMs is quadratically convergent.

Def. Let e_i denote the error after step i of a iterative method. The iteration is quadratically convergent if:

$$\lim_{i \rightarrow \infty} \frac{e_{i+1}}{e_i^2} = M < \infty$$

Theorem: Let f be twice continuously differentiable & $f(r) = 0$.

If $f'(r) \neq 0$, then NM is locally & quadratically convergent

to r .

Proof To prove local convergence, note that NM is a particular

form of FPI where $g(x) = x - \frac{f(x)}{f'(x)}$

(12)

$$\text{Then, } g'(x) = \frac{1 - f'(x)^2 - f(x)f''(x)}{f'(x)^2} = \frac{f(x)f''(x)}{f'(x)^2}$$

$$|g'(r)| = \left| \frac{f(r)f''(r)}{f'(r)^2} \right| = 0 < 1, \text{ so NM is locally convergent.}$$

Now we prove quadratic convergence.

Using Taylor Series

$$f(r) = f(x_i) + (r-x_i)f'(x_i) + \frac{(r-x_i)^2}{2}f''(c_i) \quad (c_i \in (x_i, r))$$

$$0 = f(x_i) + (r-x_i)f'(x_i) + \frac{(r-x_i)^2}{2}f''(c_i)$$

$$\rightarrow \frac{-f(x_i)}{f'(x_i)} = r - x_i + \frac{(r-x_i)^2}{2} \frac{f''(c_i)}{f'(x_i)}$$

$$\rightarrow \underbrace{x_i - \frac{f(x_i)}{f'(x_i)}}_{e_i} - r = \frac{(r-x_i)^2}{2} \frac{f''(c_i)}{f'(x_i)} \quad ((r-x_i)^2 = e_i^2)$$

$$\rightarrow x_{i+1} - r = e_i^2 \cdot \frac{f''(c_i)}{2f'(x_i)}$$

$$\rightarrow e_{i+1} = e_i^2 \left| \frac{f''(c_i)}{2f'(x_i)} \right|$$

Note: $\lim_{i \rightarrow \infty} c_i \rightarrow r$

$$\rightarrow \lim_{i \rightarrow \infty} \frac{e_{i+1}}{e_i^2} = \left| \frac{f''(r)}{2f'(r)} \right| = M < \infty \quad (f'(r) \neq 0)$$

In this fashion, The error can be expressed iteratively as:

$$e_{i+1} \approx M e_i^2 \quad \left(M = \left| \frac{f''(r)}{2f'(r)} \right| \right)$$

Note: NM's does not always converge quadratically!

The algorithm is sensitive to the choice of x_0 ; in addition, NM's converges only linearly at multiple roots!

Ex. $f(x) = x^2$; let $x_0 = 1$.

for multiple roots (m):
 $\lim_{i \rightarrow \infty} \frac{e_{i+1}}{e_i} = S = \frac{m-1}{m}$

$\rightarrow x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)} \rightarrow x_1 = 1 - \frac{f(1)}{f'(1)} = .5 \dots$

$x_2 = .25$
 $x_3 = .125$
 \vdots

$\left(\frac{e_i}{e_{i-1}} = \frac{1}{2} \right)$

Note that NM's will, in fact, converge to the multiple root: $r=0$, but $e_{i+1} = \frac{e_i}{2}$, so the convergence is only linear in this case.

Ex. Find the multiplicity of the root $r=0$ for $f(x) = \sin x + x^2 \cos x - x^2 - x$, and estimate the number of steps required of NM's to converge to r within six decimal places.

$f(0) = 0$.

$f'(x) = \cos x + 2x \cos x - x^2 \rightarrow f'(0) = 0 \checkmark$

$f''(x) = -\sin x + 2 \cos x - 4x \sin x - x^2 \cos x - 2 \rightarrow f''(0) = 0 \checkmark$

However, $f'''(0) \neq 0$. So $r=0$ has multiplicity 3. ($m=3$)

Thus, by the previous result (above), $e_{i+1} \approx \frac{2}{3} e_i$

So, we solve:

$\left(\frac{2}{3}\right)^n < .5 \times 10^{-6} \rightarrow n \approx 35.78 \rightarrow \boxed{n=36}$ 36 steps! (approximated)

Thm: If f is $(m+1)$ -times differentiable on $[a, b]$, which contains root r with multiplicity $m > 1$, then Modified Newton's Method

$$x_{i+1} = x_i - m \cdot \frac{f(x_i)}{f'(x_i)}$$

← The catch: we must know the multi. of r (m) previously.

converges locally & quadratically to r .

Ex. We revisit the previous example, using Modified Newton's Method.

$$f(x) = \sin x + x^2 \cos x - x^2 - x; \quad x_0 = 1$$

$$x_4 = .00000006072272$$

$$x_5 = -.00000000633250 \rightarrow 8 \text{ digits of accuracy!}$$

Also, note that using a table of values, we can observe quadratic convergence of modified NMs, since accuracy essentially doubles w/ each iteration.

Q: When can NMs fail? (1) when $f'(r) = 0$ (2) with poor choice of x_0 (3) for function with large $|f'(x)|$.

Ex. Apply NMs: $f(x) = 4x^4 - 6x^2 - \frac{1}{4}$; $x_0 = \frac{1}{2}$

$$x_{i+1} = x_i - \frac{4x_i^4 - 6x_i^2 - \frac{1}{4}}{16x_i^3 - 12x_i}$$

$$x_1 = -\frac{1}{2}$$

$$x_2 = \frac{1}{2}$$

$$x_3 = -\frac{1}{2}$$

$$x_4 = \frac{1}{2} \dots$$

} infinite oscillations!

Picture →

