# Generalized Regression Model 

## Based on Greene's Note 15 (Chapter 8)

## Generalized Regression Model

Setting: The classical linear model assumes that $E\left[\varepsilon \varepsilon^{\prime}\right]=\operatorname{Var}[\varepsilon]=\sigma^{2}$. That is, observations are uncorrelated and all are drawn from a distribution with the same variance. The generalized regression (GR) model allows the variances to differ across observations and allows correlation across observations.

## Implications

- The assumption that $\operatorname{Var}[\varepsilon]=\sigma^{2} I$ is used to derive the result $\operatorname{Var}[\mathbf{b}]=\sigma^{2}\left(\mathbf{X}^{\prime} \mathbf{X}\right)^{-1}$. If it is not true, then the use of $s^{2}\left(\mathbf{X}^{\prime} \mathbf{X}\right)^{-1}$ to estimate $\operatorname{Var}[\mathbf{b}]$ is inappropriate.
- The assumption was used to derive most of our test statistics, so they must be revised as well.
- Least squares gives each observation a weight of $1 / n$. But, if the variances are not equal, then some observations are more informative than others.
- Least squares is based on simple sums, so the information that one observation might provide about another is never used.


## GR Model

The generalized regression model:

$$
\begin{aligned}
& \mathbf{y}=\mathbf{X} \boldsymbol{\beta}+\boldsymbol{\varepsilon}, \\
& \mathrm{E}[\varepsilon \mid \mathbf{X}]=\mathbf{0}, \operatorname{Var}[\varepsilon \mid \mathbf{X}]=\sigma^{2} \boldsymbol{\Omega} .
\end{aligned}
$$

Regressors are well behaved. We consider some examples with Trace $\Omega=\mathrm{n}$. (This is a normalization with no content.)

- Leading Cases
- Simple heteroscedasticity
- Autocorrelation
- Panel data and heterogeneity more generally.


## Least Squares

- Still unbiased. (Proof did not rely on $\Omega$ )
- For consistency, we need the true variance of $\mathbf{b}$,

$$
\begin{aligned}
\operatorname{Var}[\mathbf{b} \mid \mathbf{X}] & =\mathrm{E}\left[(\mathbf{b}-\boldsymbol{\beta})(\mathbf{b}-\boldsymbol{\beta})^{\prime} \mid \mathbf{X}\right] \\
& =\left(\mathbf{X}^{\prime} \mathbf{X}\right)^{-1} \mathrm{E}\left[\mathbf{X}^{\prime} \varepsilon \varepsilon^{\prime} \mathbf{X}\right]\left(\mathbf{X}^{\prime} \mathbf{X}\right)^{-1} \\
& =\sigma^{2}\left(\mathbf{X}^{\prime} \mathbf{X}\right)^{-1} \mathbf{X}^{\prime} \Omega \mathbf{X}\left(\mathbf{X}^{\prime} \mathbf{X}\right)^{-1} .
\end{aligned}
$$

Divide all 4 terms by $n$. If the middle one converges to a finite matrix of constants, we have the result, so we need to examine

$$
(1 / n) X^{\prime} \Omega X=(1 / n) \Sigma_{i} \Sigma_{\mathrm{j}} \omega_{\mathrm{ij}} \mathbf{x}_{\mathrm{i}} \mathbf{x}_{\mathrm{j}}^{\prime} .
$$

This will be another assumption of the model.

- Asymptotic normality? Easy for heteroscedasticity case, very difficult for autocorrelation case.


## Robust Covariance Matrix

- Robust estimation:
- How to estimate $\operatorname{Var}[\mathbf{b} \mid \mathbf{X}]=\sigma^{2}\left(\mathbf{X}^{\prime} \mathbf{X}\right)^{-1} \mathbf{X} \mathbf{\Omega} \mathbf{X}$ $\left(\mathbf{X}^{\prime} \mathbf{X}\right)^{-1}$ for the LS $\mathbf{b}$ ?
- The distinction between estimating $\sigma^{2} \Omega$ an $n$ by $n$ matrix and estimating

$$
\sigma^{2} \mathbf{X}^{\prime} \Omega \mathbf{X}=\sigma^{2} \Sigma_{\mathrm{i}} \Sigma_{\mathrm{j}} \omega_{\mathrm{ij}} \mathbf{x}_{\mathrm{i}} \mathbf{x}_{\mathrm{j}}^{\prime}
$$

- For modern applied econometrics,
- The White estimator
- Newey-West.


## The White Estimator

Est. $\operatorname{Var}[\mathbf{b}]=\left(\mathbf{X}^{\prime} \mathbf{X}\right)^{-1}\left[\sum_{\mathrm{i}=1}^{\mathrm{n}} \mathrm{e}_{\mathrm{i}}^{2} \mathbf{x}_{\mathrm{i}} \mathbf{X}_{\mathrm{i}}^{\mathbf{\prime}}\right]\left(\mathbf{X}^{\prime} \mathbf{X}\right)^{-1}$
Use $\quad \hat{\sigma}^{2}=\frac{\sum_{i=1}^{n} e_{i}^{2}}{n}$

Est. $\operatorname{Var}[\mathbf{b}]=\frac{\hat{\sigma}^{2}}{\mathrm{n}}\left(\frac{\mathbf{X}^{\prime} \mathbf{X}}{\mathrm{n}}\right)^{-1}\left(\frac{\mathbf{X}^{\prime} \hat{\mathbf{\Omega}} \mathbf{X}}{\mathrm{n}}\right)\left(\frac{\mathbf{X}^{\prime} \mathbf{X}}{\mathrm{n}}\right)$
Does $\quad \hat{\sigma}^{2}\left(\frac{\mathbf{X} \cdot \hat{\mathbf{\Omega}} \mathbf{X}}{\mathrm{n}}\right)-\sigma^{2}\left(\frac{\mathbf{X} \mathbf{} \mathbf{\Omega} \mathbf{X}}{\mathrm{n}}\right) \rightarrow \mathbf{0} \boldsymbol{?}$

## Newey-West Estimator

Heteroscedasticity Component - Diagonal Elements
$\mathbf{S}_{0}=\frac{1}{\mathrm{n}} \sum_{\mathrm{i}=1}^{\mathrm{n}} \mathrm{e}_{\mathrm{i}}^{2} \mathbf{x}_{\mathrm{i}} \mathbf{x}_{\mathrm{i}}{ }^{\prime}$
Autocorrelation Component - Off Diagonal Elements
$\mathbf{S}_{1}=\frac{1}{\mathrm{n}} \sum_{\mathrm{l}=1}^{\mathrm{L}} \sum_{\mathrm{t}=+1}^{\mathrm{n}} \mathrm{w}_{1} \mathrm{e}_{\mathrm{t}} \mathrm{e}_{\mathrm{t}-1}\left(\mathbf{x}_{\mathrm{t}} \mathbf{x}_{\mathrm{t}-1}^{\prime}+\mathbf{x}_{\mathrm{t}-1} \mathbf{x}_{\mathrm{t}}^{\prime}\right)$
$w_{1}=1-\frac{1}{L+1}=$ "Bartlett weight"
Est. $\operatorname{Var}[\mathbf{b}]=\frac{1}{\mathrm{n}}\left(\frac{\mathbf{X}^{\prime} \mathbf{X}}{\mathrm{n}}\right)^{-1}\left[\mathbf{S}_{0}+\mathbf{S}_{1}\right]\left(\frac{\mathbf{X} \mathbf{X}}{\mathrm{n}}\right)^{-1}$

## Generalized Least Squares

A transformation of the model:

$$
\begin{aligned}
\mathbf{P} & =\Omega^{-1 / 2} . \mathbf{P}^{\prime} \mathbf{P}=\Omega^{-1} \\
\mathbf{P y} & =\mathbf{P X} \beta+\mathbf{P} \boldsymbol{\varepsilon} \text { or } \\
\mathbf{y}^{\star} & =\mathbf{X}^{\star} \beta+\varepsilon^{\star} . \quad \mathrm{Why} ? \\
\mathrm{E}\left[\varepsilon^{\star} \varepsilon^{*} \mid \mathbf{X}^{\star}\right] & =\mathbf{P E}\left[\varepsilon \varepsilon^{\prime} \mid \mathbf{X}^{\star}\right] \mathbf{P} \\
& =\mathbf{P E}\left[\varepsilon \varepsilon^{\prime} \mid \mathbf{X}\right] \mathbf{P} \\
& =\sigma^{2} \mathbf{P} \Omega \mathbf{P}^{\prime}=\sigma^{2} \Omega^{-1 / 2} \Omega \Omega^{-1 / 2}=\sigma^{2} \Omega^{0} \\
& =\sigma^{2} \boldsymbol{l}
\end{aligned}
$$

## Generalized Least Squares

Aitken theorem. The Generalized Least Squares estimator, GLS.

$$
\begin{aligned}
& \mathbf{P y}=\mathrm{PX} \beta+\mathrm{P} \varepsilon \text { or } \\
& \mathbf{y}^{*}=\mathbf{X}^{*} \beta+\varepsilon^{*} . \mathrm{E}\left[\varepsilon^{\star} \varepsilon^{\star} \mid \mathbf{X}^{\star}\right]=\sigma^{2} I
\end{aligned}
$$

Use ordinary least squares in the transformed model. Satisfies the Gauss Markov theorem.

$$
\mathbf{b}^{*}=\left(\mathbf{X}^{* \prime} \mathbf{X}^{*}\right)^{-1} \mathbf{X}^{* \prime} \mathbf{y}^{*}
$$

## Generalized Least Squares

Efficient estimation of $\beta$ and, by implication, the inefficiency of least squares $\mathbf{b}$.

$$
\begin{aligned}
\hat{\boldsymbol{\beta}} & =\left(\mathbf{X}^{*} \mathbf{X}^{*}\right)^{-1} \mathbf{X}^{* \prime} \mathbf{y}^{*} \\
& =\left(\mathbf{X}^{\prime} \mathbf{P}^{\prime} \mathbf{P} \mathbf{X}\right)^{-1} \mathbf{X}^{\prime} \mathbf{P}^{\prime} \mathbf{P y} \\
& =\left(\mathbf{X}^{\prime} \mathbf{\Omega}^{-1} \mathbf{X}\right)^{-1} \mathbf{X}^{\prime} \mathbf{\Omega}^{-1} \mathbf{y}
\end{aligned}
$$

$\hat{\boldsymbol{\beta}} \neq \mathbf{b} . \hat{\boldsymbol{\beta}}$ is efficient, so by construction, $\mathbf{b}$ is not.

## Asymptotics for GLS

Asymptotic distribution of GLS. (NOTE: We apply the full set of results of the classical model to the transformed model).

Unbiasedness
Consistency - "well behaved data"
Asymptotic distribution
Test statistics

## Unbiasedness

$$
\begin{aligned}
& \begin{aligned}
\hat{\boldsymbol{\beta}} & =\left(\mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \mathbf{X}\right)^{-1} \mathbf{X} \mathbf{\Omega}^{-1} \mathbf{y} \\
& =\boldsymbol{\beta}+\left(\mathbf{X}^{-} \boldsymbol{\Omega}^{-1} \mathbf{X}\right)^{-1} \mathbf{X} \mathbf{\Omega}^{-1} \boldsymbol{\varepsilon}
\end{aligned} \\
& \begin{aligned}
\mathrm{E}[\hat{\boldsymbol{\beta}} \mid \mathbf{X}] & =\boldsymbol{\beta}+\left(\mathbf{X}^{-1} \boldsymbol{\Omega}^{-1} \mathbf{X}\right)^{-1} \mathbf{X} \boldsymbol{\Omega}^{-1} \mathrm{E}[\boldsymbol{\varepsilon} \mid \mathbf{X}] \\
& =\boldsymbol{\beta} \text { if } \mathrm{E}[\boldsymbol{\varepsilon} \mid \mathbf{X}]=\mathbf{0}
\end{aligned}
\end{aligned}
$$

## nonsistency

Use Mean Square
$\operatorname{Var}[\hat{\boldsymbol{\beta}} \mid \mathbf{X}]=\frac{\sigma^{2}}{\mathrm{n}}\left(\frac{\mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \mathbf{X}}{\mathrm{n}}\right)^{-1} \rightarrow \mathbf{0}$ ?
Requires to be $\left(\frac{\mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \mathbf{X}}{\mathrm{n}}\right)$ "well behaved"
Either converge to a constant matrix or diverge.
Heteroscedasticity case:
$\frac{\mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \mathbf{X}}{\mathrm{n}}=\frac{1}{\mathrm{n}} \sum_{\mathrm{i}=1}^{\mathrm{n}} \frac{1}{\omega_{\mathrm{i}}} \mathbf{x}_{\mathrm{i}} \mathbf{x}_{\mathrm{i}}{ }^{\prime}$
Autocorrelation case:
$\frac{\mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \mathbf{X}}{\mathrm{n}}=\frac{1}{\mathrm{n}} \sum_{\mathrm{i}=1}^{\mathrm{n}} \sum_{\mathrm{j}=1}^{\mathrm{n}} \frac{1}{\omega_{\mathrm{ij}}} \mathbf{x}_{\mathrm{i}} \mathbf{x}_{\mathrm{j}} \cdot \mathrm{n}$ n terms. Convergence is unclear.

## Asymptotic Normality

$\sqrt{\mathrm{n}}(\hat{\boldsymbol{\beta}}-\boldsymbol{\beta})=\sqrt{\mathrm{n}}\left(\frac{\mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \mathbf{X}}{\mathrm{n}}\right)^{-1} \frac{1}{\mathrm{n}} \mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \boldsymbol{\varepsilon}$
Converge to normal with a stable variance $\mathrm{O}(1)$ ?
$\left(\frac{\mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \mathbf{X}}{\mathrm{n}}\right)^{-1} \rightarrow$ a constant matrix?
$\frac{1}{n} \mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \boldsymbol{\varepsilon} \rightarrow$ a mean to which we can apply the central limit theorem?
Heteroscedasticity case?
$\frac{1}{n} \mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \boldsymbol{\varepsilon}=\frac{1}{n} \sum_{\mathrm{i}=1}^{\mathrm{n}} \frac{\mathbf{x}_{\mathrm{i}}}{\sqrt{\omega_{\mathrm{i}}}}\left(\frac{\varepsilon_{\mathrm{i}}}{\sqrt{\omega_{\mathrm{i}}}}\right) . \operatorname{Var}\left(\frac{\varepsilon_{\mathrm{i}}}{\sqrt{\omega_{\mathrm{i}}}}\right)=\sigma^{2}, \frac{\mathbf{x}_{\mathrm{i}}}{\sqrt{\omega_{\mathrm{i}}}}$ is just data.
Apply Lindeberg-Feller. (Or assuming $\mathbf{x}_{i} / \sqrt{\omega_{i}}$ is a draw from a common distribution with mean and fixed variance - some recent treatments.)
Autocorrelation case?

## Asymptotic Normality (Cont.)

For the autocorrelation case
$\frac{1}{\mathrm{n}} \mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \boldsymbol{\varepsilon}=\frac{1}{\mathrm{n}} \sum_{\mathrm{i}=1}^{\mathrm{n}} \sum_{\mathrm{j}=1}^{\mathrm{n}} \boldsymbol{\Omega}^{\mathrm{ij}} \mathbf{x}_{\mathrm{i}} \mathbf{x}_{\mathrm{j}} \varepsilon_{\mathrm{i}} \varepsilon_{\mathrm{i}}$

Does the double sum converge? Uncertain. Requires elements of $\boldsymbol{\Omega}^{-1}$ to become small as the distance between i and j increases. (Has to resemble the heteroscedasticity case.)

# Test Statistics (Assuming Known $\Omega$ ) 

- With known $\Omega$, apply all familiar results to the transformed model.
- With normality, t and F statistics apply to least squares based on Py and PX
- With asymptotic normality, use Wald statistics and the chi-squared distribution, still based on the transformed model.


## Generalized (Weighted) Least Squares:Heteroscedasticity

$$
\begin{aligned}
& \operatorname{Var}[\varepsilon]=\sigma^{2} \Omega=\sigma^{2}\left[\begin{array}{cccc}
\omega_{1} & 0 & \ldots & 0 \\
0 & \omega_{2} & \ldots & 0 \\
0 & 0 & \ldots & 0 \\
0 & 0 & \ldots & \omega_{n}
\end{array}\right] \\
& \Omega^{-1 / 2}=\left[\begin{array}{ccccc}
1 / \sqrt{\omega_{1}} & 0 & \ldots & 0 \\
0 & 1 / \sqrt{\omega_{2}} & \ldots & 0 \\
0 & 0 & \ldots & 0 \\
0 & 0 & \ldots & 1 / \sqrt{\omega_{n}}
\end{array}\right]
\end{aligned}
$$

$$
\hat{\boldsymbol{\beta}}=\left(\mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \mathbf{X}\right)^{-1}\left(\mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \mathbf{y}\right)=\left(\sum_{\mathrm{i}=1}^{n} \frac{1}{\omega_{\mathrm{i}}} \mathbf{x}_{\mathrm{i}} \mathbf{x}_{\mathrm{i}}^{\prime}\right)^{-1}\left(\sum_{\mathrm{i}=1}^{\mathrm{n}} \frac{1}{\omega_{\mathrm{i}}} \mathbf{x}_{\mathrm{i}} \mathbf{y}_{\mathrm{i}}\right)
$$

$$
\hat{\sigma}^{2}=\frac{\sum_{i=1}^{n}\left(\frac{y_{i}-\mathbf{x}_{i} \hat{\boldsymbol{\beta}}}{\omega_{i}}\right)^{2}}{n-K}
$$

## Autocorrelation

$$
\varepsilon_{\mathrm{t}}=\rho \varepsilon_{\mathrm{t}-1}+\mathrm{u}_{\mathrm{t}}
$$

('First order autocorrelation.' How does this come about?)
Assume $-1<\rho<1$. Why?
$u_{t}=$ 'nonautocorrelated white noise'
$\varepsilon_{\mathrm{t}}=\rho \varepsilon_{\mathrm{t}-1}+\mathrm{u}_{\mathrm{t}}$ (the autoregressive form)
$=\rho\left(\rho \varepsilon_{t-2}+u_{t-1}\right)+u_{t}$
$=\ldots$ (continue to substitute)
$=u_{t}+\rho u_{t-1}+\rho^{2} u_{t-2}+\rho^{3} u_{t-3}+\ldots$
$=$ (the moving average form)
(Some observations about modeling time series.)

## Autocorrelation

$$
\begin{aligned}
\operatorname{Var}\left[\varepsilon_{t}\right] & =\operatorname{Var}\left[u_{t}+\rho u_{t-1}+\rho^{2} u_{t-1}+\ldots\right] \\
& =\operatorname{Var}\left[\sum_{i=0}^{\infty} \rho^{i} u_{t-i}\right] \\
& =\sum_{i=0}^{\infty} \rho^{2 i} \sigma_{u}^{2}=\frac{\sigma_{u}^{2}}{1-\rho^{2}}
\end{aligned}
$$

An easier way: Since $\operatorname{Var}\left[\varepsilon_{\mathrm{t}}\right]=\operatorname{Var}\left[\varepsilon_{\mathrm{t}-1}\right]$ and $\varepsilon_{\mathrm{t}}=\rho \varepsilon_{\mathrm{t}-1}+\mathrm{u}_{\mathrm{t}}$ $\operatorname{Var}\left[\varepsilon_{\mathrm{t}}\right]=\rho^{2} \operatorname{Var}\left[\varepsilon_{\mathrm{t}-1}\right]+\operatorname{Var}\left[\mathrm{u}_{\mathrm{t}}\right]+2 \rho \operatorname{Cov}\left[\varepsilon_{\mathrm{t}-1}, \mathrm{u}_{\mathrm{t}}\right]$

$$
\begin{aligned}
& =\rho^{2} \operatorname{Var}\left[\varepsilon_{t}\right]+\sigma_{u}^{2} \\
& =\frac{\sigma_{u}^{2}}{1-\rho^{2}}
\end{aligned}
$$

## Autocovariances

Continuing...

$$
\begin{aligned}
\operatorname{Cov}\left[\varepsilon_{\mathrm{t}}, \varepsilon_{\mathrm{t}-1}\right] & =\operatorname{Cov}\left[\rho \varepsilon_{\mathrm{t}-1}+\mathrm{u}_{\mathrm{t}}, \varepsilon_{\mathrm{t}-1}\right] \\
& =\rho \operatorname{Cov}\left[\varepsilon_{\mathrm{t}-1}, \varepsilon_{\mathrm{t}-1}\right]+\operatorname{Cov}\left[\mathrm{u}_{\mathrm{t}}, \varepsilon_{\mathrm{t}-1}\right] \\
& =\rho \operatorname{Var}\left[\varepsilon_{\mathrm{t}-1}\right]=\rho \operatorname{Var}\left[\varepsilon_{\mathrm{t}}\right] \\
& =\frac{\rho \sigma_{\mathrm{u}}^{2}}{\left(1-\rho^{2}\right)} \\
\operatorname{Cov}\left[\varepsilon_{\mathrm{t}}, \varepsilon_{\mathrm{t}-2}\right] & =\operatorname{Cov}\left[\rho \varepsilon_{\mathrm{t}-1}+\mathrm{u}_{\mathrm{t}}, \varepsilon_{\mathrm{t}-2}\right] \\
& =\rho \operatorname{Cov}\left[\varepsilon_{\mathrm{t}-1}, \varepsilon_{\mathrm{t}-2}\right]+\operatorname{Cov}\left[\mathrm{u}_{\mathrm{t}}, \varepsilon_{\mathrm{t}-2}\right] \\
& =\rho \operatorname{Cov}\left[\varepsilon_{\mathrm{t}}, \varepsilon_{\mathrm{t}-1}\right] \\
& =\frac{\rho^{2} \sigma_{\mathrm{u}}^{2}}{\left(1-\rho^{2}\right)} \text { and so on. }
\end{aligned}
$$

## Autocorrelation Matrix

$$
\sigma^{2} \boldsymbol{\Omega}=\left(\frac{\sigma_{u}^{2}}{1-\rho^{2}}\right)\left[\begin{array}{ccccc}
1 & \rho & \rho^{2} & \cdots & \rho^{T-1} \\
\rho & 1 & \rho & \cdots & \rho^{T-2} \\
\rho^{2} & \rho & 1 & \cdots & \rho^{T-3} \\
\vdots & \vdots & \vdots & \ddots & \vdots \\
\rho^{T-1} & \rho^{T-2} & \rho^{T-3} & \cdots & 1
\end{array}\right]
$$

(Note, trace $\boldsymbol{\Omega}=\mathrm{n}$ as required.)

## Generalized Least Squares

$$
\begin{aligned}
& \boldsymbol{\Omega}^{-1 / 2}=\left[\begin{array}{ccccc}
\sqrt{1-\rho^{2}} & 0 & 0 & \ldots & 0 \\
-\rho & 1 & 0 & \ldots & 0 \\
0 & -\rho & 1 & \ldots & 0 \\
\ldots & \ldots & \ldots & \ldots & \ldots \\
0 & 0 & 0 & -\rho & 0
\end{array}\right] \\
& \boldsymbol{\Omega}^{-1 / 2} \mathbf{y}=\left(\begin{array}{c}
\left(\sqrt{1-\rho^{2}}\right) y_{1} \\
y_{2}-\rho y_{2} \\
y_{3}-\rho y_{2} \\
\ldots \\
y_{T}-\rho_{\mathrm{T}-1}
\end{array}\right)
\end{aligned}
$$

## The Autoregressive Transformation

$$
\begin{aligned}
& y_{\mathrm{t}}=\mathbf{x}_{\mathbf{t}}^{\prime} \boldsymbol{\beta}+\varepsilon_{\mathrm{t}} \quad \varepsilon_{\mathrm{t}}=\rho \varepsilon_{\mathrm{t}-1}+\mathrm{u}_{\mathrm{t}} \\
& \rho \mathrm{y}_{\mathrm{t}-1}=\rho \mathbf{x}_{\mathrm{t}-1} \boldsymbol{\beta}^{\boldsymbol{\beta}}+\rho \varepsilon_{\mathrm{t}-1} \\
& ---------- \\
& \mathrm{y}_{\mathrm{t}}-\rho \mathrm{y}_{\mathrm{t}-1}=\left(\mathbf{x}_{\mathrm{t}}-\rho \mathbf{x}_{\mathbf{t}-1}\right)^{\prime} \boldsymbol{\beta}+\left(\varepsilon_{\mathrm{t}}-\rho \varepsilon_{\mathrm{t}-1}\right) \\
& \mathrm{y}_{\mathrm{t}}-\rho \mathrm{y}_{\mathrm{t}-1}=\left(\mathbf{x}_{\mathbf{t}}-\rho \mathbf{x}_{\mathbf{t}-1}\right)^{\prime} \boldsymbol{\beta}+\mathrm{u}_{\mathrm{t}}
\end{aligned}
$$

(Where did the first observation go?)

## Unknown $\Omega$

- The problem (of course), $\Omega$ is unknown. For now, we will consider two methods of estimation:
- Two step, or feasible estimation. Estimate $\Omega$ first, then do GLS. Emphasize - same logic as White and Newey-West. We don't need to estimate $\Omega$. We need to find a matrix that behaves the same as $(1 / n) \mathbf{X}^{\prime} \Omega^{-1} \mathbf{X}$.
- Properties of the feasible GLS estimator Maximum likelihood estimation of $\beta, \sigma^{2}$, and $\Omega$ all at the same time.
- Joint estimation of all parameters. Fairly rare. Some generalities...
- We will examine two applications: Harvey's model of heteroscedasticity and Beach-MacKinnon on the first order autocorrelation model


## Specification

- $\Omega$ must be specified first.
- A full unrestricted $\Omega$ contains $n(n+1) / 2-1$ parameters. (Why minus 1? Remember, $\operatorname{tr}(\boldsymbol{\Omega})=\mathrm{n}$, so one element is determined.)
- $\boldsymbol{\Omega}$ is generally specified in terms of a few parameters. Thus, $\boldsymbol{\Omega}=\boldsymbol{\Omega}(\theta)$ for some small parameter vector $\theta$. It becomes a question of estimating $\theta$.
- Examples:


## Heteroscedasticity: Harvey’s Model

- $\operatorname{Var}\left[\varepsilon_{\mathrm{i}} \mid \mathbf{X}\right]=\sigma^{2} \exp \left(\gamma^{\prime} \mathbf{z}_{\mathrm{i}}\right)$
- $\operatorname{Cov}\left[\varepsilon_{i}, \varepsilon_{j} \mid X\right]=0$
e.g.: $z_{i}=$ firm size
e.g.: $\mathbf{z}_{i}=$ a set of dummy variables (e.g., countries) (The groupwise heteroscedasticity model.)
- $\left[\sigma^{2} \boldsymbol{\Omega}\right]=\operatorname{diagonal}\left[\exp \left(\theta+\gamma^{\prime} \mathbf{z}_{\mathbf{i}}\right)\right]$,

$$
\theta=\log \left(\sigma^{2}\right)
$$

## AR(1) Model of Autocorrelation

$$
\sigma^{2} \boldsymbol{\Omega}=\left(\frac{\sigma_{u}^{2}}{1-\rho^{2}}\right)\left[\begin{array}{ccccc}
1 & \rho & \rho^{2} & \cdots & \rho^{T-1} \\
\rho & 1 & \rho & \cdots & \rho^{T-2} \\
\rho^{2} & \rho & 1 & \cdots & \rho^{T-3} \\
\vdots & \vdots & \vdots & \ddots & \vdots \\
\rho^{T-1} & \rho^{T-2} & \rho^{T-3} & \cdots & 1
\end{array}\right]
$$

## Two Step Estimation

The general result for estimation when $\Omega$ is estimated.
GLS uses $\left[X^{\prime} \Omega^{-1} \mathbf{X}\right] \mathbf{X}^{\prime} \Omega^{-1} \mathbf{y}$ which converges in probability to $\beta$.
We seek a vector which converges to the same thing that this does. Call it "Feasible GLS" or FGLS, based on $\left[\mathbf{X}^{\prime} \hat{\mathbf{\Omega}}^{-1} \mathbf{X}\right] \mathbf{X}^{\prime} \hat{\mathbf{\Omega}}^{-\mathbf{1}} \mathbf{y}$
The object is to find a set of parameters such that
$\left[\mathbf{X}^{\prime} \hat{\mathbf{\Omega}}^{-1} \mathbf{X}\right] \mathbf{X}^{\prime} \hat{\mathbf{\Omega}}^{-1} \mathbf{y} \quad-\quad\left[\mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \mathbf{X}\right] \mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \mathbf{y} \quad \rightarrow 0$

## Feasible GLS

For FGLS estimation, we do not seek an estimator of $\boldsymbol{\Omega}$
such that

$$
\hat{\mathbf{\Omega}}-\boldsymbol{\Omega} \rightarrow \mathbf{0}
$$

This makes no sense, since $\hat{\boldsymbol{\Omega}}$ is nxn and does not "converge" to anything. We seek a matrix $\boldsymbol{\Omega}$ such that

$$
(1 / n) \mathbf{X}^{\prime} \hat{\mathbf{\Omega}}^{-1} \mathbf{X}-(1 / n) \mathbf{X}^{\prime} \mathbf{\Omega}^{-1} \mathbf{X} \rightarrow \mathbf{0}
$$

For the asymptotic properties, we will require that

$$
(1 / n) \mathbf{X}^{\prime} \hat{\mathbf{\Omega}}^{-1} \varepsilon-(1 / n) \mathbf{X}^{\prime} \boldsymbol{\Omega}^{-1} \varepsilon \rightarrow \mathbf{0}
$$

Note in this case, these are two random vectors, which we require to converge to the same random vector.

## Two Step FGLS

(Theorem 8.5) To achieve full efficiency, we do not need an efficient estimate of the parameters in $\Omega$, only a consistent one. Why?

## Harvey's Model

Examine Harvey's model once again.
Methods of estimation:
Two step FGLS: Use the least squares residuals to estimate $\theta$, then use $\left\{\mathrm{X}^{\prime}[\mathbf{\Omega}(\theta)]^{-1} \mathrm{X}\right\}^{-1} \mathrm{X}^{\prime}[\mathbf{\Omega}(\theta)]^{-1} \mathrm{y}$ to estimate $\boldsymbol{\beta}$.
Full maximum likelihood estimation. Estimate all parameters simultaneously.
A handy result due to Oberhofer and Kmenta - the "zig-zag" approach.
Examine a model of groupwise heteroscedasticity.

## Harvey's Model for Groupwise Heteroscedasticity

Groupwise sample, $\mathrm{y}_{\mathrm{ig}}, \mathrm{x}_{\mathrm{ig}}, \ldots$
$N$ groups, each with $\mathrm{N}_{\mathrm{g}}$ observations.
$\operatorname{Var}\left[\varepsilon_{i g}\right]=\sigma_{g}{ }^{2}$
Let $\mathrm{d}_{\mathrm{ig}}=1$ if observation $\mathrm{i}, \mathrm{g}$ is in group $\mathrm{j}, 0$ else.
= group dummy variable.
$\operatorname{Var}\left[\varepsilon_{i g}\right]=\sigma_{g}{ }^{2} \exp \left(\theta_{2} \mathrm{~d}_{2}+\ldots \theta_{G} \mathrm{~d}_{\mathrm{G}}\right)$
$\operatorname{Var}_{1}=\sigma_{\mathrm{g}}{ }^{2}, \operatorname{Var}_{2}=\sigma_{\mathrm{g}}{ }^{2} \exp \left(\theta_{2}\right)$ and so on.

## Estimating Variance Components

- OLS is still consistent:
- Est.Var ${ }_{1}=\mathrm{e}_{1}{ }^{\prime} \mathrm{e}_{1} / \mathrm{N}_{1}$ estimates $\sigma_{\mathrm{g}}{ }^{2}$
- Est. Var $_{2}=\mathrm{e}_{2}{ }^{\prime} \mathrm{e}_{2} / \mathrm{N}_{2}$ estimates $\sigma_{\mathrm{g}}{ }^{2} \exp \left(\theta_{2}\right)$
- Estimator of $\theta_{2}$ is $\ln \left[\left(\mathrm{e}_{2}{ }^{\prime} \mathrm{e}_{2} / \mathrm{N}_{2}\right) /\left(\mathrm{e}_{1}{ }^{\prime} \mathrm{e}_{1} / \mathrm{N}_{1}\right)\right]$
- (1) Now use FGLS - weighted least squares
- Recompute residuals using WLS slopes
- (2) Recompute variance estimators
- Iterate to a solution... between (1) and (2)

